



The Isabelle/Isar Implementation

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Abstract

We describe the key concepts underlying the Isabelle/Isar implementation, including ML references for the most important functions. The aim is to give some insight into the overall system architecture, and provide clues on implementing applications within this framework.

Isabelle was not designed; it evolved. Not everyone likes this idea. Specification experts rightly abhor trial-and-error programming. They suggest that no one should write a program without first writing a complete formal specification. But university departments are not software houses. Programs like Isabelle are not products: when they have served their purpose, they are discarded.

Lawrence C. Paulson, “Isabelle: The Next 700 Theorem Provers”

As I did 20 years ago, I still fervently believe that the only way to make software secure, reliable, and fast is to make it small. Fight features.

Andrew S. Tanenbaum

Contents

1	Preliminaries	1
1.1	Contexts	1
1.1.1	Theory context	2
1.1.2	Proof context	4
1.1.3	Generic contexts	5
1.1.4	Context data	6
1.2	Names	7
1.2.1	Strings of symbols	7
1.2.2	Basic names	9
1.2.3	Indexed names	10
1.2.4	Qualified names and name spaces	11
2	Primitive logic	14
2.1	Types	14
2.2	Terms	17
2.3	Theorems	20
2.3.1	Primitive connectives and rules	20
2.3.2	Auxiliary definitions	24
2.4	Object-level rules	25
2.4.1	Hereditary Harrop Formulae	25
2.4.2	Rule composition	27
3	Tactical reasoning	29
3.1	Goals	29
3.2	Tactics	30
3.2.1	Resolution and assumption tactics	32
3.2.2	Explicit instantiation within a subgoal context	34
3.3	Tacticals	35
4	Structured proofs	36
4.1	Variables	36
4.2	Assumptions	38
4.3	Results	40

5	Syntax and type-checking	42
6	Isar language elements	43
6.1	Proof commands	43
6.2	Proof methods	43
6.3	Attributes	43
7	Local theory specifications	44
7.1	Definitional elements	44
7.2	Morphisms and declarations	46
8	System integration	47
8.1	Isar toplevel	47
8.1.1	Toplevel transitions	48
8.1.2	Toplevel control	50
8.2	ML toplevel	50
8.3	Theory database	52
A	Advanced ML programming	55
A.1	Style	55
A.2	Thread-safe programming	56
B	Basic library functions	60
B.1	Linear transformations	60
B.2	Options and partiality	63
B.3	Common data structures	63
B.3.1	Lists (as set-like data structures)	63
B.3.2	Association lists	64
B.3.3	Tables	65
	Bibliography	66
	Index	67

List of Figures

1.1	A theory definition depending on ancestors	3
2.1	Primitive connectives of Pure	20
2.2	Primitive inferences of Pure	21
2.3	Conceptual axiomatization of Pure equality	21
2.4	Admissible substitution rules	21
2.5	Definitions of auxiliary connectives	24

Preliminaries

1.1 Contexts

A logical context represents the background that is required for formulating statements and composing proofs. It acts as a medium to produce formal content, depending on earlier material (declarations, results etc.).

For example, derivations within the Isabelle/Pure logic can be described as a judgment $\Gamma \vdash_{\Theta} \varphi$, which means that a proposition φ is derivable from hypotheses Γ within the theory Θ . There are logical reasons for keeping Θ and Γ separate: theories can be liberal about supporting type constructors and schematic polymorphism of constants and axioms, while the inner calculus of $\Gamma \vdash \varphi$ is strictly limited to Simple Type Theory (with fixed type variables in the assumptions).

Contexts and derivations are linked by the following key principles:

- Transfer: monotonicity of derivations admits results to be transferred into a *larger* context, i.e. $\Gamma \vdash_{\Theta} \varphi$ implies $\Gamma' \vdash_{\Theta'} \varphi$ for contexts $\Theta' \supseteq \Theta$ and $\Gamma' \supseteq \Gamma$.
- Export: discharge of hypotheses admits results to be exported into a *smaller* context, i.e. $\Gamma' \vdash_{\Theta} \varphi$ implies $\Gamma \vdash_{\Theta} \Delta \implies \varphi$ where $\Gamma' \supseteq \Gamma$ and $\Delta = \Gamma' - \Gamma$. Note that Θ remains unchanged here, only the Γ part is affected.

By modeling the main characteristics of the primitive Θ and Γ above, and abstracting over any particular logical content, we arrive at the fundamental notions of *theory context* and *proof context* in Isabelle/Isar. These implement a certain policy to manage arbitrary *context data*. There is a strongly-typed mechanism to declare new kinds of data at compile time.

The internal bootstrap process of Isabelle/Pure eventually reaches a stage where certain data slots provide the logical content of Θ and Γ sketched above, but this does not stop there! Various additional data slots support all kinds of mechanisms that are not necessarily part of the core logic.

For example, there would be data for canonical introduction and elimination rules for arbitrary operators (depending on the object-logic and application), which enables users to perform standard proof steps implicitly (cf. the *rule* method [11]).

Thus Isabelle/Isar is able to bring forth more and more concepts successively. In particular, an object-logic like Isabelle/HOL continues the Isabelle/Pure setup by adding specific components for automated reasoning (classical reasoner, tableau prover, structured induction etc.) and derived specification mechanisms (inductive predicates, recursive functions etc.). All of this is ultimately based on the generic data management by theory and proof contexts introduced here.

1.1.1 Theory context

A *theory* is a data container with explicit name and unique identifier. Theories are related by a (nominal) sub-theory relation, which corresponds to the dependency graph of the original construction; each theory is derived from a certain sub-graph of ancestor theories.

The *merge* operation produces the least upper bound of two theories, which actually degenerates into absorption of one theory into the other (due to the nominal sub-theory relation).

The *begin* operation starts a new theory by importing several parent theories and entering a special *draft* mode, which is sustained until the final *end* operation. A draft theory acts like a linear type, where updates invalidate earlier versions. An invalidated draft is called “stale”.

The *checkpoint* operation produces an intermediate stepping stone that will survive the next update: both the original and the changed theory remain valid and are related by the sub-theory relation. Checkpointing essentially recovers purely functional theory values, at the expense of some extra internal bookkeeping.

The *copy* operation produces an auxiliary version that has the same data content, but is unrelated to the original: updates of the copy do not affect the original, neither does the sub-theory relation hold.

The example in figure 1.1 below shows a theory graph derived from *Pure*, with theory *Length* importing *Nat* and *List*. The body of *Length* consists of a sequence of updates, working mostly on drafts. Intermediate checkpoints may occur as well, due to the history mechanism provided by the Isar top-level, cf. §8.1.

There is a separate notion of *theory reference* for maintaining a live link to

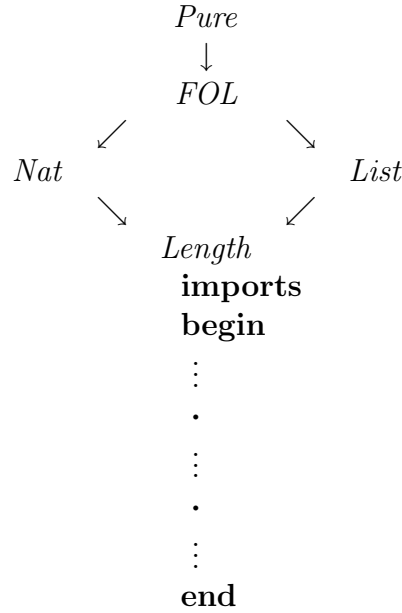


Figure 1.1: A theory definition depending on ancestors

an evolving theory context: updates on drafts are propagated automatically. Dynamic updating stops after an explicit *end* only.

Derived entities may store a theory reference in order to indicate the context they belong to. This implicitly assumes monotonic reasoning, because the referenced context may become larger without further notice.

ML

Reference

```

type theory
Theory.subthy: theory * theory -> bool
Theory.merge: theory * theory -> theory
Theory.checkpoint: theory -> theory
Theory.copy: theory -> theory

type theory_ref
Theory.deref: theory_ref -> theory
Theory.check_thy: theory -> theory_ref
  
```

theory represents theory contexts. This is essentially a linear type! Most operations destroy the original version, which then becomes “stale”.

Theory.subthy (*thy*₁, *thy*₂) compares theories according to the inherent graph structure of the construction. This sub-theory relation is a nominal approximation of inclusion (\subseteq) of the corresponding content.

`Theory.merge` (thy_1 , thy_2) absorbs one theory into the other. This fails for unrelated theories!

`Theory.checkpoint` thy produces a safe stepping stone in the linear development of thy . The next update will result in two related, valid theories.

`Theory.copy` thy produces a variant of thy that holds a copy of the same data. The result is not related to the original; the original is unchanged.

`theory_ref` represents a sliding reference to an always valid theory; updates on the original are propagated automatically.

`Theory.deref` $thy\text{-}ref$ turns a `theory_ref` into an `theory` value. As the referenced theory evolves monotonically over time, later invocations of `Theory.deref` may refer to a larger context.

`Theory.check_thy` thy produces a `theory_ref` from a valid `theory` value.

1.1.2 Proof context

A proof context is a container for pure data with a back-reference to the theory it belongs to. The *init* operation creates a proof context from a given theory. Modifications to draft theories are propagated to the proof context as usual, but there is also an explicit *transfer* operation to force resynchronization with more substantial updates to the underlying theory. The actual context data does not require any special bookkeeping, thanks to the lack of destructive features.

Entities derived in a proof context need to record inherent logical requirements explicitly, since there is no separate context identification as for theories. For example, hypotheses used in primitive derivations (cf. §2.3) are recorded separately within the sequent $\Gamma \vdash \varphi$, just to make double sure. Results could still leak into an alien proof context due to programming errors, but Isabelle/Isar includes some extra validity checks in critical positions, notably at the end of a sub-proof.

Proof contexts may be manipulated arbitrarily, although the common discipline is to follow block structure as a mental model: a given context is extended consecutively, and results are exported back into the original context. Note that the Isar proof states model block-structured reasoning explicitly, using a stack of proof contexts internally.

ML Reference

```

type Proof.context
ProofContext.init: theory -> Proof.context
ProofContext.theory_of: Proof.context -> theory
ProofContext.transfer: theory -> Proof.context -> Proof.context

```

`Proof.context` represents proof contexts. Elements of this type are essentially pure values, with a sliding reference to the background theory.

`ProofContext.init thy` produces a proof context derived from *thy*, initializing all data.

`ProofContext.theory_of ctxt` selects the background theory from *ctxt*, dereferencing its internal `theory_ref`.

`ProofContext.transfer thy ctxt` promotes the background theory of *ctxt* to the super theory *thy*.

1.1.3 Generic contexts

A generic context is the disjoint sum of either a theory or proof context. Occasionally, this enables uniform treatment of generic context data, typically extra-logical information. Operations on generic contexts include the usual injections, partial selections, and combinators for lifting operations on either component of the disjoint sum.

Moreover, there are total operations *theory-of* and *proof-of* to convert a generic context into either kind: a theory can always be selected from the sum, while a proof context might have to be constructed by an ad-hoc *init* operation.

ML Reference

```

type Context.generic
Context.theory_of: Context.generic -> theory
Context.proof_of: Context.generic -> Proof.context

```

`Context.generic` is the direct sum of `theory` and `Proof.context`, with the datatype constructors `Context.Theory` and `Context.Proof`.

`Context.theory_of context` always produces a theory from the generic *context*, using `ProofContext.theory_of` as required.

`Context.proof_of context` always produces a proof context from the generic *context*, using `ProofContext.init` as required (note that this re-initializes the context data with each invocation).

1.1.4 Context data

The main purpose of theory and proof contexts is to manage arbitrary data. New data types can be declared incrementally at compile time. There are separate declaration mechanisms for any of the three kinds of contexts: theory, proof, generic.

Theory data may refer to destructive entities, which are maintained in direct correspondence to the linear evolution of theory values, including explicit copies.¹ A theory data declaration needs to implement the following SML signature:

type T	representing type
val $empty: T$	empty default value
val $copy: T \rightarrow T$	refresh impure data
val $extend: T \rightarrow T$	re-initialize on import
val $merge: T \times T \rightarrow T$	join on import

The *empty* value acts as initial default for *any* theory that does not declare actual data content; *copy* maintains persistent integrity for impure data, it is just the identity for pure values; *extend* acts like a unitary version of *merge*, both operations should also include the functionality of *copy* for impure data.

Proof context data is purely functional. A declaration needs to implement the following SML signature:

type T	representing type
val $init: theory \rightarrow T$	produce initial value

The *init* operation is supposed to produce a pure value from the given background theory.

Generic data provides a hybrid interface for both theory and proof data. The declaration is essentially the same as for (pure) theory data, without *copy*. The *init* operation for proof contexts merely selects the current data value from the background theory.

A data declaration of type T results in the following interface:

$init: theory \rightarrow T$
$get: context \rightarrow T$
$put: T \rightarrow context \rightarrow context$
$map: (T \rightarrow T) \rightarrow context \rightarrow context$

¹Most existing instances of destructive theory data are merely historical relics (e.g. the destructive theorem storage, and destructive hints for the Simplifier and Classical rules).

Here *init* is only applicable to impure theory data to install a fresh copy persistently (destructive update on uninitialized has no permanent effect). The other operations provide access for the particular kind of context (theory, proof, or generic context). Note that this is a safe interface: there is no other way to access the corresponding data slot of a context. By keeping these operations private, a component may maintain abstract values authentically, without other components interfering.

ML Reference

```
functor TheoryDataFun
functor ProofDataFun
functor GenericDataFun
```

`TheoryDataFun(spec)` declares data for type `theory` according to the specification provided as argument structure. The resulting structure provides data `init` and access operations as described above.

`ProofDataFun(spec)` is analogous to `TheoryDataFun` for type `Proof.context`.

`GenericDataFun(spec)` is analogous to `TheoryDataFun` for type `Context.generic`.

1.2 Names

In principle, a name is just a string, but there are various convention for encoding additional structure. For example, “*Foo.bar.baz*” is considered as a qualified name consisting of three basic name components. The individual constituents of a name may have further substructure, e.g. the string “\<alpha>” encodes as a single symbol.

1.2.1 Strings of symbols

A *symbol* constitutes the smallest textual unit in Isabelle — raw characters are normally not encountered at all. Isabelle strings consist of a sequence of symbols, represented as a packed string or a list of strings. Each symbol is in itself a small string, which has either one of the following forms:

1. a single ASCII character “*c*”, for example “a”,
2. a regular symbol “\<*ident*>”, for example “\<alpha>”,
3. a control symbol “\<^*ident*>”, for example “\<^bold>”,

4. a raw symbol “\<^raw: *text*>” where *text* consists of printable characters excluding “.” and “>”, for example “\<^raw:\$\sum_{i = 1}^n\$>”,
5. a numbered raw control symbol “\<^rawn>” where *n* consists of digits, for example “\<^raw42>”.

The *ident* syntax for symbol names is *letter* (*letter* | *digit*)*, where *letter* = *A..Za..z* and *digit* = *0..9*. There are infinitely many regular symbols and control symbols, but a fixed collection of standard symbols is treated specifically. For example, “\<alpha>” is classified as a letter, which means it may occur within regular Isabelle identifiers.

Since the character set underlying Isabelle symbols is 7-bit ASCII and 8-bit characters are passed through transparently, Isabelle may also process Unicode/UCS data in UTF-8 encoding. Unicode provides its own collection of mathematical symbols, but there is no built-in link to the standard collection of Isabelle.

Output of Isabelle symbols depends on the print mode (§??). For example, the standard L^AT_EX setup of the Isabelle document preparation system would present “\<alpha>” as α , and “\<^bold>\<alpha>” as **α** .

