

The Octave Queueing Toolbox

User's Guide, Edition 1 for release 1.2.2
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Moreno Marzolla

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This is the first edition of the Queueing Toolbox documentation, and is consistent with version 1.2.2 of the package.

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1 Summary

1.1 About the Queueing Toolbox

This document describes the `queueing` toolbox for GNU Octave (`queueing` in short). The `queueing` toolbox, previously known as `qnetworks`, is a collection of functions written in GNU Octave for analyzing queueing networks and Markov chains. Specifically, `queueing` contains functions for analyzing Jackson networks, open, closed or mixed product-form BCMP networks, and computation of performance bounds. The following algorithms have been implemented

- Convolution for closed, single-class product-form networks with load-dependent service centers;
- Exact and approximate Mean Value Analysis (MVA) for single and multiple class product-form closed networks;
- MVA for mixed, multiple class product-form networks with load-independent service centers;
- Approximate MVA for closed, single-class networks with blocking (MVABLO algorithm by F. Akyildiz);
- Asymptotic Bounds, Balanced System Bounds and Geometric Bounds;

`queueing` provides functions for analyzing the following kind of single-station queueing systems:

- $M/M/1$
- $M/M/m$
- $M/M/\infty$
- $M/M/1/k$ single-server, finite capacity system
- $M/M/m/k$ multiple-server, finite capacity system
- Asymmetric $M/M/m$
- $M/G/1$ (general service time distribution)
- $M/H_m/1$ (Hyperexponential service time distribution)

Functions for Markov chain analysis are also provided:

- Birth-death process;
- Transient and steady-state occupancy probabilities;
- Mean times to absorption;
- Expected sojourn times and time-averaged sojourn times;
- Mean first passage times;

The `queueing` toolbox is distributed under the terms of the GNU General Public License (GPL), version 3 or later (see [Appendix A \[Copying\], page 77](#)). You are encouraged to share this software with others, and make this package more useful by contributing additional functions and reporting problems. See [Section 1.2 \[Contributing Guidelines\], page 2](#).

If you use the `queueing` toolbox in a technical paper, please cite it as:

Moreno Marzolla, *The qnetworks Toolbox: A Software Package for Queueing Networks Analysis*. Khalid Al-Begain, Dieter Fiems and William J. Knottenbelt, Editors, Proceedings 17th International Conference on Analytical and Stochastic Modeling Techniques and Applications (ASMTA 2010) Cardiff, UK, June 14–16, 2010, volume 6148 of Lecture Notes in Computer Science, Springer, pp. 102–116, ISBN 978-3-642-13567-5

If you use BibTeX, this is the citation block:

```
@inproceedings{queueing,
  author      = {Moreno Marzolla},
  title       = {The qnetworks Toolbox: A Software Package for Queueing
                 Networks Analysis},
  booktitle   = {Analytical and Stochastic Modeling Techniques and
                 Applications, 17th International Conference,
                 ASMTA 2010, Cardiff, UK, June 14–16, 2010. Proceedings},
  editor      = {Khalid Al-Begain and Dieter Fiems and William J. Knottenbelt},
  year        = {2010},
  publisher   = {Springer},
  series      = {Lecture Notes in Computer Science},
  volume      = {6148},
  pages       = {102--116},
  ee          = {http://dx.doi.org/10.1007/978-3-642-13568-2_8},
  isbn       = {978-3-642-13567-5}
}
```

An early draft of the paper above is available as Technical Report [UBLCS-2010-04](#), February 2010, Department of Computer Science, University of Bologna, Italy.