ML Reference

```

type Symbol.symbol
Symbol.explode: string -> Symbol.symbol list
Symbol.is_letter: Symbol.symbol -> bool
Symbol.is_digit: Symbol.symbol -> bool
Symbol.is_quasi: Symbol.symbol -> bool
Symbol.is_blank: Symbol.symbol -> bool

type Symbol.sym
Symbol.decode: Symbol.symbol -> Symbol.sym

```

`Symbol.symbol` represents individual Isabelle symbols; this is an alias for `string`.

`Symbol.explode` *str* produces a symbol list from the packed form. This function supercedes `String.explode` for virtually all purposes of manipulating text in Isabelle!

`Symbol.is_letter`, `Symbol.is_digit`, `Symbol.is_quasi`, `Symbol.is_blank` classify standard symbols according to fixed syntactic conventions of Isabelle, cf. [11].

`Symbol.sym` is a concrete datatype that represents the different kinds of symbols explicitly, with constructors `Symbol.Char`, `Symbol.Sym`, `Symbol.Ctrl`, `Symbol.Raw`.

`Symbol.decode` converts the string representation of a symbol into the datatype version.

1.2.2 Basic names

A *basic name* essentially consists of a single Isabelle identifier. There are conventions to mark separate classes of basic names, by attaching a suffix of underscores: one underscore means *internal name*, two underscores means *Skolem name*, three underscores means *internal Skolem name*.

For example, the basic name *foo* has the internal version *foo-*, with Skolem versions *foo--* and *foo---*, respectively.

These special versions provide copies of the basic name space, apart from anything that normally appears in the user text. For example, system generated variables in Isar proof contexts are usually marked as internal, which prevents mysterious name references like *xaa* to appear in the text.

Manipulating binding scopes often requires on-the-fly renamings. A *name context* contains a collection of already used names. The *declare* operation adds names to the context.

The *invents* operation derives a number of fresh names from a given starting point. For example, the first three names derived from *a* are *a*, *b*, *c*.

The *variants* operation produces fresh names by incrementing tentative names as base-26 numbers (with digits *a..z*) until all clashes are resolved. For example, name *foo* results in variants *fooa*, *foob*, *fooc*, ..., *fooaa*, *fooab* etc.; each renaming step picks the next unused variant from this sequence.

ML Reference

```
Name.internal: string -> string
Name.skolem: string -> string

type Name.context
Name.context: Name.context
Name.declare: string -> Name.context -> Name.context
Name.invents: Name.context -> string -> int -> string list
Name.variants: string list -> Name.context -> string list * Name.context
```

`Name.internal name` produces an internal name by adding one underscore.

`Name.skolem name` produces a Skolem name by adding two underscores.

`Name.context` represents the context of already used names; the initial value is `Name.context`.

`Name.declare` *name* enters a used name into the context.

`Name.invents` *context name n* produces *n* fresh names derived from *name*.

`Name.variants` *names context* produces fresh variants of *names*; the result is entered into the context.

1.2.3 Indexed names

An *indexed name* (or *indexname*) is a pair of a basic name and a natural number. This representation allows efficient renaming by incrementing the second component only. The canonical way to rename two collections of indexnames apart from each other is this: determine the maximum index *maxidx* of the first collection, then increment all indexes of the second collection by *maxidx* + 1; the maximum index of an empty collection is -1 .

Occasionally, basic names and indexed names are injected into the same pair type: the (improper) indexname $(x, -1)$ is used to encode basic names.

Isabelle syntax observes the following rules for representing an indexname (x, i) as a packed string:

- $?x$ if *x* does not end with a digit and $i = 0$,
- $?xi$ if *x* does not end with a digit,
- $?x.i$ otherwise.

Indexnames may acquire large index numbers over time. Results are normalized towards 0 at certain checkpoints, notably at the end of a proof. This works by producing variants of the corresponding basic name components. For example, the collection $?x1, ?x7, ?x42$ becomes $?x, ?xa, ?xb$.

ML Reference

`type indexname`

`indexname` represents indexed names. This is an abbreviation for `string * int`.

The second component is usually non-negative, except for situations where $(x, -1)$ is used to embed basic names into this type.

1.2.4 Qualified names and name spaces

A *qualified name* consists of a non-empty sequence of basic name components. The packed representation uses a dot as separator, as in “*A.b.c*”. The last component is called *base name*, the remaining prefix *qualifier* (which may be empty). The idea of qualified names is to encode nested structures by recording the access paths as qualifiers. For example, an item named “*A.b.c*” may be understood as a local entity *c*, within a local structure *b*, within a global structure *A*. Typically, name space hierarchies consist of 1–2 levels of qualification, but this need not be always so.

The empty name is commonly used as an indication of unnamed entities, whenever this makes any sense. The basic operations on qualified names are smart enough to pass through such improper names unchanged.

A *naming* policy tells how to turn a name specification into a fully qualified internal name (by the *full* operation), and how fully qualified names may be accessed externally. For example, the default naming policy is to prefix an implicit path: *full x* produces *path.x*, and the standard accesses for *path.x* include both *x* and *path.x*. Normally, the naming is implicit in the theory or proof context; there are separate versions of the corresponding.

A *name space* manages a collection of fully internalized names, together with a mapping between external names and internal names (in both directions). The corresponding *intern* and *extern* operations are mostly used for parsing and printing only! The *declare* operation augments a name space according to the accesses determined by the naming policy.

As a general principle, there is a separate name space for each kind of formal entity, e.g. logical constant, type constructor, type class, theorem. It is usually clear from the occurrence in concrete syntax (or from the scope) which kind of entity a name refers to. For example, the very same name *c* may be used uniformly for a constant, type constructor, and type class.

There are common schemes to name theorems systematically, according to the name of the main logical entity involved, e.g. *c.intro* for a canonical theorem related to constant *c*. This technique of mapping names from one space into another requires some care in order to avoid conflicts. In particular, theorem names derived from a type constructor or type class are better suffixed in addition to the usual qualification, e.g. *c-type.intro* and *c-class.intro* for theorems related to type *c* and class *c*, respectively.

ML

Reference

```

Long_Name.base_name: string -> string
Long_Name.qualifier: string -> string
Long_Name.append: string -> string -> string
Long_Name.implode: string list -> string
Long_Name.explode: string -> string list

type Namespace.naming
Namespace.default_naming: Namespace.naming
Namespace.add_path: string -> Namespace.naming -> Namespace.naming
Namespace.full_name: Namespace.naming -> binding -> string

type Namespace.T
Namespace.empty: Namespace.T
Namespace.merge: Namespace.T * Namespace.T -> Namespace.T
Namespace.declare: Namespace.naming -> binding -> Namespace.T ->
  string * Namespace.T
Namespace.intern: Namespace.T -> string -> string
Namespace.extern: Namespace.T -> string -> string

```

`Long_Name.base_name` *name* returns the base name of a qualified name.

`Long_Name.qualifier` *name* returns the qualifier of a qualified name.

`Long_Name.append` *name*₁ *name*₂ appends two qualified names.

`Long_Name.implode` *names* and `Long_Name.explode` *name* convert between the packed string representation and the explicit list form of qualified names.

`Namespace.naming` represents the abstract concept of a naming policy.

`Namespace.default_naming` is the default naming policy. In a theory context, this is usually augmented by a path prefix consisting of the theory name.

`Namespace.add_path` *path* *naming* augments the naming policy by extending its path component.

`Namespace.full_name` *naming* *binding* turns a name binding (usually a basic name) into the fully qualified internal name, according to the given naming policy.

`Namespace.T` represents name spaces.

`Namespace.empty` and `Namespace.merge` (*space*₁, *space*₂) are the canonical operations for maintaining name spaces according to theory data management (§1.1.4).

`Namespace.declare` *naming* *bindings* *space* enters a name binding as fully qualified internal name into the name space, with external accesses determined by the naming policy.

`Namespace.intern` *space name* internalizes a (partially qualified) external name.

This operation is mostly for parsing! Note that fully qualified names stemming from declarations are produced via `Namespace.full_name` and `Namespace.declare` (or their derivatives for `theory` and `Proof.context`).

`Namespace.extern` *space name* externalizes a (fully qualified) internal name.

This operation is mostly for printing! User code should not rely on the precise result too much.

Primitive logic

The logical foundations of Isabelle/Isar are that of the Pure logic, which has been introduced as a Natural Deduction framework in [8]. This is essentially the same logic as “ *λHOL* ” in the more abstract setting of Pure Type Systems (PTS) [1], although there are some key differences in the specific treatment of simple types in Isabelle/Pure.

Following type-theoretic parlance, the Pure logic consists of three levels of λ -calculus with corresponding arrows, \Rightarrow for syntactic function space (terms depending on terms), \wedge for universal quantification (proofs depending on terms), and \Longrightarrow for implication (proofs depending on proofs).

Derivations are relative to a logical theory, which declares type constructors, constants, and axioms. Theory declarations support schematic polymorphism, which is strictly speaking outside the logic.¹

2.1 Types

The language of types is an uninterpreted order-sorted first-order algebra; types are qualified by ordered type classes.

A *type class* is an abstract syntactic entity declared in the theory context. The *subclass relation* $c_1 \subseteq c_2$ is specified by stating an acyclic generating relation; the transitive closure is maintained internally. The resulting relation is an ordering: reflexive, transitive, and antisymmetric.

A *sort* is a list of type classes written as $s = \{c_1, \dots, c_m\}$, which represents symbolic intersection. Notationally, the curly braces are omitted for singleton intersections, i.e. any class c may be read as a sort $\{c\}$. The ordering on type classes is extended to sorts according to the meaning of intersections: $\{c_1, \dots, c_m\} \subseteq \{d_1, \dots, d_n\}$ iff $\forall j. \exists i. c_i \subseteq d_j$. The empty intersection $\{\}$ refers to the universal sort, which is the largest element wrt. the sort order. The intersections of all (finitely many) classes declared in the current theory are the minimal elements wrt. the sort order.

¹This is the deeper logical reason, why the theory context Θ is separate from the proof context Γ of the core calculus.

A *fixed type variable* is a pair of a basic name (starting with a ' character) and a sort constraint, e.g. $('a, s)$ which is usually printed as α_s . A *schematic type variable* is a pair of an indexname and a sort constraint, e.g. $(('a, 0), s)$ which is usually printed as $? \alpha_s$.

Note that *all* syntactic components contribute to the identity of type variables, including the sort constraint. The core logic handles type variables with the same name but different sorts as different, although some outer layers of the system make it hard to produce anything like this.

A *type constructor* κ is a k -ary operator on types declared in the theory. Type constructor application is written postfix as $(\alpha_1, \dots, \alpha_k)\kappa$. For $k = 0$ the argument tuple is omitted, e.g. *prop* instead of $()prop$. For $k = 1$ the parentheses are omitted, e.g. α *list* instead of $(\alpha)list$. Further notation is provided for specific constructors, notably the right-associative infix $\alpha \Rightarrow \beta$ instead of $(\alpha, \beta)fun$.

A *type* is defined inductively over type variables and type constructors as follows: $\tau = \alpha_s \mid ? \alpha_s \mid (\tau_1, \dots, \tau_k)\kappa$.

A *type abbreviation* is a syntactic definition $(\vec{\alpha})\kappa = \tau$ of an arbitrary type expression τ over variables $\vec{\alpha}$. Type abbreviations appear as type constructors in the syntax, but are expanded before entering the logical core.

A *type arity* declares the image behavior of a type constructor wrt. the algebra of sorts: $\kappa :: (s_1, \dots, s_k)s$ means that $(\tau_1, \dots, \tau_k)\kappa$ is of sort s if every argument type τ_i is of sort s_i . Arity declarations are implicitly completed, i.e. $\kappa :: (\vec{s})c$ entails $\kappa :: (\vec{s})c'$ for any $c' \supseteq c$.

The sort algebra is always maintained as *coregular*, which means that type arities are consistent with the subclass relation: for any type constructor κ , and classes $c_1 \subseteq c_2$, and arities $\kappa :: (\vec{s}_1)c_1$ and $\kappa :: (\vec{s}_2)c_2$ holds $\vec{s}_1 \subseteq \vec{s}_2$ component-wise.

The key property of a coregular order-sorted algebra is that sort constraints can be solved in a most general fashion: for each type constructor κ and sort s there is a most general vector of argument sorts (s_1, \dots, s_k) such that a type scheme $(\alpha_{s_1}, \dots, \alpha_{s_k})\kappa$ is of sort s . Consequently, type unification has most general solutions (modulo equivalence of sorts), so type-inference produces primary types as expected [7].

ML Reference

```

type class
type sort
type arity
type typ
map_atyps: (typ -> typ) -> typ -> typ
fold_atyps: (typ -> 'a -> 'a) -> typ -> 'a -> 'a
Sign.subsort: theory -> sort * sort -> bool
Sign.of_sort: theory -> typ * sort -> bool
Sign.add_types: (binding * int * mixfix) list -> theory -> theory
Sign.add_tyabbrs_i:
  (binding * string list * typ * mixfix) list -> theory -> theory
Sign.primitive_class: binding * class list -> theory -> theory
Sign.primitive_classrel: class * class -> theory -> theory
Sign.primitive_arity: arity -> theory -> theory

```

`class` represents type classes; this is an alias for `string`.

`sort` represents sorts; this is an alias for `class list`.

`arity` represents type arities; this is an alias for triples of the form (κ, \vec{s}, s) for $\kappa :: (\vec{s})s$ described above.

`typ` represents types; this is a datatype with constructors `TFree`, `TVar`, `Type`.

`map_atyps f τ` applies the mapping f to all atomic types (`TFree`, `TVar`) occurring in τ .

`fold_atyps f τ` iterates the operation f over all occurrences of atomic types (`TFree`, `TVar`) in τ ; the type structure is traversed from left to right.

`Sign.subsort thy (s_1, s_2)` tests the subsort relation $s_1 \subseteq s_2$.

`Sign.of_sort thy (τ, s)` tests whether type τ is of sort s .

`Sign.add_types $[(\kappa, k, mx), \dots]$` declares a new type constructors κ with k arguments and optional mixfix syntax.

`Sign.add_tyabbrs_i $[(\kappa, \vec{\alpha}, \tau, mx), \dots]$` defines a new type abbreviation $(\vec{\alpha})\kappa = \tau$ with optional mixfix syntax.

`Sign.primitive_class $(c, [c_1, \dots, c_n])$` declares a new class c , together with class relations $c \subseteq c_i$, for $i = 1, \dots, n$.

`Sign.primitive_classrel (c_1, c_2)` declares the class relation $c_1 \subseteq c_2$.

`Sign.primitive_arity (κ, \vec{s}, s)` declares the arity $\kappa :: (\vec{s})s$.

2.2 Terms

The language of terms is that of simply-typed λ -calculus with de-Brujin indices for bound variables (cf. [3] or [9]), with the types being determined by the corresponding binders. In contrast, free variables and constants are have an explicit name and type in each occurrence.

A *bound variable* is a natural number b , which accounts for the number of intermediate binders between the variable occurrence in the body and its binding position. For example, the de-Brujin term $\lambda_{nat}. \lambda_{nat}. 1 + 0$ would correspond to $\lambda x_{nat}. \lambda y_{nat}. x + y$ in a named representation. Note that a bound variable may be represented by different de-Brujin indices at different occurrences, depending on the nesting of abstractions.

A *loose variable* is a bound variable that is outside the scope of local binders. The types (and names) for loose variables can be managed as a separate context, that is maintained as a stack of hypothetical binders. The core logic operates on closed terms, without any loose variables.

A *fixed variable* is a pair of a basic name and a type, e.g. (x, τ) which is usually printed x_τ . A *schematic variable* is a pair of an indexname and a type, e.g. $((x, 0), \tau)$ which is usually printed as $?x_\tau$.

A *constant* is a pair of a basic name and a type, e.g. (c, τ) which is usually printed as c_τ . Constants are declared in the context as polymorphic families $c :: \sigma$, meaning that all substitution instances c_τ for $\tau = \sigma\theta$ are valid.

The vector of *type arguments* of constant c_τ wrt. the declaration $c :: \sigma$ is defined as the codomain of the matcher $\theta = \{?\alpha_1 \mapsto \tau_1, \dots, ?\alpha_n \mapsto \tau_n\}$ presented in canonical order (τ_1, \dots, τ_n) . Within a given theory context, there is a one-to-one correspondence between any constant c_τ and the application $c(\tau_1, \dots, \tau_n)$ of its type arguments. For example, with $plus :: \alpha \Rightarrow \alpha \Rightarrow \alpha$, the instance $plus_{nat} \Rightarrow nat \Rightarrow nat$ corresponds to $plus(nat)$.

Constant declarations $c :: \sigma$ may contain sort constraints for type variables in σ . These are observed by type-inference as expected, but *ignored* by the core logic. This means the primitive logic is able to reason with instances of polymorphic constants that the user-level type-checker would reject due to violation of type class restrictions.

An *atomic* term is either a variable or constant. A *term* is defined inductively over atomic terms, with abstraction and application as follows: $t = b \mid x_\tau \mid ?x_\tau \mid c_\tau \mid \lambda_\tau. t \mid t_1 t_2$. Parsing and printing takes care of converting between an external representation with named bound variables. Subsequently, we shall use the latter notation instead of internal de-Brujin representation.

The inductive relation $t :: \tau$ assigns a (unique) type to a term according

to the structure of atomic terms, abstractions, and applicatins:

$$\frac{}{a_\tau :: \tau} \quad \frac{t :: \sigma}{(\lambda x_\tau. t) :: \tau \Rightarrow \sigma} \quad \frac{t :: \tau \Rightarrow \sigma \quad u :: \tau}{t u :: \sigma}$$

A *well-typed term* is a term that can be typed according to these rules.

Typing information can be omitted: type-inference is able to reconstruct the most general type of a raw term, while assigning most general types to all of its variables and constants. Type-inference depends on a context of type constraints for fixed variables, and declarations for polymorphic constants.

The identity of atomic terms consists both of the name and the type component. This means that different variables x_{τ_1} and x_{τ_2} may become the same after type instantiation. Some outer layers of the system make it hard to produce variables of the same name, but different types. In contrast, mixed instances of polymorphic constants occur frequently.

The *hidden polymorphism* of a term $t :: \sigma$ is the set of type variables occurring in t , but not in σ . This means that the term implicitly depends on type arguments that are not accounted in the result type, i.e. there are different type instances $t\theta :: \sigma$ and $t\theta' :: \sigma$ with the same type. This slightly pathological situation notoriously demands additional care.

A *term abbreviation* is a syntactic definition $c_\sigma \equiv t$ of a closed term t of type σ , without any hidden polymorphism. A term abbreviation looks like a constant in the syntax, but is expanded before entering the logical core. Abbreviations are usually reverted when printing terms, using $t \rightarrow c_\sigma$ as rules for higher-order rewriting.

Canonical operations on λ -terms include $\alpha\beta\eta$ -conversion: α -conversion refers to capture-free renaming of bound variables; β -conversion contracts an abstraction applied to an argument term, substituting the argument in the body: $(\lambda x. b)a$ becomes $b[a/x]$; η -conversion contracts vacuous application-abstraction: $\lambda x. f x$ becomes f , provided that the bound variable does not occur in f .

Terms are normally treated modulo α -conversion, which is implicit in the de-Bruijn representation. Names for bound variables in abstractions are maintained separately as (meaningless) comments, mostly for parsing and printing. Full $\alpha\beta\eta$ -conversion is commonplace in various standard operations (§2.4) that are based on higher-order unification and matching.

ML Reference

```

type term
op aconv: term * term -> bool
map_types: (typ -> typ) -> term -> term
fold_types: (typ -> 'a -> 'a) -> term -> 'a -> 'a
map_aterms: (term -> term) -> term -> term
fold_aterms: (term -> 'a -> 'a) -> term -> 'a -> 'a

fastype_of: term -> typ
lambda: term -> term -> term
betapply: term * term -> term
Sign.declare_const: Properties.T -> (binding * typ) * mixfix ->
  theory -> term * theory
Sign.add_abbrev: string -> Properties.T -> binding * term ->
  theory -> (term * term) * theory
Sign.const_typargs: theory -> string * typ -> typ list
Sign.const_instance: theory -> string * typ list -> typ

```

`term` represents de-Bruijn terms, with comments in abstractions, and explicitly named free variables and constants; this is a datatype with constructors `Bound`, `Free`, `Var`, `Const`, `Abs`, `op` `$`.

`t aconv u` checks α -equivalence of two terms. This is the basic equality relation on type `term`; raw datatype equality should only be used for operations related to parsing or printing!

`map_types f t` applies the mapping f to all types occurring in t .

`fold_types f t` iterates the operation f over all occurrences of types in t ; the term structure is traversed from left to right.

`map_aterms f t` applies the mapping f to all atomic terms (`Bound`, `Free`, `Var`, `Const`) occurring in t .

`fold_aterms f t` iterates the operation f over all occurrences of atomic terms (`Bound`, `Free`, `Var`, `Const`) in t ; the term structure is traversed from left to right.

`fastype_of t` determines the type of a well-typed term. This operation is relatively slow, despite the omission of any sanity checks.

`lambda a b` produces an abstraction $\lambda a. b$, where occurrences of the atomic term a in the body b are replaced by bound variables.

`betapply (t, u)` produces an application $t u$, with topmost β -conversion if t is an abstraction.

`Sign.declare_const properties ((c, σ), mx)` declares a new constant $c :: \sigma$ with optional mixfix syntax.

`Sign.add_abbrev` *print-mode properties* (c, t) introduces a new term abbreviation $c \equiv t$.

`Sign.const_typargs` *thy* (c, τ) and `Sign.const_instance` *thy* $(c, [\tau_1, \dots, \tau_n])$ convert between two representations of polymorphic constants: full type instance vs. compact type arguments form.

2.3 Theorems

A *proposition* is a well-typed term of type *prop*, a *theorem* is a proven proposition (depending on a context of hypotheses and the background theory). Primitive inferences include plain Natural Deduction rules for the primary connectives \wedge and \implies of the framework. There is also a builtin notion of equality/equivalence \equiv .

2.3.1 Primitive connectives and rules

The theory *Pure* contains constant declarations for the primitive connectives \wedge , \implies , and \equiv of the logical framework, see figure 2.1. The derivability judgment $A_1, \dots, A_n \vdash B$ is defined inductively by the primitive inferences given in figure 2.2, with the global restriction that the hypotheses must *not* contain any schematic variables. The builtin equality is conceptually axiomatized as shown in figure 2.3, although the implementation works directly with derived inferences.

$all :: (\alpha \Rightarrow prop) \Rightarrow prop$	universal quantification (binder \wedge)
$\implies :: prop \Rightarrow prop \Rightarrow prop$	implication (right associative infix)
$\equiv :: \alpha \Rightarrow \alpha \Rightarrow prop$	equality relation (infix)

Figure 2.1: Primitive connectives of Pure

The introduction and elimination rules for \wedge and \implies are analogous to formation of dependently typed λ -terms representing the underlying proof objects. Proof terms are irrelevant in the Pure logic, though; they cannot occur within propositions. The system provides a runtime option to record explicit proof terms for primitive inferences. Thus all three levels of λ -calculus become explicit: \Rightarrow for terms, and \wedge/\implies for proofs (cf. [2]).

Observe that locally fixed parameters (as in \wedge -*intro*) need not be recorded in the hypotheses, because the simple syntactic types of Pure are always

$$\begin{array}{c}
\frac{A \in \Theta}{\vdash A} \text{ (axiom)} \quad \frac{}{A \vdash A} \text{ (assume)} \\
\\
\frac{\Gamma \vdash b[x] \quad x \notin \Gamma}{\Gamma \vdash \wedge x. b[x]} (\wedge\text{-intro}) \quad \frac{\Gamma \vdash \wedge x. b[x]}{\Gamma \vdash b[a]} (\wedge\text{-elim}) \\
\\
\frac{}{\Gamma \vdash A \implies A} (\implies\text{-intro}) \quad \frac{\Gamma_1 \vdash A \implies B \quad \Gamma_2 \vdash A}{\Gamma_1 \cup \Gamma_2 \vdash B} (\implies\text{-elim})
\end{array}$$

Figure 2.2: Primitive inferences of Pure

$$\begin{array}{ll}
\vdash (\lambda x. b[x]) a \equiv b[a] & \beta\text{-conversion} \\
\vdash x \equiv x & \text{reflexivity} \\
\vdash x \equiv y \implies P x \implies P y & \text{substitution} \\
\vdash (\wedge x. f x \equiv g x) \implies f \equiv g & \text{extensionality} \\
\vdash (A \implies B) \implies (B \implies A) \implies A \equiv B & \text{logical equivalence}
\end{array}$$

Figure 2.3: Conceptual axiomatization of Pure equality

inhabitable. “Assumptions” $x :: \tau$ for type-membership are only present as long as some x_τ occurs in the statement body.²

The axiomatization of a theory is implicitly closed by forming all instances of type and term variables: $\vdash A\theta$ holds for any substitution instance of an axiom $\vdash A$. By pushing substitutions through derivations inductively, we also get admissible *generalize* and *instantiate* rules as shown in figure 2.4.

$$\begin{array}{c}
\frac{\Gamma \vdash B[\alpha] \quad \alpha \notin \Gamma}{\Gamma \vdash B[? \alpha]} \quad \frac{\Gamma \vdash B[x] \quad x \notin \Gamma}{\Gamma \vdash B[? x]} \quad (\text{generalize}) \\
\\
\frac{\Gamma \vdash B[? \alpha]}{\Gamma \vdash B[\tau]} \quad \frac{\Gamma \vdash B[? x]}{\Gamma \vdash B[t]} \quad (\text{instantiate})
\end{array}$$

Figure 2.4: Admissible substitution rules

Note that *instantiate* does not require an explicit side-condition, because Γ may never contain schematic variables.

²This is the key difference to “ λHOL ” in the PTS framework [1], where hypotheses $x : A$ are treated uniformly for propositions and types.

In principle, variables could be substituted in hypotheses as well, but this would disrupt the monotonicity of reasoning: deriving $\Gamma\theta \vdash B\theta$ from $\Gamma \vdash B$ is correct, but $\Gamma\theta \supseteq \Gamma$ does not necessarily hold: the result belongs to a different proof context.

An *oracle* is a function that produces axioms on the fly. Logically, this is an instance of the *axiom* rule (figure 2.2), but there is an operational difference. The system always records oracle invocations within derivations of theorems by a unique tag.

Axiomatizations should be limited to the bare minimum, typically as part of the initial logical basis of an object-logic formalization. Later on, theories are usually developed in a strictly definitional fashion, by stating only certain equalities over new constants.

A *simple definition* consists of a constant declaration $c :: \sigma$ together with an axiom $\vdash c \equiv t$, where $t :: \sigma$ is a closed term without any hidden polymorphism. The RHS may depend on further defined constants, but not c itself. Definitions of functions may be presented as $c \vec{x} \equiv t$ instead of the puristic $c \equiv \lambda \vec{x}. t$.

An *overloaded definition* consists of a collection of axioms for the same constant, with zero or one equations $c((\vec{\alpha})\kappa) \equiv t$ for each type constructor κ (for distinct variables $\vec{\alpha}$). The RHS may mention previously defined constants as above, or arbitrary constants $d(\alpha_i)$ for some α_i projected from $\vec{\alpha}$. Thus overloaded definitions essentially work by primitive recursion over the syntactic structure of a single type argument.

ML Reference

```

type ctyp
type cterm
Thm.ctyp_of: theory -> typ -> ctyp
Thm.cterm_of: theory -> term -> cterm

type thm
proofs: int ref
Thm.assume: cterm -> thm
Thm.forall_intr: cterm -> thm -> thm
Thm.forall_elim: cterm -> thm -> thm
Thm.implies_intr: cterm -> thm -> thm
Thm.implies_elim: thm -> thm -> thm
Thm.generalize: string list * string list -> int -> thm -> thm
Thm.instantiate: (ctyp * ctyp) list * (cterm * cterm) list -> thm -> thm
Thm.axiom: theory -> string -> thm
Thm.add_oracle: binding * ('a -> cterm) -> theory
  -> (string * ('a -> thm)) * theory

```

```

Theory.add_axioms_i: (binding * term) list -> theory -> theory
Theory.add_deps: string -> string * typ -> (string * typ) list -> theory -> theory
Theory.add_defs_i: bool -> bool -> (binding * term) list -> theory -> theory

```

`ctyp` and `cterm` represent certified types and terms, respectively. These are abstract datatypes that guarantee that its values have passed the full well-formedness (and well-typedness) checks, relative to the declarations of type constructors, constants etc. in the theory.

`Thm.ctyp_of thy τ` and `Thm.cterm_of thy t` explicitly checks types and terms, respectively. This also involves some basic normalizations, such expansion of type and term abbreviations from the theory context.

Re-certification is relatively slow and should be avoided in tight reasoning loops. There are separate operations to decompose certified entities (including actual theorems).

`thm` represents proven propositions. This is an abstract datatype that guarantees that its values have been constructed by basic principles of the `Thm` module. Every `thm` value contains a sliding back-reference to the enclosing theory, cf. §1.1.1.

`proofs` determines the detail of proof recording within `thm` values: 0 records only the names of oracles, 1 records oracle names and propositions, 2 additionally records full proof terms. Officially named theorems that contribute to a result are always recorded.

`Thm.assume`, `Thm.forall_intr`, `Thm.forall_elim`, `Thm.implies_intr`, and `Thm.implies_elim` correspond to the primitive inferences of figure 2.2.

`Thm.generalize ($\vec{\alpha}$, \vec{x})` corresponds to the *generalize* rules of figure 2.4. Here collections of type and term variables are generalized simultaneously, specified by the given basic names.

`Thm.instantiate ($\vec{\alpha}_s$, \vec{x}_τ)` corresponds to the *instantiate* rules of figure 2.4. Type variables are substituted before term variables. Note that the types in \vec{x}_τ refer to the instantiated versions.

`Thm.axiom thy name` retrieves a named axiom, cf. *axiom* in figure 2.2.

`Thm.add_oracle (binding, oracle)` produces a named oracle rule, essentially generating arbitrary axioms on the fly, cf. *axiom* in figure 2.2.

`Theory.add_axioms_i [(name, A), ...]` declares arbitrary propositions as axioms.

`Theory.add_deps name c_τ \vec{d}_σ` declares dependencies of a named specification for constant c_τ , relative to existing specifications for constants \vec{d}_σ .

`Theory.add_defs_i unchecked overloaded [(name, c $\vec{x} \equiv t$), ...]` states a definitional axiom for an existing constant c . Dependencies are recorded (cf. `Theory.add_deps`), unless the *unchecked* option is set.

2.3.2 Auxiliary definitions

Theory *Pure* provides a few auxiliary definitions, see figure 2.5. These special constants are normally not exposed to the user, but appear in internal encodings.

$conjunction :: prop \Rightarrow prop \Rightarrow prop$	(infix $\&$)
$\vdash A \& B \equiv (\wedge C. (A \Longrightarrow B \Longrightarrow C) \Longrightarrow C)$	
$prop :: prop \Rightarrow prop$	(prefix $\#$, suppressed)
$\#A \equiv A$	
$term :: \alpha \Rightarrow prop$	(prefix <i>TERM</i>)
$term\ x \equiv (\wedge A. A \Longrightarrow A)$	
$TYPE :: \alpha\ itself$	(prefix <i>TYPE</i>)
$(unspecified)$	

Figure 2.5: Definitions of auxiliary connectives

Derived conjunction rules include introduction $A \Longrightarrow B \Longrightarrow A \& B$, and destructions $A \& B \Longrightarrow A$ and $A \& B \Longrightarrow B$. Conjunction allows to treat simultaneous assumptions and conclusions uniformly. For example, multiple claims are intermediately represented as explicit conjunction, but this is refined into separate sub-goals before the user continues the proof; the final result is projected into a list of theorems (cf. §3.1).