1.2 Contributing Guidelines

Contributions and bug reports are *always* welcome. If you want to contribute to the `queueing` package, here are some guidelines:

- If you are contributing a new function, please embed proper documentation within the function itself. The documentation must be in `texinfo` format, so that it can be extracted and formatted into the printable manual. See the existing functions of the `queueing` package for the documentation style.
- Make sure that each new function properly checks the validity of its input parameters. For example, each function accepting vectors should check whether the dimensions match.
- Provide bibliographic references for each new algorithm you contribute. If your implementation differs in some way from the reference you give, please describe how and why your implementation differs. Add references to the `doc/references.txi` file.
- Include test and demo blocks with your code. Test blocks are particularly important, since most algorithms tend to be quite tricky to implement correctly. If appropriate, test blocks should also verify that the function fails on incorrect input parameters.

Send your contribution to Moreno Marzolla (moreno.marzolla@unibo.it). If you are just a user of this package and find it useful, let me know by dropping me a line. Thanks.

1.3 Acknowledgements

The following people (listed in alphabetical order) contributed to the `queueing` package, either by providing feedback, reporting bugs or contributing code: Philip Carinhas, Phil Colbourn, Diego Didona, Yves Durand, Marco Guazzone, Michele Mazzucco, Dmitry Kolesnikov.

2 Installation and Getting Started

2.1 Installation through Octave package management system

The most recent version of `queueing` is 1.2.2 and can be downloaded from Octave-Forge

<http://octave.sourceforge.net/queueing/>

Additional information can be found at

<http://www.moreno.marzolla.name/software/queueing/>

To install `queueing`, follow these steps:

1. If you have a recent version of GNU Octave and a network connection, you can install `queueing` directly from Octave command prompt using this command:

```
octave:1> pkg install -forge queueing
```

The command above will automaticall download and install the latest version of the `queueing` toolbox from Octave Forge, and install it on your machine.

If you do not have root access, you can do a local install using:

```
octave:1> pkg install -local -forge queueing
```

This will install `queueing` within your home directory, and the package will be available to your user only.

2. Alternatively, you can first download `queueing` from Octave-Forge; then, to install the package in the system-wide location issue this command at the Octave prompt:

```
octave:1> pkg install queueing-1.2.2.tar.gz
```

(you may need to start Octave as root in order to allow the installation to copy the files to the target locations). After this, all functions will be readily available each time Octave starts, without the need to tweak the search path.

If you do not have root access, you can do a local install using:

```
octave:1> pkg install -local queueing-1.2.2.tar.gz
```

Note: Octave version 3.2.3 as shipped with Ubuntu 10.04 LTS seems to ignore `-local` and always tries to install the package on the system directory.

3. Verify that the package is indeed installed using the `pkg list` command at the Octave prompt; after succesfull installation you should see something like that:

```
octave:1>pkg list queueing
Package Name | Version | Installation directory
-----+-----+-----
queueing    | 1.2.2   | /home/moreno/octave/queueing-1.2.2
```

4. Starting from version 1.1.1, `queueing` is no longer automatically loaded on Octave startup. To make the functions available for use, you need to issue the command

```
octave:1>pkg load queueing
```

at the Octave prompt. To automatically load `queueing` each time Octave starts, you can add the command above to the startup script (usually, `~/.octaverc` on Unix systems).

5. To completely remove `queueing` from your system, use the `pkg uninstall` command:

```
octave:1> pkg uninstall queueing
```

2.2 Manual installation

If you want to manually install `queueing` in a custom location, you can download the tarball and unpack it somewhere:

```
tar xvfz queueing-1.2.2.tar.gz
cd queueing-1.2.2/queueing/
```

Copy all `.m` files from the `inst/` directory to some target location. Then, start Octave with the `-p` option to add the target location to the search path, so that Octave will find all `queueing` functions automatically:

```
octave -p /path/to/queueing
```

For example, if all `queueing` m-files are in `/usr/local/queueing`, you can start Octave as follows:

```
octave -p /usr/local/queueing
```

If you want, you can add the following line to `~/.octaverc`:

```
addpath("/path/to/queueing");
```

so that the path `/path/to/queueing` is automatically added to the search path each time Octave is started, and you no longer need to specify the `-p` option on the command line.

2.3 Development sources

The source code of the `queueing` package can be found in the Subversion repository at the URL:

<http://octave.svn.sourceforge.net/viewvc/octave/trunk/octave-forge/main/queueing/>

The source distribution contains additional development files which are not present in the installation tarball. This section briefly describes the content of the source tree. This is only relevant for developers who want to modify the code or documentation; normal users of the `queueing` package don't need

The source distribution contains the following directories:

<code>doc/</code>	Documentation source. Most of the documentation is extracted from the comment blocks of individual function files from the <code>inst/</code> directory.
<code>inst/</code>	This directory contains the <code>m</code> -files which implement the various Queueing Network algorithms provided by <code>queueing</code> . As a notational convention, the names of source files containing functions for Queueing Networks start with the 'qn' prefix; the name of source files containing functions for Continuous-Time Markov Chains (CTMCs) start with the 'ctmc' prefix, and the names of files containing functions for Discrete-Time Markov Chains (DTMCs) start with the 'dtmc' prefix.
<code>test/</code>	This directory contains the test functions used to invoke all tests on all function files.
<code>devel/</code>	This directory contains function files which are either not working properly, or need additional testing before they are moved to the <code>inst/</code> directory.

The `queueing` package ships with a Makefile which can be used to produce the documentation (in PDF and HTML format), and automatically execute all function tests. Specifically, the following targets are defined:

- all** Running ‘`make`’ (or ‘`make all`’) on the top-level directory builds the programs used to extract the documentation from the comments embedded in the `m`-files, and then produce the documentation in PDF and HTML format (`doc/queueing.pdf` and `doc/queueing.html`, respectively).
- check** Running ‘`make check`’ will execute all tests contained in the `m`-files. If you modify the code of any function in the `inst/` directory, you should run the tests to ensure that no errors have been introduced. You are also encouraged to contribute new tests, especially for functions which are not adequately validated.
- clean**
- distclean**
- dist** The ‘`make clean`’, ‘`make distclean`’ and ‘`make dist`’ commands are used to clean up the source directory and prepare the distribution archive in compressed tar format.

2.4 Naming Conventions

Most of the functions in the `queueing` package obey a common naming convention. Function names are made of several parts; the first part is a prefix which indicates the class of problems the function addresses:

- ctmc-** Functions for continuous-time Markov chains
- dtmc-** Functions for discrete-time Markov chains
- qs-** Functions for analyzing queueing systems (individual service centers)
- qn-** Functions for analyzing queueing networks

Functions dealing with Markov chains start with either the `ctmc` or `dtmc` prefix; the prefix is optionally followed by an additional string which hints at what the function does:

- bd** Birth-Death process
- mtta** Mean Time to Absorption
- fpt** First Passage Times
- exps** Expected Sojourn Times
- taexps** Time-Averaged Expected Sojourn Times

For example, function `ctmcbd` returns the infinitesimal generator matrix for a continuous birth-death process, while `dtmcbd` returns the transition probability matrix for a discrete birth-death process. Note that there exist functions `ctmc` and `dtmc` (without any suffix) that compute steady-state and transient state occupancy probabilities for CTMCs and DTMCs, respectively. See [Chapter 3 \[Markov Chains\]](#), page 11.

Functions whose name starts with `qs-` deal with single station queueing systems. The suffix describes the type of system, e.g., `qsmm1` for $M/M/1$, `qnmmm` for $M/M/m$ and so on. See [Chapter 4 \[Single Station Queueing Systems\]](#), page 25.

Finally, functions whose name starts with **qn-** deal with queueing networks. The character that follows indicates whether the function handles open ('o') or closed ('c') networks, and whether there is a single customer class ('s') or multiple classes ('m'). The string **mix** indicates that the function supports mixed networks with both open and closed customer classes.