The *prop* marker ($\#$) makes arbitrarily complex propositions appear as atomic, without changing the meaning: $\Gamma \vdash A$ and $\Gamma \vdash \#A$ are interchangeable. See §3.1 for specific operations.

The *term* marker turns any well-typed term into a derivable proposition: $\vdash\ TERM\ t$ holds unconditionally. Although this is logically vacuous, it allows to treat terms and proofs uniformly, similar to a type-theoretic framework.

The *TYPE* constructor is the canonical representative of the unspecified type $\alpha\ itself$; it essentially injects the language of types into that of terms. There is specific notation $TYPE(\tau)$ for $TYPE_\tau\ itself$. Although being devoid of any particular meaning, the $TYPE(\tau)$ accounts for the type τ within the term language. In particular, $TYPE(\alpha)$ may be used as formal argument in primitive definitions, in order to circumvent hidden polymorphism (cf.

§2.2). For example, $c \text{ TYPE}(\alpha) \equiv A[\alpha]$ defines $c :: \alpha \text{ itself} \Rightarrow \text{prop}$ in terms of a proposition A that depends on an additional type argument, which is essentially a predicate on types.

ML

Reference

```
Conjunction.intr: thm -> thm -> thm
Conjunction.elim: thm -> thm * thm
Drule.mk_term: cterm -> thm
Drule.dest_term: thm -> cterm
Logic.mk_type: typ -> term
Logic.dest_type: term -> typ
```

`Conjunction.intr` derives $A \ \& \ B$ from A and B .

`Conjunction.elim` derives A and B from $A \ \& \ B$.

`Drule.mk_term` derives $TERM \ t$.

`Drule.dest_term` recovers term t from $TERM \ t$.

`Logic.mk_type` τ produces the term $TYPE(\tau)$.

`Logic.dest_type` $TYPE(\tau)$ recovers the type τ .

2.4 Object-level rules

The primitive inferences covered so far mostly serve foundational purposes. User-level reasoning usually works via object-level rules that are represented as theorems of Pure. Composition of rules involves *backchaining*, *higher-order unification* modulo $\alpha\beta\eta$ -conversion of λ -terms, and so-called *lifting* of rules into a context of \wedge and \implies connectives. Thus the full power of higher-order Natural Deduction in Isabelle/Pure becomes readily available.

2.4.1 Hereditary Harrop Formulae

The idea of object-level rules is to model Natural Deduction inferences in the style of Gentzen [4], but we allow arbitrary nesting similar to [10]. The most basic rule format is that of a *Horn Clause*:

$$\frac{A_1 \quad \dots \quad A_n}{A}$$

where A, A_1, \dots, A_n are atomic propositions of the framework, usually of the form *Trueprop* B , where B is a (compound) object-level statement. This object-level inference corresponds to an iterated implication in Pure like this:

$$A_1 \implies \dots A_n \implies A$$

As an example consider conjunction introduction: $A \implies B \implies A \wedge B$. Any parameters occurring in such rule statements are conceptionally treated as arbitrary:

$$\wedge x_1 \dots x_m. A_1 x_1 \dots x_m \implies \dots A_n x_1 \dots x_m \implies A x_1 \dots x_m$$

Nesting of rules means that the positions of A_i may again hold compound rules, not just atomic propositions. Propositions of this format are called *Hereditary Harrop Formulae* in the literature [6]. Here we give an inductive characterization as follows:

x	set of variables
A	set of atomic propositions
H = $\wedge \mathbf{x}^*. \mathbf{H}^* \implies \mathbf{A}$	set of Hereditary Harrop Formulas

Thus we essentially impose nesting levels on propositions formed from \wedge and \implies . At each level there is a prefix of parameters and compound premises, concluding an atomic proposition. Typical examples are \longrightarrow -introduction $(A \implies B) \implies A \longrightarrow B$ or mathematical induction $P\ 0 \implies (\wedge n. P\ n \implies P\ (Suc\ n)) \implies P\ n$. Even deeper nesting occurs in well-founded induction $(\wedge x. (\wedge y. y \prec x \implies P\ y) \implies P\ x) \implies P\ x$, but this already marks the limit of rule complexity seen in practice.

Regular user-level inferences in Isabelle/Pure always maintain the following canonical form of results:

- Normalization by $(A \implies (\wedge x. B\ x)) \equiv (\wedge x. A \implies B\ x)$, which is a theorem of Pure, means that quantifiers are pushed in front of implication at each level of nesting. The normal form is a Hereditary Harrop Formula.
- The outermost prefix of parameters is represented via schematic variables: instead of $\wedge \vec{x}. \vec{H}\ \vec{x} \implies A\ \vec{x}$ we have $\vec{H}\ ?\vec{x} \implies A\ ?\vec{x}$. Note that this representation loses information about the order of parameters, and vacuous quantifiers vanish automatically.

ML Reference

`Simplifier.norm_hhf: thm -> thm`

`Simplifier.norm_hhf thm` normalizes the given theorem according to the canonical form specified above. This is occasionally helpful to repair some low-level tools that do not handle Hereditary Harrop Formulae properly.

2.4.2 Rule composition

The rule calculus of Isabelle/Pure provides two main inferences: *resolution* (i.e. back-chaining of rules) and *assumption* (i.e. closing a branch), both modulo higher-order unification. There are also combined variants, notably *elim-resolution* and *dest-resolution*.

To understand the all-important *resolution* principle, we first consider raw *composition* (modulo higher-order unification with substitution θ):

$$\frac{\vec{A} \Longrightarrow B \quad B' \Longrightarrow C \quad B\theta = B'\theta}{\vec{A}\theta \Longrightarrow C\theta} \text{ (composition)}$$

Here the conclusion of the first rule is unified with the premise of the second; the resulting rule instance inherits the premises of the first and conclusion of the second. Note that C can again consist of iterated implications. We can also permute the premises of the second rule back-and-forth in order to compose with B' in any position (subsequently we shall always refer to position 1 w.l.o.g.).

In *composition* the internal structure of the common part B and B' is not taken into account. For proper *resolution* we require B to be atomic, and explicitly observe the structure $\bigwedge \vec{x}. \vec{H} \vec{x} \Longrightarrow B' \vec{x}$ of the premise of the second rule. The idea is to adapt the first rule by “lifting” it into this context, by means of iterated application of the following inferences:

$$\frac{\vec{A} \Longrightarrow B}{(\vec{H} \Longrightarrow \vec{A}) \Longrightarrow (\vec{H} \Longrightarrow B)} \text{ (imp-lift)}$$

$$\frac{\vec{A} \text{ ? } \vec{a} \Longrightarrow B \text{ ? } \vec{a}}{(\bigwedge \vec{x}. \vec{A} (\text{? } \vec{a} \vec{x})) \Longrightarrow (\bigwedge \vec{x}. B (\text{? } \vec{a} \vec{x}))} \text{ (all-lift)}$$

By combining raw composition with lifting, we get full *resolution* as follows:

$$\frac{\begin{array}{l} \vec{A} \text{ ? } \vec{a} \Longrightarrow B \text{ ? } \vec{a} \\ (\bigwedge \vec{x}. \vec{H} \vec{x} \Longrightarrow B' \vec{x}) \Longrightarrow C \\ (\bigwedge \vec{x}. B (\text{? } \vec{a} \vec{x}))\theta = B'\theta \end{array}}{(\bigwedge \vec{x}. \vec{H} \vec{x} \Longrightarrow \vec{A} (\text{? } \vec{a} \vec{x}))\theta \Longrightarrow C\theta} \text{ (resolution)}$$

Continued resolution of rules allows to back-chain a problem towards more and sub-problems. Branches are closed either by resolving with a rule of 0 premises, or by producing a “short-circuit” within a solved situation (again modulo unification):

$$\frac{(\wedge \vec{x}. \vec{H} \vec{x} \implies A \vec{x}) \implies C \quad A\theta = H_i\theta \text{ (for some } i\text{)}}{C\theta} \text{ (assumption)}$$

FIXME *elim-resolution, dest-resolution*

ML Reference

```
op RS: thm * thm -> thm
op OF: thm * thm list -> thm
```

rule *RS rule*₂ resolves *rule*₁ with *rule*₂ according to the *resolution* principle explained above. Note that the corresponding attribute in the Isar language is called *THEN*.

rule *OF rules* resolves a list of rules with the first rule, addressing its premises 1, ..., *length rules* (operating from last to first). This means the newly emerging premises are all concatenated, without interfering. Also note that compared to *RS*, the rule argument order is swapped: *rule*₁ *RS rule*₂ = *rule*₂ *OF* [*rule*₁].

Tactical reasoning

Tactical reasoning works by refining the initial claim in a backwards fashion, until a solved form is reached. A *goal* consists of several subgoals that need to be solved in order to achieve the main statement; zero subgoals means that the proof may be finished. A *tactic* is a refinement operation that maps a goal to a lazy sequence of potential successors. A *tactical* is a combinator for composing tactics.

3.1 Goals

Isabelle/Pure represents a goal as a theorem stating that the subgoals imply the main goal: $A_1 \implies \dots \implies A_n \implies C$. The outermost goal structure is that of a Horn Clause: i.e. an iterated implication without any quantifiers¹. For $n = 0$ a goal is called “solved”.

The structure of each subgoal A_i is that of a general Hereditary Harrop Formula $\bigwedge x_1 \dots \bigwedge x_k. H_1 \implies \dots \implies H_m \implies B$. Here x_1, \dots, x_k are goal parameters, i.e. arbitrary-but-fixed entities of certain types, and H_1, \dots, H_m are goal hypotheses, i.e. facts that may be assumed locally. Together, this forms the goal context of the conclusion B to be established. The goal hypotheses may be again arbitrary Hereditary Harrop Formulas, although the level of nesting rarely exceeds 1–2 in practice.

The main conclusion C is internally marked as a protected proposition, which is represented explicitly by the notation $\#C$. This ensures that the decomposition into subgoals and main conclusion is well-defined for arbitrarily structured claims.

Basic goal management is performed via the following Isabelle/Pure rules:

$$\frac{}{C \implies \#C} (init) \quad \frac{\#C}{C} (finish)$$

¹Recall that outermost $\bigwedge x. \varphi[x]$ is always represented via schematic variables in the body: $\varphi[?x]$. These variables may get instantiated during the course of reasoning.

The following low-level variants admit general reasoning with protected propositions:

$$\frac{C}{\#C} \text{ (protect)} \quad \frac{A_1 \Rightarrow \dots \Rightarrow A_n \Rightarrow \#C}{A_1 \Rightarrow \dots \Rightarrow A_n \Rightarrow C} \text{ (conclude)}$$

ML

Reference

```
Goal.init: cterm -> thm
Goal.finish: thm -> thm
Goal.protect: thm -> thm
Goal.conclude: thm -> thm
```

`Goal.init` C initializes a tactical goal from the well-formed proposition C .

`Goal.finish` thm checks whether theorem thm is a solved goal (no subgoals), and concludes the result by removing the goal protection.

`Goal.protect` thm protects the full statement of theorem thm .

`Goal.conclude` thm removes the goal protection, even if there are pending subgoals.

3.2 Tactics

A *tactic* is a function $goal \rightarrow goal^{**}$ that maps a given goal state (represented as a theorem, cf. §3.1) to a lazy sequence of potential successor states. The underlying sequence implementation is lazy both in head and tail, and is purely functional in *not* supporting memoing.²

An *empty result sequence* means that the tactic has failed: in a compound tactic expressions other tactics might be tried instead, or the whole refinement step might fail outright, producing a toplevel error message. When implementing tactics from scratch, one should take care to observe the basic protocol of mapping regular error conditions to an empty result; only serious faults should emerge as exceptions.

By enumerating *multiple results*, a tactic can easily express the potential outcome of an internal search process. There are also combinators for building proof tools that involve search systematically, see also §3.3.

²The lack of memoing and the strict nature of SML requires some care when working with low-level sequence operations, to avoid duplicate or premature evaluation of results.

As explained in §3.1, a goal state essentially consists of a list of subgoals that imply the main goal (conclusion). Tactics may operate on all subgoals or on a particularly specified subgoal, but must not change the main conclusion (apart from instantiating schematic goal variables).

Tactics with explicit *subgoal addressing* are of the form $int \rightarrow tactic$ and may be applied to a particular subgoal (counting from 1). If the subgoal number is out of range, the tactic should fail with an empty result sequence, but must not raise an exception!

Operating on a particular subgoal means to replace it by an interval of zero or more subgoals in the same place; other subgoals must not be affected, apart from instantiating schematic variables ranging over the whole goal state.

A common pattern of composing tactics with subgoal addressing is to try the first one, and then the second one only if the subgoal has not been solved yet. Special care is required here to avoid bumping into unrelated subgoals that happen to come after the original subgoal. Assuming that there is only a single initial subgoal is a very common error when implementing tactics!

Tactics with internal subgoal addressing should expose the subgoal index as *int* argument in full generality; a hardwired subgoal 1 inappropriate.

The main well-formedness conditions for proper tactics are summarized as follows.

- General tactic failure is indicated by an empty result, only serious faults may produce an exception.
- The main conclusion must not be changed, apart from instantiating schematic variables.
- A tactic operates either uniformly on all subgoals, or specifically on a selected subgoal (without bumping into unrelated subgoals).
- Range errors in subgoal addressing produce an empty result.

Some of these conditions are checked by higher-level goal infrastructure (§4.3); others are not checked explicitly, and violating them merely results in ill-behaved tactics experienced by the user (e.g. tactics that insist in being applicable only to singleton goals, or disallow composition with basic tacticals).

ML**Reference**

```

type tactic = thm -> thm Seq.seq
no_tac: tactic
all_tac: tactic
print_tac: string -> tactic
PRIMITIVE: (thm -> thm) -> tactic
SUBGOAL: (term * int -> tactic) -> int -> tactic
CSUBGOAL: (cterm * int -> tactic) -> int -> tactic

```

`tactic` represents tactics. The well-formedness conditions described above need to be observed. See also `~~/src/Pure/General/seq.ML` for the underlying implementation of lazy sequences.

`int -> tactic` represents tactics with explicit subgoal addressing, with well-formedness conditions as described above.

`no_tac` is a tactic that always fails, returning the empty sequence.

`all_tac` is a tactic that always succeeds, returning a singleton sequence with unchanged goal state.

`print_tac message` is like `all_tac`, but prints a message together with the goal state on the tracing channel.

`PRIMITIVE rule` turns a primitive inference rule into a tactic with unique result. Exception `THM` is considered a regular tactic failure and produces an empty result; other exceptions are passed through.

`SUBGOAL (fn (subgoal, i) => tactic)` is the most basic form to produce a tactic with subgoal addressing. The given abstraction over the subgoal term and subgoal number allows to peek at the relevant information of the full goal state. The subgoal range is checked as required above.

`CSUBGOAL` is similar to `SUBGOAL`, but passes the subgoal as `cterm` instead of raw `term`. This avoids expensive re-certification in situations where the subgoal is used directly for primitive inferences.

3.2.1 Resolution and assumption tactics

Resolution is the most basic mechanism for refining a subgoal using a theorem as object-level rule. *Elim-resolution* is particularly suited for elimination rules: it resolves with a rule, proves its first premise by assumption, and finally deletes that assumption from any new subgoals. *Destruct-resolution* is like *elim-resolution*, but the given destruction rules are first turned into

canonical elimination format. *Forward-resolution* is like destruct-resolution, but without deleting the selected assumption. The *r/e/d/f* naming convention is maintained for several different kinds of resolution rules and tactics.

Assumption tactics close a subgoal by unifying some of its premises against its conclusion.