-os-	Open, single-class network: open network with a single class of customers
-om-	Open, multiclass network: open network with multiple job classes
-cs-	Closed, single-class network
-cm-	Closed, multiclass network
-mix-	Mixed network with open and closed classes of customers

The last part of the function name indicates the algorithm implemented by the function. See [Chapter 5 \[Queueing Networks\]](#), page 33.

-aba	Asymptotic Bounds Analysis
-bsb	Balanced System Bounds
-gb	Geometric Bounds
-pb	PB Bounds
-cb	Composite Bounds (CB)
-mva	Mean Value Analysis (MVA) algorithm
-cmva	Conditional MVA
-mvald	MVA with general load-dependent servers
-mvaap	Approximate MVA
-mvablo	MVABLO approximation for blocking queueing networks
-conv	Convolution algorithm
-convld	Convolution algorithm with general load-dependent servers

The current version (1.2.2) of the **queueing** package still supports the old function names (although they are no longer documented and will disappear in future releases). However, calling one of the deprecated functions results in a warning message being displayed; the message appears only one time per session:

```
octave:1> qnclosedab(10,[1 2 3])
+ warning: qnclosedab is deprecated. Please use qncsaba instead
⇒ ans = 0.16667
```

Therefore, your legacy code should run unmodified with the current version of the **queueing** package. You can turn off all warning messages with the following command:

```
octave:1> warning ("off", "qn:deprecated-function");
```

However, it is recommended to update to the new API and not ignore the warnings above. To help you catch usages of deprecated functions, even with applications which produce a lot of console output, you can transform warnings into errors so that your application will stop immediately:

```
octave:1> warning ("error", "qn:deprecated-function");
```

2.5 Quickstart Guide

You can use all functions by simply invoking their name with the appropriate parameters; the `queueing` package should display an error message in case of missing/wrong parameters. Extensive documentation is provided for each function, and can be displayed with the `help` command. For example:

```
octave:2> help qncsmvablo
```

prints the documentation for the `qncsmvablo` function. Additional information can be found in the `queueing` manual, which is available in PDF format in `doc/queueing.pdf` and in HTML format in `doc/queueing.html`.

Many functions have demo blocks containing code snippets which illustrate how that function can be used. For example, to execute the demos for the `qnclosed` function, use the `demo` command as follows:

```
octave:4> demo qnclosed
```

Here we illustrate some basic usage of the `queueing` package by considering a few examples.

Example 1 Compute the stationary state occupancy probabilities of a continuous-time Markov chain with infinitesimal generator matrix

$$\mathbf{Q} = \begin{pmatrix} -0.8 & 0.6 & 9.2 \\ 0.3 & -0.7 & 0.4 \\ 0.2 & 0.2 & -0.4 \end{pmatrix}$$

```
Q = [ -0.8  0.6  0.2; \
      0.3 -0.7  0.4; \
      0.2  0.2 -0.4 ];
q = ctmc(Q)
⇒ q = 0.23256  0.32558  0.44186
```

Example 2 Compute the transient state occupancy probability after $n = 3$ transitions of a three state discrete time birth-death process, with birth probabilities $\lambda_{01} = 0.3$ and $\lambda_{12} = 0.5$ and death probabilities $\mu_{10} = 0.5$ and $\mu_{21} = 0.7$, assuming that the system is initially in state zero (i.e., the initial state occupancy probabilities are $(1, 0, 0)$).

```
n = 3;
p0 = [1 0 0];
P = dtmcbd( [0.3 0.5], [0.5 0.7] );
p = dtmc(P,n,p0)
⇒ p = 0.55300  0.29700  0.15000
```

Example 3 Compute server utilization, response time, mean number of requests and throughput of a closed queueing network with $N = 4$ requests and three $M/M/1$ -FCFS queues with mean service times $\mathbf{S} = (1.0, 0.8, 1.4)$ and average number of visits $\mathbf{V} = (1.0, 0.8, 0.8)$

```

S = [1.0 0.8 1.4];
V = [1.0 0.8 0.8];
N = 4;
[U R Q X] = qncsmva(N, S, V)
⇒
U = 0.70064    0.44841    0.78471
R = 2.1030     1.2642     3.2433
Q = 1.47346    0.70862    1.81792
X = 0.70064    0.56051    0.56051

```

Example 4 Compute server utilization, response time, mean number of requests and throughput of an open queueing network with three $M/M/1$ -FCFS queues with mean service times $\mathbf{S} = (1.0, 0.8, 1.4)$ and average number of visits $\mathbf{V} = (1.0, 0.8, 0.8)$. The overall arrival rate is $\lambda = 0.8$ req/s

```

S = [1.0 0.8 1.4];
V = [1.0 0.8 0.8];
lambda = 0.8;
[U R Q X] = qnos(lambda, S, V)
⇒
U = 0.80000    0.51200    0.89600
R = 5.0000     1.6393     13.4615
Q = 4.0000     1.0492     8.6154
X = 0.80000    0.64000    0.64000

```

3 Markov Chains

3.1 Discrete-Time Markov Chains

Let $X_0, X_1, \dots, X_n, \dots$ be a sequence of random variables defined over a discrete state space $1, 2, \dots$. The sequence $X_0, X_1, \dots, X_n, \dots$ is a *stochastic process* with discrete time $0, 1, 2, \dots$. A *Markov chain* is a stochastic process $\{X_n, n = 0, 1, 2, \dots\}$ which satisfies the following Markov property:

$$P(X_{n+1} = x_{n+1} \mid X_n = x_n, X_{n-1} = x_{n-1}, \dots, X_0 = x_0) = P(X_{n+1} = x_{n+1} \mid X_n = x_n)$$

which basically means that the probability that the system is in a particular state at time $n + 1$ only depends on the state the system was at time n .

The evolution of a Markov chain with finite state space $\{1, 2, \dots, N\}$ can be fully described by a stochastic matrix $\mathbf{P}(n) = [P_{i,j}(n)]$ such that $P_{i,j}(n) = P(X_{n+1} = j \mid X_n = i)$. If the Markov chain is homogeneous (that is, the transition probability matrix $\mathbf{P}(n)$ is time-independent), we can write $\mathbf{P} = [P_{i,j}]$, where $P_{i,j} = P(X_{n+1} = j \mid X_n = i)$ for all $n = 0, 1, \dots$.

The transition probability matrix \mathbf{P} must satisfy the following two properties: (1) $P_{i,j} \geq 0$ for all i, j , and (2) $\sum_{j=1}^N P_{i,j} = 1$ for all i .

`[r err] = dtmcchkP (P)` [Function File]

Check whether P is a valid transition probability matrix.

If P is valid, r is the size (number of rows or columns) of P . If P is not a transition probability matrix, r is set to zero, and err to an appropriate error string.

3.1.1 State occupancy probabilities

Given a discrete-time Markov chain with state space $\{1, 2, \dots, N\}$, we denote with $\pi(n) = (\pi_1(n), \pi_2(n), \dots, \pi_N(n))$ the *state occupancy probability vector* at step n , $n = 0, 1, \dots$. $\pi_i(n)$ denotes the probability that the system is in state i after n transitions.

Given the transition probability matrix \mathbf{P} and the initial state occupancy probability vector $\pi(0) = (\pi_1(0), \pi_2(0), \dots, \pi_N(0))$, $\pi(n)$ can be computed as:

$$\pi(n) = \pi(0)\mathbf{P}^n$$

Under certain conditions, there exists a *stationary state occupancy probability* $\pi = \lim_{n \rightarrow +\infty} \pi(n)$, which is independent from $\pi(0)$. The stationary vector π is the solution of the following linear system:

$$\begin{cases} \pi\mathbf{P} = \pi \\ \pi\mathbf{1}^T = 1 \end{cases}$$

where $\mathbf{1}$ is the row vector of ones, and $(\cdot)^T$ the transpose operator.