All the tactics in this section operate on a subgoal designated by a positive integer. Other subgoals might be affected indirectly, due to instantiation of schematic variables.

There are various sources of non-determinism, the tactic result sequence enumerates all possibilities of the following choices (if applicable):

1. selecting one of the rules given as argument to the tactic;
2. selecting a subgoal premise to eliminate, unifying it against the first premise of the rule;
3. unifying the conclusion of the subgoal to the conclusion of the rule.

Recall that higher-order unification may produce multiple results that are enumerated here.

ML Reference

```

resolve_tac: thm list -> int -> tactic
eresolve_tac: thm list -> int -> tactic
dresolve_tac: thm list -> int -> tactic
forward_tac: thm list -> int -> tactic

assume_tac: int -> tactic
eq_assume_tac: int -> tactic

match_tac: thm list -> int -> tactic
ematch_tac: thm list -> int -> tactic
dmatch_tac: thm list -> int -> tactic

```

resolve_tac *thms i* refines the goal state using the given theorems, which should normally be introduction rules. The tactic resolves a rule's conclusion with subgoal *i*, replacing it by the corresponding versions of the rule's premises.

eresolve_tac *thms i* performs elim-resolution with the given theorems, which should normally be elimination rules.

dresolve_tac *thms i* performs destruct-resolution with the given theorems, which should normally be destruction rules. This replaces an assumption by the result of applying one of the rules.

`forward_tac` is like `dresolve_tac` except that the selected assumption is not deleted. It applies a rule to an assumption, adding the result as a new assumption.

`assume_tac` i attempts to solve subgoal i by assumption (modulo higher-order unification).

`eq_assume_tac` is similar to `assume_tac`, but checks only for immediate α -convertibility instead of using unification. It succeeds (with a unique next state) if one of the assumptions is equal to the subgoal's conclusion. Since it does not instantiate variables, it cannot make other subgoals unprovable.

`match_tac`, `ematch_tac`, and `dmatch_tac` are similar to `resolve_tac`, `eresolve_tac`, and `dresolve_tac`, respectively, but do not instantiate schematic variables in the goal state.

Flexible subgoals are not updated at will, but are left alone. Strictly speaking, matching means to treat the unknowns in the goal state as constants; these tactics merely discard unifiers that would update the goal state.

3.2.2 Explicit instantiation within a subgoal context

The main resolution tactics (§3.2.1) use higher-order unification, which works well in many practical situations despite its daunting theoretical properties. Nonetheless, there are important problem classes where unguided higher-order unification is not so useful. This typically involves rules like universal elimination, existential introduction, or equational substitution. Here the unification problem involves fully flexible $?P ?x$ schemes, which are hard to manage without further hints.

By providing a (small) rigid term for $?x$ explicitly, the remaining unification problem is to assign a (large) term to $?P$, according to the shape of the given subgoal. This is sufficiently well-behaved in most practical situations.

Isabelle provides separate versions of the standard $r/e/d/f$ resolution tactics that allow to provide explicit instantiations of unknowns of the given rule, wrt. terms that refer to the implicit context of the selected subgoal.

An instantiation consists of a list of pairs of the form $(?x, t)$, where $?x$ is a schematic variable occurring in the given rule, and t is a term from the current proof context, augmented by the local goal parameters of the selected subgoal; cf. the *focus* operation described in §4.1.

Entering the syntactic context of a subgoal is a brittle operation, because its exact form is somewhat accidental, and the choice of bound variable names depends on the presence of other local and global names. Explicit renaming

of subgoal parameters prior to explicit instantiation might help to achieve a bit more robustness.

Type instantiations may be given as well, via pairs like $(?a, \tau)$. Type instantiations are distinguished from term instantiations by the syntactic form of the schematic variable. Types are instantiated before terms are. Since term instantiation already performs type-inference as expected, explicit type instantiations are seldom necessary.

ML Reference

```
res_inst_tac: Proof.context -> (indexname * string) list -> thm -> int -> tactic
eres_inst_tac: Proof.context -> (indexname * string) list -> thm -> int -> tactic
dres_inst_tac: Proof.context -> (indexname * string) list -> thm -> int -> tactic
forw_inst_tac: Proof.context -> (indexname * string) list -> thm -> int -> tactic
rename_tac: string list -> int -> tactic
```

`res_inst_tac ctxt insts thm i` instantiates the rule `thm` with the instantiations `insts`, as described above, and then performs resolution on subgoal `i`.

`eres_inst_tac` is like `res_inst_tac`, but performs elim-resolution.

`dres_inst_tac` is like `res_inst_tac`, but performs destruct-resolution.

`forw_inst_tac` is like `dres_inst_tac` except that the selected assumption is not deleted.

`rename_tac names i` renames the innermost parameters of subgoal `i` according to the provided `names` (which need to be distinct identifiers).

3.3 Tacticals

A *tactical* is a functional combinator for building up complex tactics from simpler ones. Typical tactical perform sequential composition, disjunction (choice), iteration, or goal addressing. Various search strategies may be expressed via tacticals.

FIXME

Structured proofs

4.1 Variables

Any variable that is not explicitly bound by λ -abstraction is considered as “free”. Logically, free variables act like outermost universal quantification at the sequent level: $A_1(x), \dots, A_n(x) \vdash B(x)$ means that the result holds *for all* values of x . Free variables for terms (not types) can be fully internalized into the logic: $\vdash B(x)$ and $\vdash \bigwedge x. B(x)$ are interchangeable, provided that x does not occur elsewhere in the context. Inspecting $\vdash \bigwedge x. B(x)$ more closely, we see that inside the quantifier, x is essentially “arbitrary, but fixed”, while from outside it appears as a place-holder for instantiation (thanks to \bigwedge elimination).

The Pure logic represents the idea of variables being either inside or outside the current scope by providing separate syntactic categories for *fixed variables* (e.g. x) vs. *schematic variables* (e.g. $?x$). Incidentally, a universal result $\vdash \bigwedge x. B(x)$ has the HHF normal form $\vdash B(?x)$, which represents its generality nicely without requiring an explicit quantifier. The same principle works for type variables: $\vdash B(? \alpha)$ represents the idea of “ $\vdash \forall \alpha. B(\alpha)$ ” without demanding a truly polymorphic framework.

Additional care is required to treat type variables in a way that facilitates type-inference. In principle, term variables depend on type variables, which means that type variables would have to be declared first. For example, a raw type-theoretic framework would demand the context to be constructed in stages as follows: $\Gamma = \alpha: \text{type}, x: \alpha, a: A(x_\alpha)$.

We allow a slightly less formalistic mode of operation: term variables x are fixed without specifying a type yet (essentially *all* potential occurrences of some instance x_τ are fixed); the first occurrence of x within a specific term assigns its most general type, which is then maintained consistently in the context. The above example becomes $\Gamma = x: \text{term}, \alpha: \text{type}, A(x_\alpha)$, where type α is fixed *after* term x , and the constraint $x :: \alpha$ is an implicit consequence of the occurrence of x_α in the subsequent proposition.

This twist of dependencies is also accommodated by the reverse operation of exporting results from a context: a type variable α is considered fixed as

long as it occurs in some fixed term variable of the context. For example, exporting $x: \text{term}, \alpha: \text{type} \vdash x_\alpha = x_\alpha$ produces in the first step $x: \text{term} \vdash x_\alpha = x_\alpha$ for fixed α , and only in the second step $\vdash ?x_{? \alpha} = ?x_{? \alpha}$ for schematic $?x$ and $? \alpha$.

The Isabelle/Isar proof context manages the gory details of term vs. type variables, with high-level principles for moving the frontier between fixed and schematic variables.

The *add-fixes* operation explicitly declares fixed variables; the *declare-term* operation absorbs a term into a context by fixing new type variables and adding syntactic constraints.

The *export* operation is able to perform the main work of generalizing term and type variables as sketched above, assuming that fixing variables and terms have been declared properly.

There *import* operation makes a generalized fact a genuine part of the context, by inventing fixed variables for the schematic ones. The effect can be reversed by using *export* later, potentially with an extended context; the result is equivalent to the original modulo renaming of schematic variables.

The *focus* operation provides a variant of *import* for nested propositions (with explicit quantification): $\bigwedge x_1 \dots x_n. B(x_1, \dots, x_n)$ is decomposed by inventing fixed variables x_1, \dots, x_n for the body.

ML Reference

```
Variable.add_fixes:
  string list -> Proof.context -> string list * Proof.context
Variable.variant_fixes:
  string list -> Proof.context -> string list * Proof.context
Variable.declare_term: term -> Proof.context -> Proof.context
Variable.declare_constraints: term -> Proof.context -> Proof.context
Variable.export: Proof.context -> Proof.context -> thm list -> thm list
Variable.polymorphic: Proof.context -> term list -> term list
Variable.import_thms: bool -> thm list -> Proof.context ->
  ((ctyp list * cterm list) * thm list) * Proof.context
Variable.focus: cterm -> Proof.context -> (cterm list * cterm) * Proof.context
```

Variable.add_fixes *xs ctxt* fixes term variables *xs*, returning the resulting internal names. By default, the internal representation coincides with the external one, which also means that the given variables must not be fixed already. There is a different policy within a local proof body: the given names are just hints for newly invented Skolem variables.

Variable.variant_fixes is similar to **Variable.add_fixes**, but always produces fresh variants of the given names.

`Variable.declare_term t $ctxt$` declares term t to belong to the context. This automatically fixes new type variables, but not term variables. Syntactic constraints for type and term variables are declared uniformly, though.

`Variable.declare_constraints t $ctxt$` declares syntactic constraints from term t , without making it part of the context yet.

`Variable.export $inner$ $outer$ $thms$` generalizes fixed type and term variables in $thms$ according to the difference of the *inner* and *outer* context, following the principles sketched above.

`Variable.polymorphic $ctxt$ ts` generalizes type variables in ts as far as possible, even those occurring in fixed term variables. The default policy of type-inference is to fix newly introduced type variables, which is essentially reversed with `Variable.polymorphic`: here the given terms are detached from the context as far as possible.

`Variable.import_thms $open$ $thms$ $ctxt$` invents fixed type and term variables for the schematic ones occurring in $thms$. The *open* flag indicates whether the fixed names should be accessible to the user, otherwise newly introduced names are marked as “internal” (§1.2).

`Variable.focus B` decomposes the outermost \wedge prefix of proposition B .

4.2 Assumptions

An *assumption* is a proposition that it is postulated in the current context. Local conclusions may use assumptions as additional facts, but this imposes implicit hypotheses that weaken the overall statement.

Assumptions are restricted to fixed non-schematic statements, i.e. all generality needs to be expressed by explicit quantifiers. Nevertheless, the result will be in HHF normal form with outermost quantifiers stripped. For example, by assuming $\wedge x :: \alpha. P\ x$ we get $\wedge x :: \alpha. P\ x \vdash P\ ?x$ for schematic $?x$ of fixed type α . Local derivations accumulate more and more explicit references to hypotheses: $A_1, \dots, A_n \vdash B$ where A_1, \dots, A_n needs to be covered by the assumptions of the current context.

The *add-assms* operation augments the context by local assumptions, which are parameterized by an arbitrary *export* rule (see below).

The *export* operation moves facts from a (larger) inner context into a (smaller) outer context, by discharging the difference of the assumptions as specified by the associated export rules. Note that the discharged portion is determined by the difference contexts, not the facts being exported! There is

a separate flag to indicate a goal context, where the result is meant to refine an enclosing sub-goal of a structured proof state.

The most basic export rule discharges assumptions directly by means of the \Rightarrow introduction rule:

$$\frac{\Gamma \vdash B}{\Gamma \setminus A \vdash A \Rightarrow B} (\Rightarrow\text{-intro})$$

The variant for goal refinements marks the newly introduced premises, which causes the canonical Isar goal refinement scheme to enforce unification with local premises within the goal:

$$\frac{\Gamma \vdash B}{\Gamma \setminus A \vdash \#A \Rightarrow B} (\#\Rightarrow\text{-intro})$$

Alternative versions of assumptions may perform arbitrary transformations on export, as long as the corresponding portion of hypotheses is removed from the given facts. For example, a local definition works by fixing x and assuming $x \equiv t$, with the following export rule to reverse the effect:

$$\frac{\Gamma \vdash B \ x}{\Gamma \setminus x \equiv t \vdash B \ t} (\equiv\text{-expand})$$

This works, because the assumption $x \equiv t$ was introduced in a context with x being fresh, so x does not occur in Γ here.

ML Reference

```

type Assumption.export
Assumption.assume: cterm -> thm
Assumption.add_assms: Assumption.export ->
  cterm list -> Proof.context -> thm list * Proof.context
Assumption.add_assumes:
  cterm list -> Proof.context -> thm list * Proof.context
Assumption.export: bool -> Proof.context -> Proof.context -> thm -> thm

```

`Assumption.export` represents arbitrary export rules, which is any function of type `bool -> cterm list -> thm -> thm`, where the `bool` indicates goal mode, and the `cterm list` the collection of assumptions to be discharged simultaneously.

`Assumption.assume` A turns proposition A into a raw assumption $A \vdash A'$, where the conclusion A' is in HHF normal form.

`Assumption.add_assms` r As augments the context by assumptions As with export rule r . The resulting facts are hypothetical theorems as produced by the raw `Assumption.assume`.

`Assumption.add_assumes As` is a special case of `Assumption.add_assms` where the export rule performs \Rightarrow -intro or $\# \Rightarrow$ -intro, depending on goal mode.

`Assumption.export is-goal inner outer thm` exports result *thm* from the the *inner* context back into the *outer* one; *is-goal* = *true* means this is a goal context. The result is in HHF normal form. Note that `ProofContext.export` combines `Variable.export` and `Assumption.export` in the canonical way.

4.3 Results

Local results are established by monotonic reasoning from facts within a context. This allows common combinations of theorems, e.g. via \wedge/\Rightarrow elimination, resolution rules, or equational reasoning, see §2.3. Unaccounted context manipulations should be avoided, notably raw \wedge/\Rightarrow introduction or ad-hoc references to free variables or assumptions not present in the proof context.

The *SUBPROOF* combinator allows to structure a tactical proof recursively by decomposing a selected sub-goal: $(\wedge x. A(x) \Rightarrow B(x)) \Rightarrow \dots$ is turned into $B(x) \Rightarrow \dots$ after fixing x and assuming $A(x)$. This means the tactic needs to solve the conclusion, but may use the premise as a local fact, for locally fixed variables.

The *prove* operation provides an interface for structured backwards reasoning under program control, with some explicit sanity checks of the result. The goal context can be augmented by additional fixed variables (cf. §4.1) and assumptions (cf. §4.2), which will be available as local facts during the proof and discharged into implications in the result. Type and term variables are generalized as usual, according to the context.

The *obtain* operation produces results by eliminating existing facts by means of a given tactic. This acts like a dual conclusion: the proof demonstrates that the context may be augmented by certain fixed variables and assumptions. See also [11] for the user-level **obtain** and **guess** elements. Final results, which may not refer to the parameters in the conclusion, need to exported explicitly into the original context.

ML Reference

```
SUBPROOF: ({context: Proof.context, schematics: ctyp list * cterm list,
  params: cterm list, asms: cterm list, concl: cterm,
  prems: thm list} -> tactic) -> Proof.context -> int -> tactic
```

```

Goal.prove: Proof.context -> string list -> term list -> term ->
  ({prems: thm list, context: Proof.context} -> tactic) -> thm
Goal.prove_multi: Proof.context -> string list -> term list -> term list ->
  ({prems: thm list, context: Proof.context} -> tactic) -> thm list
Obtain.result: (Proof.context -> tactic) ->
  thm list -> Proof.context -> (cterm list * thm list) * Proof.context

```

SUBPROOF *tac ctxt i* decomposes the structure of the specified sub-goal, producing an extended context and a reduced goal, which needs to be solved by the given tactic. All schematic parameters of the goal are imported into the context as fixed ones, which may not be instantiated in the sub-proof.