$p = \text{dtmc}(P)$ [Function File]
 $p = \text{dtmc}(P, n, p0)$ [Function File]

Compute stationary or transient state occupancy probabilities for a discrete-time Markov chain.

With a single argument, compute the stationary state occupancy probability vector $p(1), \dots, p(N)$ for a discrete-time Markov chain with state space $\{1, 2, \dots, N\}$ and with $N \times N$ transition probability matrix P . With three arguments, compute the transient state occupancy vector $p(1), \dots, p(N)$ that the system is in state i after n steps, given initial occupancy probabilities $p0(1), \dots, p0(N)$.

INPUTS

P $P(i, j)$ is the transition probability from state i to state j . P must be an irreducible stochastic matrix, which means that the sum of each row must be 1 ($\sum_{j=1}^N P_{i,j} = 1$), and the rank of P must be equal to its dimension.

n Number of transitions after which compute the state occupancy probabilities ($n = 0, 1, \dots$)

$p0$ $p0(i)$ is the probability that at step 0 the system is in state i .

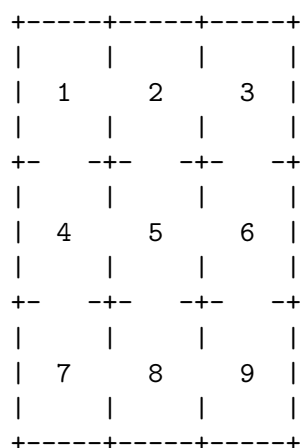
OUTPUTS

p If this function is called with a single argument, $p(i)$ is the steady-state probability that the system is in state i . If this function is called with three arguments, $p(i)$ is the probability that the system is in state i after n transitions, given the initial probabilities $p0(i)$ that the initial state is i .

See also: `ctmc`.

EXAMPLE

This example is from [GrSn97], page 75. Let us consider a maze with nine rooms, as shown in the following figure



A mouse is placed in one of the rooms and can wander around. At each step, the mouse moves from the current room to a neighboring one with equal probability: if it is in room 1, it can move to room 2 and 4 with probability $1/2$, respectively. If the mouse is in room 8, it can move to either 7, 5 or 9 with probability $1/3$.

The transition probability \mathbf{P} from room i to room j is the following:

$$\mathbf{P} = \begin{pmatrix} 0 & 1/2 & 0 & 1/2 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 & 0 & 1/2 & 0 & 0 & 0 \\ 1/3 & 0 & 0 & 0 & 1/3 & 0 & 1/3 & 0 & 0 \\ 0 & 1/4 & 0 & 1/4 & 0 & 1/4 & 0 & 1/4 & 0 \\ 0 & 0 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 1/3 \\ 0 & 0 & 0 & 1/2 & 0 & 0 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 0 & 1/3 & 0 & 1/3 & 0 & 1/3 \\ 0 & 0 & 0 & 0 & 0 & 1/2 & 0 & 1/2 & 0 \end{pmatrix}$$

The stationary state occupancy probability vector can be computed using the following code:

```
P = zeros(9,9);
P(1,[2 4]) = 1/2;
P(2,[1 5 3]) = 1/3;
P(3,[2 6]) = 1/2;
P(4,[1 5 7]) = 1/3;
P(5,[2 4 6 8]) = 1/4;
P(6,[3 5 9]) = 1/3;
P(7,[4 8]) = 1/2;
P(8,[7 5 9]) = 1/3;
P(9,[6 8]) = 1/2;
p = dtmc(P);
disp(p)
⇒ 0.083333    0.125000    0.083333    0.125000
    0.166667    0.125000    0.083333    0.125000
    0.083333
```

3.1.2 Birth-death process

$P = \text{dtmcbd}(b, d)$ [Function File]

Returns the transition probability matrix P for a discrete birth-death process over state space $1, 2, \dots, N$. $b(i)$ is the transition probability from state i to $i + 1$, and $d(i)$ is the transition probability from state $i + 1$ to state i , $i = 1, 2, \dots, N - 1$.