Goal.prove *ctxt xs As C tac* states goal *C* in the context augmented by fixed variables *xs* and assumptions *As*, and applies tactic *tac* to solve it. The latter may depend on the local assumptions being presented as facts. The result is in HHF normal form.

Goal.prove_multi is similar to **Goal.prove**, but states several conclusions simultaneously. The goal is encoded by means of Pure conjunction; **Goal.conjunction_tac** will turn this into a collection of individual sub-goals.

Obtain.result *tac thms ctxt* eliminates the given facts using a tactic, which results in additional fixed variables and assumptions in the context. Final results need to be exported explicitly.

Syntax and type-checking

FIXME

Isar language elements

The primary Isar language consists of three main categories of language elements:

1. Proof commands
2. Proof methods
3. Attributes

6.1 Proof commands

FIXME

6.2 Proof methods

FIXME

6.3 Attributes

FIXME

Local theory specifications

A *local theory* combines aspects of both theory and proof context (cf. §1.1), such that definitional specifications may be given relatively to parameters and assumptions. A local theory is represented as a regular proof context, augmented by administrative data about the *target context*.

The target is usually derived from the background theory by adding local **fix** and **assume** elements, plus suitable modifications of non-logical context data (e.g. a special type-checking discipline). Once initialized, the target is ready to absorb definitional primitives: **define** for terms and **note** for theorems. Such definitions may get transformed in a target-specific way, but the programming interface hides such details.

Isabelle/Pure provides target mechanisms for locales, type-classes, type-class instantiations, and general overloading. In principle, users can implement new targets as well, but this rather arcane discipline is beyond the scope of this manual. In contrast, implementing derived definitional packages to be used within a local theory context is quite easy: the interfaces are even simpler and more abstract than the underlying primitives for raw theories.

Many definitional packages for local theories are available in Isabelle. Although a few old packages only work for global theories, the local theory interface is already the standard way of implementing definitional packages in Isabelle.

7.1 Definitional elements

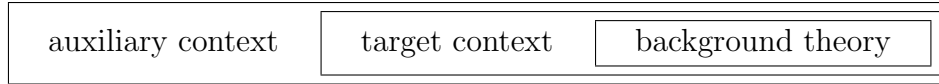
There are separate elements **define** $c \equiv t$ for terms, and **note** $b = thm$ for theorems. Types are treated implicitly, according to Hindley-Milner discipline (cf. §4.1). These definitional primitives essentially act like *let*-bindings within a local context that may already contain earlier *let*-bindings and some initial λ -bindings. Thus we gain *dependent definitions* that are relative to an initial axiomatic context. The following diagram illustrates this idea of axiomatic elements versus definitional elements:

	λ -binding	<i>let</i> -binding
types	fixed α	arbitrary β
terms	fix $x :: \tau$	define $c \equiv t$
theorems	assume $a: A$	note $b = \langle B \rangle$

A user package merely needs to produce suitable **define** and **note** elements according to the application. For example, a package for inductive definitions might first **define** a certain predicate as some fixed-point construction, then **note** a proven result about monotonicity of the functor involved here, and then produce further derived concepts via additional **define** and **note** elements.

The cumulative sequence of **define** and **note** produced at package runtime is managed by the local theory infrastructure by means of an *auxiliary context*. Thus the system holds up the impression of working within a fully abstract situation with hypothetical entities: **define** $c \equiv t$ always results in a literal fact $\langle c \equiv t \rangle$, where c is a fixed variable c . The details about global constants, name spaces etc. are handled internally.

So the general structure of a local theory is a sandwich of three layers:



When a definitional package is finished, the auxiliary context is reset to the target context. The target now holds definitions for terms and theorems that stem from the hypothetical **define** and **note** elements, transformed by the particular target policy (see [5, §4–5] for details).

ML Reference

```

type local_theory = Proof.context
TheoryTarget.init: string option -> theory -> local_theory

LocalTheory.define: string ->
  (binding * mixfix) * (Attrib.binding * term) -> local_theory ->
  (term * (string * thm)) * local_theory
LocalTheory.note: string ->
  Attrib.binding * thm list -> local_theory ->
  (string * thm list) * local_theory

```

`local_theory` represents local theories. Although this is merely an alias for `Proof.context`, it is semantically a subtype of the same: a `local_theory` holds target information as special context data. Subtyping means that any value `lthy: local_theory` can be also used with operations on expecting a regular `ctxt: Proof.context`.

`TheoryTarget.init` *NONE* *thy* initializes a trivial local theory from the given background theory. Alternatively, *SOME name* may be given to initialize a **locale** or **class** context (a fully-qualified internal name is expected here). This is useful for experimentation — normally the Isar toplevel already takes care to initialize the local theory context.

`LocalTheory.define` *kind* $((b, mx), (a, rhs))$ *lthy* defines a local entity according to the specification that is given relatively to the current *lthy* context. In particular the term of the RHS may refer to earlier local entities from the auxiliary context, or hypothetical parameters from the target context. The result is the newly defined term (which is always a fixed variable with exactly the same name as specified for the LHS), together with an equational theorem that states the definition as a hypothetical fact.

Unless an explicit name binding is given for the RHS, the resulting fact will be called *b-def*. Any given attributes are applied to that same fact — immediately in the auxiliary context *and* in any transformed versions stemming from target-specific policies or any later interpretations of results from the target context (think of **locale** and **interpretation**, for example). This means that attributes should be usually plain declarations such as *simp*, while non-trivial rules like *simplified* are better avoided.

The *kind* determines the theorem kind tag of the resulting fact. Typical examples are `Thm.definitionK`, `Thm.theoremK`, or `Thm.internalK`.

`LocalTheory.note` *kind* (a, ths) *lthy* is analogous to `LocalTheory.define`, but defines facts instead of terms. There is also a slightly more general variant `LocalTheory.notes` that defines several facts (with attribute expressions) simultaneously.

This is essentially the internal version of the **lemmas** command, or **declare** if an empty name binding is given.

7.2 Morphisms and declarations

FIXME

System integration

8.1 Isar toplevel

The Isar toplevel may be considered the central hub of the Isabelle/Isar system, where all key components and sub-systems are integrated into a single read-eval-print loop of Isar commands. We shall even incorporate the existing ML toplevel of the compiler and run-time system (cf. §8.2).

Isabelle/Isar departs from the original “LCF system architecture” where ML was really The Meta Language for defining theories and conducting proofs. Instead, ML now only serves as the implementation language for the system (and user extensions), while the specific Isar toplevel supports the concepts of theory and proof development natively. This includes the graph structure of theories and the block structure of proofs, support for unlimited undo, facilities for tracing, debugging, timing, profiling etc.

The toplevel maintains an implicit state, which is transformed by a sequence of transitions – either interactively or in batch-mode. In interactive mode, Isar state transitions are encapsulated as safe transactions, such that both failure and undo are handled conveniently without destroying the underlying draft theory (cf. §1.1.1). In batch mode, transitions operate in a linear (destructive) fashion, such that error conditions abort the present attempt to construct a theory or proof altogether.

The toplevel state is a disjoint sum of empty *toplevel*, or *theory*, or *proof*. On entering the main Isar loop we start with an empty toplevel. A theory is commenced by giving a **theory** header; within a theory we may issue theory commands such as **definition**, or state a **theorem** to be proven. Now we are within a proof state, with a rich collection of Isar proof commands for structured proof composition, or unstructured proof scripts. When the proof is concluded we get back to the theory, which is then updated by storing the resulting fact. Further theory declarations or theorem statements with proofs may follow, until we eventually conclude the theory development by issuing **end**. The resulting theory is then stored within the theory database and we are back to the empty toplevel.

In addition to these proper state transformations, there are also some

diagnostic commands for peeking at the toplevel state without modifying it (e.g. **thm**, **term**, **print-cases**).

ML Reference

```
type Toplevel.state
Toplevel.UNDEF: exn
Toplevel.is_toplevel: Toplevel.state -> bool
Toplevel.theory_of: Toplevel.state -> theory
Toplevel.proof_of: Toplevel.state -> Proof.state
Toplevel.debug: bool ref
Toplevel.timing: bool ref
Toplevel.profiling: int ref
```

Toplevel.state represents Isar toplevel states, which are normally manipulated through the concept of toplevel transitions only (§8.1.1). Also note that a raw toplevel state is subject to the same linearity restrictions as a theory context (cf. §1.1.1).

Toplevel.UNDEF is raised for undefined toplevel operations. Many operations work only partially for certain cases, since **Toplevel.state** is a sum type.

Toplevel.is_toplevel *state* checks for an empty toplevel state.

Toplevel.theory_of *state* selects the theory of a theory or proof (!), otherwise raises **Toplevel.UNDEF**.

Toplevel.proof_of *state* selects the Isar proof state if available, otherwise raises **Toplevel.UNDEF**.

set Toplevel.debug makes the toplevel print further details about internal error conditions, exceptions being raised etc.

set Toplevel.timing makes the toplevel print timing information for each Isar command being executed.

Toplevel.profiling := *n* controls low-level profiling of the underlying ML run-time system. For Poly/ML, *n* = 1 means time and *n* = 2 space profiling.

8.1.1 Toplevel transitions

An Isar toplevel transition consists of a partial function on the toplevel state, with additional information for diagnostics and error reporting: there are fields for command name, source position, optional source text, as well as

flags for interactive-only commands (which issue a warning in batch-mode), printing of result state, etc.

The operational part is represented as the sequential union of a list of partial functions, which are tried in turn until the first one succeeds. This acts like an outer case-expression for various alternative state transitions. For example, **qed** acts differently for a local proofs vs. the global ending of the main proof.

Toplevel transitions are composed via transition transformers. Internally, Isar commands are put together from an empty transition extended by name and source position (and optional source text). It is then left to the individual command parser to turn the given concrete syntax into a suitable transition transformer that adjoins actual operations on a theory or proof state etc.

ML Reference

```

Toplevel.print: Toplevel.transition -> Toplevel.transition
Toplevel.no_timing: Toplevel.transition -> Toplevel.transition
Toplevel.keep: (Toplevel.state -> unit) ->
  Toplevel.transition -> Toplevel.transition
Toplevel.theory: (theory -> theory) ->
  Toplevel.transition -> Toplevel.transition
Toplevel.theory_to_proof: (theory -> Proof.state) ->
  Toplevel.transition -> Toplevel.transition
Toplevel.proof: (Proof.state -> Proof.state) ->
  Toplevel.transition -> Toplevel.transition
Toplevel.proofs: (Proof.state -> Proof.state Seq.seq) ->
  Toplevel.transition -> Toplevel.transition
Toplevel.end_proof: (bool -> Proof.state -> Proof.context) ->
  Toplevel.transition -> Toplevel.transition

```

Toplevel.print *tr* sets the print flag, which causes the toplevel loop to echo the result state (in interactive mode).

Toplevel.no_timing *tr* indicates that the transition should never show timing information, e.g. because it is a diagnostic command.

Toplevel.keep *tr* adjoins a diagnostic function.

Toplevel.theory *tr* adjoins a theory transformer.

Toplevel.theory_to_proof *tr* adjoins a global goal function, which turns a theory into a proof state. The theory may be changed before entering the proof; the generic Isar goal setup includes an argument that specifies how to apply the proven result to the theory, when the proof is finished.

Toplevel.proof *tr* adjoins a deterministic proof command, with a singleton result.

Toplevel.proofs *tr* adjoins a general proof command, with zero or more result states (represented as a lazy list).

Toplevel.end_proof *tr* adjoins a concluding proof command, that returns the resulting theory, after storing the resulting facts in the context etc.

8.1.2 Toplevel control

There are a few special control commands that modify the behavior the toplevel itself, and only make sense in interactive mode. Under normal circumstances, the user encounters these only implicitly as part of the protocol between the Isabelle/Isar system and a user-interface such as ProofGeneral.

undo follows the three-level hierarchy of empty toplevel vs. theory vs. proof: undo within a proof reverts to the previous proof context, undo after a proof reverts to the theory before the initial goal statement, undo of a theory command reverts to the previous theory value, undo of a theory header discontinues the current theory development and removes it from the theory database (§8.3).

kill aborts the current level of development: kill in a proof context reverts to the theory before the initial goal statement, kill in a theory context aborts the current theory development, removing it from the database.

exit drops out of the Isar toplevel into the underlying ML toplevel (§8.2). The Isar toplevel state is preserved and may be continued later.

quit terminates the Isabelle/Isar process without saving.

8.2 ML toplevel

The ML toplevel provides a read-compile-eval-print loop for ML values, types, structures, and functors. ML declarations operate on the global system state, which consists of the compiler environment plus the values of ML reference variables. There is no clean way to undo ML declarations, except for reverting to a previously saved state of the whole Isabelle process. ML input is either read interactively from a TTY, or from a string (usually within a theory text), or from a source file (usually loaded from a theory).

Whenever the ML toplevel is active, the current Isabelle theory context is passed as an internal reference variable. Thus ML code may access the theory context during compilation, it may even change the value of a theory being under construction — while observing the usual linearity restrictions (cf. §1.1.1).

ML Reference

```
the_context: unit -> theory
Context.>> : (Context.generic -> Context.generic) -> unit
```

`the_context ()` refers to the theory context of the ML toplevel — at compile time! ML code needs to take care to refer to `the_context ()` correctly. Recall that evaluation of a function body is delayed until actual runtime. Moreover, persistent ML toplevel bindings to an unfinished theory should be avoided: code should either project out the desired information immediately, or produce an explicit `theory_ref` (cf. §1.1.1).

`Context.>> f` applies context transformation f to the implicit context of the ML toplevel.

It is very important to note that the above functions are really restricted to the compile time, even though the ML compiler is invoked at runtime! The majority of ML code uses explicit functional arguments of a theory or proof context instead. Thus it may be invoked for an arbitrary context later on, without having to worry about any operational details.

```
Isar.main: unit -> unit
Isar.loop: unit -> unit
Isar.state: unit -> Toplevel.state
Isar.exn: unit -> (exn * string) option
Isar.context: unit -> Proof.context
Isar.goal: unit -> thm
```

`Isar.main ()` invokes the Isar toplevel from ML, initializing an empty toplevel state.

`Isar.loop ()` continues the Isar toplevel with the current state, after having dropped out of the Isar toplevel loop.

`Isar.state ()` and `Isar.exn ()` get current toplevel state and error condition, respectively. This only works after having dropped out of the Isar toplevel loop.

`Isar.context ()` produces the proof context from `Isar.state ()`, analogous to `Context.proof_of` (§1.1.3).

`Isar.goal ()` picks the tactical goal from `Isar.state ()`, represented as a theorem according to §3.1.

8.3 Theory database

The theory database maintains a collection of theories, together with some administrative information about their original sources, which are held in an external store (i.e. some directory within the regular file system).

The theory database is organized as a directed acyclic graph; entries are referenced by theory name. Although some additional interfaces allow to include a directory specification as well, this is only a hint to the underlying theory loader. The internal theory name space is flat!

Theory *A* is associated with the main theory file *A.thy*, which needs to be accessible through the theory loader path. Any number of additional ML source files may be associated with each theory, by declaring these dependencies in the theory header as **uses**, and loading them consecutively within the theory context. The system keeps track of incoming ML sources and associates them with the current theory. The file *A.ML* is loaded after a theory has been concluded, in order to support legacy proof ML proof scripts.

The basic internal actions of the theory database are *update*, *outdate*, and *remove*:

- *update A* introduces a link of *A* with a *theory* value of the same name; it asserts that the theory sources are now consistent with that value;
- *outdate A* invalidates the link of a theory database entry to its sources, but retains the present theory value;
- *remove A* deletes entry *A* from the theory database.

These actions are propagated to sub- or super-graphs of a theory entry as expected, in order to preserve global consistency of the state of all loaded theories with the sources of the external store. This implies certain causalities between actions: *update* or *outdate* of an entry will *outdate* all descendants; *remove* will *remove* all descendants.

There are separate user-level interfaces to operate on the theory database directly or indirectly. The primitive actions then just happen automatically while working with the system. In particular, processing a theory header **theory *A* imports $B_1 \dots B_n$ begin** ensures that the sub-graph of the collective imports $B_1 \dots B_n$ is up-to-date, too. Earlier theories are reloaded

as required, with *update* actions proceeding in topological order according to theory dependencies. There may be also a wave of implied *outdate* actions for derived theory nodes until a stable situation is achieved eventually.

ML Reference

```
theory: string -> theory
use_thy: string -> unit
use_thys: string list -> unit
ThyInfo.touch_thy: string -> unit
ThyInfo.remove_thy: string -> unit

ThyInfo.begin_theory: ... -> bool -> theory
ThyInfo.end_theory: theory -> unit
ThyInfo.register_theory: theory -> unit

datatype action = Update | Outdate | Remove
ThyInfo.add_hook: (ThyInfo.action -> string -> unit) -> unit
```

`theory A` retrieves the theory value presently associated with name *A*. Note that the result might be outdated.

`use_thy A` ensures that theory *A* is fully up-to-date wrt. the external file store, reloading outdated ancestors as required.

`use_thys` is similar to `use_thy`, but handles several theories simultaneously. Thus it acts like processing the import header of a theory, without performing the merge of the result, though.

`ThyInfo.touch_thy A` performs an *outdate* action on theory *A* and all descendants.

`ThyInfo.remove_thy A` deletes theory *A* and all descendants from the theory database.

`ThyInfo.begin_theory` is the basic operation behind a **theory** header declaration. This ML function is normally not invoked directly.

`ThyInfo.end_theory` concludes the loading of a theory proper and stores the result in the theory database.

`ThyInfo.register_theory text thy` registers an existing theory value with the theory loader database. There is no management of associated sources.

`ThyInfo.add_hook f` registers function *f* as a hook for theory database actions. The function will be invoked with the action and theory name being involved; thus derived actions may be performed in associated system components, e.g. maintaining the state of an editor for the theory sources.

The kind and order of actions occurring in practice depends both on user interactions and the internal process of resolving theory imports. Hooks should not rely on a particular policy here! Any exceptions raised by the hook are ignored.

Advanced ML programming

A.1 Style

Like any style guide, also this one should not be interpreted dogmatically, but with care and discernment. It consists of a collection of recommendations which have been turned out useful over long years of Isabelle system development and are supposed to support writing of readable and managable code. Special cases encourage derivations, as far as you know what you are doing.¹

fundamental law of programming Whenever writing code, keep in mind: A program is written once, modified ten times, and read hundred times. So simplify its writing, always keep future modifications in mind, and never jeopardize readability. Every second you hesitate to spend on making your code more clear you will have to spend ten times understanding what you have written later on.

white space matters Treat white space in your code as if it determines the meaning of code.

- The space bar is the easiest key to find on the keyboard, press it as often as necessary. `2 + 2` is better than `2+2`, likewise `f (x, y)` is better than `f(x,y)`.
- Restrict your lines to 80 characters. This will allow you to keep the beginning of a line in view while watching its end.²
- Ban tabulators; they are a context-sensitive formatting feature and likely to confuse anyone not using your favorite editor.³

¹This style guide is loosely based on <http://caml.inria.fr/resources/doc/guides/guidelines.en.html>

²To acknowledge the lax practice of text editing these days, we tolerate as much as 100 characters per line, but anything beyond 120 is not considered proper source text.

³Some modern programming language even forbid tabulators altogether according to the formal syntax definition.

- Get rid of trailing whitespace. Instead, do not suppress a trailing newline at the end of your files.
- Choose a generally accepted style of indentation, then use it systematically throughout the whole application. An indentation of two spaces is appropriate. Avoid dangling indentation.

cut-and-paste succeeds over copy-and-paste *Never* copy-and-paste code when programming. If you need the same piece of code twice, introduce a reasonable auxiliary function (if there is no such function, very likely you got something wrong). Any copy-and-paste will turn out to be painful when something has to be changed later on.

comments are a device which requires careful thinking before using it. The best comment for your code should be the code itself. Prefer efforts to write clear, understandable code over efforts to explain nasty code.

functional programming is based on functions Model things as abstract as appropriate. Avoid unnecessarily concrete datatype representations. For example, consider a function taking some table data structure as argument and performing lookups on it. Instead of taking a table, it could likewise take just a lookup function. Accustom your way of coding to the level of expressiveness a functional programming language is giving onto you.

tuples are often in the way. When there is no striking argument to tuple function arguments, just write your function curried.

telling names Any name should tell its purpose as exactly as possible, while keeping its length to the absolutely necessary minimum. Always give the same name to function arguments which have the same meaning. Separate words by underscores (`int_of_string`, not `intOfString`).⁴

A.2 Thread-safe programming

Recent versions of Poly/ML (5.2.1 or later) support robust multithreaded execution, based on native operating system threads of the underlying platform. Thus threads will actually be executed in parallel on multi-core systems. A

⁴Some recent tools for Emacs include special precautions to cope with bumpy names in *camelCase*, e.g. for improved on-screen readability. It is easier to abstain from using such names in the first place.

speedup-factor of approximately 1.5–3 can be expected on a regular 4-core machine.⁵ Threads also help to organize advanced operations of the system, with explicit communication between sub-components, real-time conditions, time-outs etc.

Threads lack the memory protection of separate processes, and operate concurrently on shared heap memory. This has the advantage that results of independent computations are immediately available to other threads, without requiring untyped character streams, awkward serialization etc.

On the other hand, some programming guidelines need to be observed in order to make unprotected parallelism work out smoothly. While the ML system implementation is responsible to maintain basic integrity of the representation of ML values in memory, the application programmer needs to ensure that multithreaded execution does not break the intended semantics.

Critical shared resources. Actually only those parts outside the purely functional world of ML are critical. In particular, this covers

- global references (or arrays), i.e. those that persist over several invocations of associated operations,⁶
- direct I/O on shared channels, notably *stdin*, *stdout*, *stderr*.

The majority of tools implemented within the Isabelle/Isar framework will not require any of these critical elements: nothing special needs to be observed when staying in the purely functional fragment of ML. Note that output via the official Isabelle channels does not count as direct I/O, so the operations `writeln`, `warning`, `tracing` etc. are safe.

Moreover, ML bindings within the toplevel environment (`type`, `val`, `structure` etc.) due to run-time invocation of the compiler are also safe, because Isabelle/Isar manages this as part of the theory or proof context.

Multithreading in Isabelle/Isar. The theory loader automatically exploits the overall parallelism of independent nodes in the development graph, as well as the inherent irrelevance of proofs for goals being fully specified in advance. This means, checking of individual Isar proofs is parallelized by default. Beyond that, very sophisticated proof tools may use local parallelism

⁵There is some inherent limitation of the speedup factor due to garbage collection, which is still sequential. It helps to provide initial heap space generously, using the `-H` option of Poly/ML.

⁶This is independent of the visibility of such mutable values in the toplevel scope.

internally, via the general programming model of “future values” (see also `~/src/Pure/Concurrent/future.ML`).

Any ML code that works relatively to the present background theory is already safe. Contextual data may be easily stored within the theory or proof context, thanks to the generic data concept of Isabelle/Isar (see §1.1.4). This greatly diminishes the demand for global state information in the first place.

In rare situations where actual mutable content needs to be manipulated, Isabelle provides a single *critical section* that may be entered while preventing any other thread from doing the same. Entering the critical section without contention is very fast, and several basic system operations do so frequently. This also means that each thread should leave the critical section quickly, otherwise parallel execution performance may degrade significantly.

Despite this potential bottle-neck, centralized locking is convenient, because it prevents deadlocks without demanding special precautions. Explicit communication demands other means, though. The high-level abstraction of synchronized variables `~/src/Pure/Concurrent/synchronized.ML` enables parallel components to communicate via shared state; see also `~/src/Pure/Concurrent/mailbox.ML` as canonical example.

Good conduct of impure programs. The following guidelines enable non-functional programs to participate in multithreading.

- Minimize global state information. Using proper theory and proof context data will actually return to functional update of values, without any special precautions for multithreading. Apart from the fully general functors for theory and proof data (see §1.1.4) there are drop-in replacements that emulate primitive references for common cases of *configuration options* for type `bool/int/string` (see structure `Config` and `Attrib.config_bool` etc.), and lists of theorems (see functor `NamedThmsFun`).
- Keep components with local state information *re-entrant*. Instead of poking initial values into (private) global references, create a new state record on each invocation, and pass that through any auxiliary functions of the component. The state record may well contain mutable references, without requiring any special synchronizations, as long as each invocation sees its own copy. Occasionally, one might even return to plain functional updates on non-mutable record values here.
- Isolate process configuration flags. The main legitimate application of global references is to configure the whole process in a certain way,

essentially affecting all threads. A typical example is the `show_types` flag, which tells the pretty printer to output explicit type information for terms. Such flags usually do not affect the functionality of the core system, but only the view being presented to the user.

Occasionally, such global process flags are treated like implicit arguments to certain operations, by using the `setmp` combinator for safe temporary assignment. Its traditional purpose was to ensure proper recovery of the original value when exceptions are raised in the body, now the functionality is extended to enter the *critical section* (with its usual potential of degrading parallelism).

Note that recovery of plain value passing semantics via `setmp ref value` assumes that this *ref* is exclusively manipulated within the critical section. In particular, any persistent global assignment of *ref* := *value* needs to be marked critical as well, to prevent intruding another threads local view, and a lost-update in the global scope, too.

Recall that in an open “LCF-style” system like Isabelle/Isar, the user participates in constructing the overall environment. This means that state-based facilities offered by one component will require special caution later on. So minimizing critical elements, by staying within the plain value-oriented view relative to theory or proof contexts most of the time, will also reduce the chance of mishaps occurring to end-users.

ML Reference

```
NAMED_CRITICAL: string -> (unit -> 'a) -> 'a
CRITICAL: (unit -> 'a) -> 'a
setmp: 'a ref -> 'a -> ('b -> 'c) -> 'b -> 'c
```

`NAMED_CRITICAL name f` evaluates *f* () while staying within the critical section of Isabelle/Isar. No other thread may do so at the same time, but non-critical parallel execution will continue. The *name* argument serves for diagnostic purposes and might help to spot sources of congestion.

`CRITICAL` is the same as `NAMED_CRITICAL` with empty name argument.

`setmp ref value f x` evaluates *f x* while staying within the critical section and having *ref* := *value* assigned temporarily. This recovers a value-passing semantics involving global references, regardless of exceptions or concurrency.

Basic library functions

Beyond the proposal of the SML/NJ basis library, Isabelle comes with its own library, from which selected parts are given here. These should encourage a study of the Isabelle sources, in particular files *Pure/library.ML* and *Pure/General/*.ML*.

B.1 Linear transformations

ML

Reference

```
op |> : 'a * ('a -> 'b) -> 'b
```

Many problems in functional programming can be thought of as linear transformations, i.e. a calculation starts with a particular value $x : \text{foo}$ which is then transformed by application of a function $f : \text{foo} \rightarrow \text{foo}$, continued by an application of a function $g : \text{foo} \rightarrow \text{bar}$, and so on. As a canonical example, take functions enriching a theory by constant declaration and primitive definitions:

```
Sign.declare_const: Properties.T -> (binding * typ) * mixfix
-> theory -> term * theory
Thm.add_def: bool -> bool -> binding * term -> theory -> thm * theory
```

Written with naive application, an addition of constant *bar* with type $\text{foo} \Rightarrow \text{foo}$ and a corresponding definition $\text{bar} \equiv \lambda x. x$ would look like:

```
(fn (t, thy) => Thm.add_def false false
  (Binding.name "bar_def", Logic.mk_equals (t, @{term "%x. x"})) thy)
  (Sign.declare_const []
    ((Binding.name "bar", @{typ "foo => foo"}), NoSyn) thy)
```

With increasing numbers of applications, this code gets quite unreadable. Further, it is unintuitive that things are written down in the opposite order as they actually “happen”.

At this stage, Isabelle offers some combinators which allow for more convenient notation, most notably reverse application:

```
thy
|> Sign.declare_const [] ((Binding.name "bar", @{typ "foo => foo"}), NoSyn)
|> (fn (t, thy) => thy
|> Thm.add_def false false
      (Binding.name "bar_def", Logic.mk_equals (t, @{term "%x. x"})))
```

ML Reference

```
op |-> : ('c * 'a) * ('c -> 'a -> 'b) -> 'b
op |>> : ('a * 'c) * ('a -> 'b) -> 'b * 'c
op ||> : ('c * 'a) * ('a -> 'b) -> 'c * 'b
op ||>> : ('c * 'a) * ('a -> 'd * 'b) -> ('c * 'd) * 'b
```

Usually, functions involving theory updates also return side results; to use these conveniently, yet another set of combinators is at hand, most notably `op |->` which allows curried access to side results:

```
thy
|> Sign.declare_const [] ((Binding.name "bar", @{typ "foo => foo"}), NoSyn)
|-> (fn t => Thm.add_def false false
      (Binding.name "bar_def", Logic.mk_equals (t, @{term "%x. x"})))
```

`op |>>` allows for processing side results on their own:

```
thy
|> Sign.declare_const [] ((Binding.name "bar", @{typ "foo => foo"}), NoSyn)
|>> (fn t => Logic.mk_equals (t, @{term "%x. x"}))
|-> (fn def => Thm.add_def false false (Binding.name "bar_def", def))
```

Orthogonally, `op ||>` applies a transformation in the presence of side results which are left unchanged:

```
thy
|> Sign.declare_const [] ((Binding.name "bar", @{typ "foo => foo"}), NoSyn)
||> Sign.add_path "foobar"
|-> (fn t => Thm.add_def false false
      (Binding.name "bar_def", Logic.mk_equals (t, @{term "%x. x"})))
||> Sign.restore_naming thy
```

`op ||>>` accumulates side results:

```
thy
|> Sign.declare_const [] ((Binding.name "bar", @{typ "foo => foo"}), NoSyn)
||>> Sign.declare_const [] ((Binding.name "foobar", @{typ "foo => foo"}), NoSyn)
|-> (fn (t1, t2) => Thm.add_def false false
      (Binding.name "bar_def", Logic.mk_equals (t1, t2)))
```

ML Reference

```
fold: ('a -> 'b -> 'b) -> 'a list -> 'b -> 'b
fold_map: ('a -> 'b -> 'c * 'b) -> 'a list -> 'b -> 'c list * 'b
```

This principles naturally lift to *lists* using the `fold` and `fold_map` combinators. The first lifts a single function

$$f : 'a \rightarrow 'b \rightarrow 'b \text{ to } 'a \text{ list} \rightarrow 'b \rightarrow 'b$$

such that

$$\begin{aligned} y \mid > \text{fold } f \ [x_1, x_2, \dots, x_n] \\ \sim y \mid > f \ x_1 \mid > f \ x_2 \mid > \dots \mid > f \ x_n \end{aligned}$$

The second accumulates side results in a list by lifting a single function

$$f : 'a \rightarrow 'b \rightarrow 'c * 'b \text{ to } 'a \text{ list} \rightarrow 'b \rightarrow 'c \text{ list} * 'b$$

such that

$$\begin{aligned} y \mid > \text{fold_map } f \ [x_1, x_2, \dots, x_n] \\ \sim y \mid > f \ x_1 \mid >> f \ x_2 \mid >> \dots \mid >> f \ x_n \\ \mid > (fn \ (z_1, z_2), \dots, z_n) \Rightarrow [z_1, z_2, \dots, z_n] \end{aligned}$$

Example:

```
let
  val consts = ["foo", "bar"];
in
  thy
    |> fold_map (fn const => Sign.declare_const []
      ((Binding.name const, @{typ "foo => foo"}), NoSyn)) consts
    |>> map (fn t => Logic.mk_equals (t, @{term "%x. x"}))
    |> (fn defs => fold_map (fn def =>
      Thm.add_def false false (Binding.empty, def)) defs)
end
```

ML Reference

```
op #> : ('a -> 'b) * ('b -> 'c) -> 'a -> 'c
op #-> : ('a -> 'c * 'b) * ('c -> 'b -> 'd) -> 'a -> 'd
op #>> : ('a -> 'c * 'b) * ('c -> 'd) -> 'a -> 'd * 'b
op ##> : ('a -> 'c * 'b) * ('b -> 'd) -> 'a -> 'c * 'd
op ##>> : ('a -> 'c * 'b) * ('b -> 'e * 'd) -> 'a -> ('c * 'e) * 'd
```

All those linear combinators also exist in higher-order variants which do not expect a value on the left hand side but a function.

ML Reference

```
op ' : ('b -> 'a) -> 'b -> 'a * 'b
tap : ('b -> 'a) -> 'b -> 'b
```

These operators allow to “query” a context in a series of context transformations:

```
thy
|> tap (fn _ => writeln "now adding constant")
|> Sign.declare_const [] ((Binding.name "bar", @{typ "foo => foo"}), NoSyn)
||>> '(fn thy => Sign.declared_const thy
      (Sign.full_name thy (Binding.name "foobar")))
|-> (fn (t, b) => if b then I
     else Sign.declare_const []
       ((Binding.name "foobar", @{typ "foo => foo"}), NoSyn) #> snd)
```

B.2 Options and partiality

ML

Reference

```
is_some: 'a option -> bool
is_none: 'a option -> bool
the: 'a option -> 'a
these: 'a list option -> 'a list
the_list: 'a option -> 'a list
the_default: 'a -> 'a option -> 'a
try: ('a -> 'b) -> 'a -> 'b option
can: ('a -> 'b) -> 'a -> bool
```

Standard selector functions on *options* are provided. The **try** and **can** functions provide a convenient interface for handling exceptions – both take as arguments a function **f** together with a parameter **x** and handle any exception during the evaluation of the application of **f** to **x**, either return a lifted result (**NONE** on failure) or a boolean value (**false** on failure).

B.3 Common data structures

B.3.1 Lists (as set-like data structures)

```
member: ('b * 'a -> bool) -> 'a list -> 'b -> bool
insert: ('a * 'a -> bool) -> 'a -> 'a list -> 'a list
remove: ('b * 'a -> bool) -> 'b -> 'a list -> 'a list
merge: ('a * 'a -> bool) -> 'a list * 'a list -> 'a list
```

Lists are often used as set-like data structures – set-like in the sense that they support a notion of **member**-ship, **insert**-ing and **remove**-ing, but are order-sensitive. This is convenient when implementing a history-like mechanism: **insert** adds an element *to the front* of a list, if not yet present; **remove** removes *all* occurrences of a particular element. Correspondingly **merge** implements a merge on two lists suitable for merges of context data (§1.1.1).

Functions are parametrized by an explicit equality function to accomplish overloaded equality; in most cases of monomorphic equality, writing `op =` should suffice.

B.3.2 Association lists

```
exception AList.DUP
AList.lookup: ('a * 'b -> bool) -> ('b * 'c) list -> 'a -> 'c option
AList.defined: ('a * 'b -> bool) -> ('b * 'c) list -> 'a -> bool
AList.update: ('a * 'a -> bool) -> ('a * 'b) -> ('a * 'b) list -> ('a * 'b) list
AList.default: ('a * 'a -> bool) -> ('a * 'b) -> ('a * 'b) list -> ('a * 'b) list
AList.delete: ('a * 'b -> bool) -> 'a -> ('b * 'c) list -> ('b * 'c) list
AList.map_entry: ('a * 'b -> bool) -> 'a
  -> ('c -> 'c) -> ('b * 'c) list -> ('b * 'c) list
AList.map_default: ('a * 'a -> bool) -> 'a * 'b -> ('b -> 'b)
  -> ('a * 'b) list -> ('a * 'b) list
AList.join: ('a * 'a -> bool) -> ('a -> 'b * 'b -> 'b) (*exception DUP*)
  -> ('a * 'b) list * ('a * 'b) list -> ('a * 'b) list (*exception AList.DUP*)
AList.merge: ('a * 'a -> bool) -> ('b * 'b -> bool)
  -> ('a * 'b) list * ('a * 'b) list -> ('a * 'b) list (*exception AList.DUP*)
```

Association lists can be seen as an extension of set-like lists: on the one hand, they may be used to implement finite mappings, on the other hand, they remain order-sensitive and allow for multiple key-value-pair with the same key: `AList.lookup` returns the *first* value corresponding to a particular key, if present. `AList.update` updates the *first* occurrence of a particular key; if no such key exists yet, the key-value-pair is added *to the front*. `AList.delete` only deletes the *first* occurrence of a key. `AList.merge` provides an operation suitable for merges of context data (§1.1.1), where an equality parameter on values determines whether a merge should be considered a conflict. A slightly generalized operation is implemented by the `AList.join` function which allows for explicit conflict resolution.

B.3.3 Tables

```

type 'a Symtab.table
exception Symtab.DUP of string
exception Symtab.SAME
exception Symtab.UNDEF of string
Symtab.empty: 'a Symtab.table
Symtab.lookup: 'a Symtab.table -> string -> 'a option
Symtab.defined: 'a Symtab.table -> string -> bool
Symtab.update: (string * 'a) -> 'a Symtab.table -> 'a Symtab.table
Symtab.default: string * 'a -> 'a Symtab.table -> 'a Symtab.table
Symtab.delete: string
    -> 'a Symtab.table -> 'a Symtab.table (*exception Symtab.UNDEF*)
Symtab.map_entry: string -> ('a -> 'a)
    -> 'a Symtab.table -> 'a Symtab.table
Symtab.map_default: (string * 'a) -> ('a -> 'a)
    -> 'a Symtab.table -> 'a Symtab.table
Symtab.join: (string -> 'a * 'a -> 'a) (*exception Symtab.DUP/Symtab.SAME*)
    -> 'a Symtab.table * 'a Symtab.table
    -> 'a Symtab.table (*exception Symtab.DUP*)
Symtab.merge: ('a * 'a -> bool)
    -> 'a Symtab.table * 'a Symtab.table
    -> 'a Symtab.table (*exception Symtab.DUP*)

```

Tables are an efficient representation of finite mappings without any notion of order; due to their efficiency they should be used whenever such pure finite mappings are necessary.

The key type of tables must be given explicitly by instantiating the `TableFun` functor which takes the key type together with its `order`; for convenience, we restrict here to the `Symtab` instance with `string` as key type.

Most table functions correspond to those of association lists.

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Index

- 'a Symtab.table (ML type), **65**
- AList.default (ML), **64**
- AList.defined (ML), **64**
- AList.delete (ML), **64**
- AList.DUP (ML exception), **64**
- AList.join (ML), **64**
- AList.lookup (ML), **64**
- AList.map_default (ML), **64**
- AList.map_entry (ML), **64**
- AList.merge (ML), **64**
- AList.update (ML), **64**
- all_lift (inference), **27**
- all_tac (ML), **32**
- arity (ML type), **16**
- assume_tac (ML), **33**
- assumption (inference), **28**
- Assumption.add_assms (ML), **39**
- Assumption.add_assumes (ML), **39**
- Assumption.assume (ML), **39**
- Assumption.export (ML type), **39**
- Assumption.export (ML), **39**
- betapply (ML), **19**
- can (ML), **63**
- class (ML type), **16**
- composition (inference), **27**
- Conjunction.elim (ML), **25**
- Conjunction.intr (ML), **25**
- Context.>> (ML), **51**
- Context.generic (ML type), **5**
- Context.proof_of (ML), **5**
- Context.theory_of (ML), **5**
- CRITICAL (ML), **59**
- CSUBGOAL (ML), **32**
- cterm (ML type), **22**
- ctyp (ML type), **22**
- dest_resolution (inference), **28**
- dmatch_tac (ML), **33**
- dres_inst_tac (ML), **35**
- dresolve_tac (ML), **33**
- Drule.dest_term (ML), **25**
- Drule.mk_term (ML), **25**
- elim_resolution (inference), **28**
- ematch_tac (ML), **33**
- eq_assume_tac (ML), **33**
- eres_inst_tac (ML), **35**
- eresolve_tac (ML), **33**
- fastype_of (ML), **19**
- fold (ML), **61**
- fold_atoms (ML), **19**
- fold_atyps (ML), **16**
- fold_map (ML), **61**
- fold_types (ML), **19**
- forw_inst_tac (ML), **35**
- forward_tac (ML), **33**
- GenericDataFun (ML functor), **7**
- Goal.conclude (ML), **30**
- Goal.finish (ML), **30**
- Goal.init (ML), **30**
- Goal.protect (ML), **30**
- Goal.prove (ML), **41**
- Goal.prove_multi (ML), **41**
- imp_lift (inference), **27**
- indexname (ML type), **10**
- insert (ML), **63**

- is_none (ML), **63**
- is_some (ML), **63**
- Isar.context (ML), **51**
- Isar.exn (ML), **51**
- Isar.goal (ML), **51**
- Isar.loop (ML), **51**
- Isar.main (ML), **51**
- Isar.state (ML), **51**
- lambda (ML), **19**
- local_theory (ML type), **45**
- LocalTheory.define (ML), **45**
- LocalTheory.note (ML), **45**
- Logic.dest_type (ML), **25**
- Logic.mk_type (ML), **25**
- Long_Name.append (ML), **12**
- Long_Name.base_name (ML), **12**
- Long_Name.explode (ML), **12**
- Long_Name.implode (ML), **12**
- Long_Name.qualifier (ML), **12**
- map_aterms (ML), **19**
- map_atyps (ML), **16**
- map_types (ML), **19**
- match_tac (ML), **33**
- member (ML), **63**
- merge (ML), **63**
- Name.context (ML type), **9**
- Name.context (ML), **9**
- Name.declare (ML), **9**
- Name.internal (ML), **9**
- Name.invents (ML), **9**
- Name.skolem (ML), **9**
- Name.variants (ML), **9**
- NAMED_CRITICAL (ML), **59**
- Namespace.add_path (ML), **12**
- Namespace.declare (ML), **12**
- Namespace.default_naming (ML), **12**
- Namespace.empty (ML), **12**
- Namespace.extern (ML), **12**
- Namespace.full_name (ML), **12**
- Namespace.intern (ML), **12**
- Namespace.merge (ML), **12**
- Namespace.naming (ML type), **12**
- Namespace.T (ML type), **12**
- no_tac (ML), **32**
- Obtain.result (ML), **41**
- op |> (ML), **60**
- op |>> (ML), **61**
- op ||> (ML), **61**
- op ||>> (ML), **61**
- op |-> (ML), **61**
- op #> (ML), **62**
- op #>> (ML), **62**
- op #-> (ML), **62**
- op ##> (ML), **62**
- op ##>> (ML), **62**
- op ‘ (ML), **62**
- op aconv (ML), **19**
- op OF (ML), **28**
- op RS (ML), **28**
- PRIMITIVE (ML), **32**
- print_tac (ML), **32**
- Proof.context (ML type), **5**
- ProofContext.init (ML), **5**
- ProofContext.theory_of (ML), **5**
- ProofContext.transfer (ML), **5**
- ProofDataFun (ML functor), **7**
- proofs (ML), **22**
- remove (ML), **63**
- rename_tac (ML), **35**
- res_inst_tac (ML), **35**
- resolution (inference), **27**
- resolve_tac (ML), **33**
- setmp (ML), **59**
- Sign.add_abbrev (ML), **19**
- Sign.add_tyabbrs_i (ML), **16**
- Sign.add_types (ML), **16**
- Sign.const_instance (ML), **19**

- Sign.const_typargs (ML), **19**
- Sign.declare_const (ML), **19**
- Sign.of_sort (ML), **16**
- Sign.primitive_arity (ML), **16**
- Sign.primitive_class (ML), **16**
- Sign.primitive_classrel (ML), **16**
- Sign.subsort (ML), **16**
- Simplifier.norm_hhf (ML), **27**
- sort (ML type), **16**
- SUBGOAL (ML), **32**
- SUBPROOF (ML), **40**
- Symbol.decode (ML), **8**
- Symbol.explode (ML), **8**
- Symbol.is_blank (ML), **8**
- Symbol.is_digit (ML), **8**
- Symbol.is_letter (ML), **8**
- Symbol.is_quasi (ML), **8**
- Symbol.sym (ML type), **8**
- Symbol.symbol (ML type), **8**
- Symtab.default (ML), **65**
- Symtab.defined (ML), **65**
- Symtab.delete (ML), **65**
- Symtab.DUP (ML exception), **65**
- Symtab.empty (ML), **65**
- Symtab.join (ML), **65**
- Symtab.lookup (ML), **65**
- Symtab.map_default (ML), **65**
- Symtab.map_entry (ML), **65**
- Symtab.merge (ML), **65**
- Symtab.SAME (ML exception), **65**
- Symtab.UNDEF (ML exception), **65**
- Symtab.update (ML), **65**
- tactic (ML type), **32**
- tap (ML), **62**
- term (ML type), **19**
- the (ML), **63**
- the_context (ML), **51**
- the_default (ML), **63**
- the_list (ML), **63**
- theory (ML type), **3**
- theory (ML), **53**
- Theory.add_axioms_i (ML), **23**
- Theory.add_defs_i (ML), **23**
- Theory.add_deps (ML), **23**
- Theory.check_thy (ML), **3**
- Theory.checkpoint (ML), **3**
- Theory.copy (ML), **3**
- Theory.deref (ML), **3**
- Theory.merge (ML), **3**
- Theory.subthy (ML), **3**
- theory_ref (ML type), **3**
- TheoryDataFun (ML functor), **7**
- TheoryTarget.init (ML), **45**
- these (ML), **63**
- thm (ML type), **22**
- Thm.add_oracle (ML), **22**
- Thm.assume (ML), **22**
- Thm.axiom (ML), **22**
- Thm.ctrm_of (ML), **22**
- Thm.ctyp_of (ML), **22**
- Thm.forall_elim (ML), **22**
- Thm.forall_intr (ML), **22**
- Thm.generalize (ML), **22**
- Thm.implies_elim (ML), **22**
- Thm.implies_intr (ML), **22**
- Thm.instantiate (ML), **22**
- ThyInfo.add_hook (ML), **53**
- ThyInfo.begin_theory (ML), **53**
- ThyInfo.end_theory (ML), **53**
- ThyInfo.register_theory (ML), **53**
- ThyInfo.remove_thy (ML), **53**
- ThyInfo.touch_thy (ML), **53**
- Toplevel.debug (ML), **48**
- Toplevel.end_proof (ML), **49**
- Toplevel.is_toplevel (ML), **48**
- Toplevel.keep (ML), **49**
- Toplevel.no_timing (ML), **49**
- Toplevel.print (ML), **49**
- Toplevel.profiling (ML), **48**
- Toplevel.proof (ML), **49**
- Toplevel.proof_of (ML), **48**

Toplevel.proofs (ML), **49**
Toplevel.state (ML type), **48**
Toplevel.theory (ML), **49**
Toplevel.theory_of (ML), **48**
Toplevel.theory_to_proof (ML), **49**
Toplevel.timing (ML), **48**
Toplevel.UNDEF (ML), **48**
try (ML), **63**
typ (ML type), **16**

use_thy (ML), **53**
use_thys (ML), **53**

Variable.add_fixes (ML), **37**
Variable.declare_constraints (ML),
 37
Variable.declare_term (ML), **37**
Variable.export (ML), **37**
Variable.focus (ML), **37**
Variable.import_thms (ML), **37**
Variable.polymorphic (ML), **37**
Variable.variant_fixes (ML), **37**