Matrix \mathbf{P} is therefore defined as:

$$\begin{pmatrix} (1 - \lambda_1) & \lambda_1 & & & \\ \mu_1 & (1 - \mu_1 - \lambda_2) & \lambda_2 & & \\ & \mu_2 & (1 - \mu_2 - \lambda_3) & \lambda_3 & \\ & & \ddots & \ddots & \ddots \\ & & & \mu_{N-2} & (1 - \mu_{N-2} - \lambda_{N-1}) & \lambda_{N-1} \\ & & & & \mu_{N-1} & (1 - \mu_{N-1}) \end{pmatrix}$$

where λ_i and μ_i are the birth and death probabilities, respectively.

See also: ctmcbd.

3.1.3 Expected Number of Visits

Given a N state discrete-time Markov chain with transition matrix \mathbf{P} and an integer $n \geq 0$, we let $L_i(n)$ be the the expected number of visits to state i during the first n transitions. The vector $\mathbf{L}(n) = (L_1(n), L_2(n), \dots, L_N(n))$ is defined as

$$\mathbf{L}(n) = \sum_{i=0}^n \pi(i) = \sum_{i=0}^n \pi(0)\mathbf{P}^i$$

where $\pi(i) = \pi(0)\mathbf{P}^i$ is the state occupancy probability after i transitions.

If \mathbf{P} is absorbing, i.e., the stochastic process eventually reaches a state with no outgoing transitions with probability 1, then we can compute the expected number of visits until absorption \mathbf{L} . To do so, we first rearrange the states to rewrite matrix \mathbf{P} as:

$$\mathbf{P} = \begin{pmatrix} \mathbf{Q} & \mathbf{R} \\ \mathbf{0} & \mathbf{I} \end{pmatrix}$$

where the first t states are transient and the last r states are absorbing ($t + r = N$). The matrix $\mathbf{N} = (\mathbf{I} - \mathbf{Q})^{-1}$ is called the *fundamental matrix*; $N_{i,j}$ is the expected number of times that the process is in the j -th transient state if it started in the i -th transient state. If we reshape \mathbf{N} to the size of \mathbf{P} (filling missing entries with zeros), we have that, for absorbing chains $\mathbf{L} = \pi(0)\mathbf{N}$.

$L = \text{dtmcexps}(P, n, p0)$ [Function File]

$L = \text{dtmcexps}(P, p0)$ [Function File]

Compute the expected number of visits to each state during the first n transitions, or until absorption.

INPUTS

P $N \times N$ transition probability matrix.

n Number of steps during which the expected number of visits are computed ($n \geq 0$). If $n=0$, returns $p0$. If $n > 0$, returns the expected number of visits after exactly n transitions.

$p0$ Initial state occupancy probability.

OUTPUTS

L When called with two arguments, $L(i)$ is the expected number of visits to transient state i before absorption. When called with three arguments, $L(i)$ is the expected number of visits to state i during the first n transitions, given initial occupancy probability $p0$.

See also: dtmcexps.

3.1.4 Time-averaged expected sojourn times

`L = dtmctaexps (P, n, p0)` [Function File]

`L = dtmctaexps (P, p0)` [Function File]

Compute the *time-averaged sojourn time* $M(i)$, defined as the fraction of time steps $\{0, 1, \dots, n\}$ (or until absorption) spent in state i , assuming that the state occupancy probabilities at time 0 are $p0$.

INPUTS

P $N \times N$ transition probability matrix.

n Number of transitions during which the time-averaged expected sojourn times are computed ($n \geq 0$). if $n = 0$, returns $p0$.

$p0$ Initial state occupancy probabilities.

OUTPUTS

M If this function is called with three arguments, $M(i)$ is the expected fraction of steps $\{0, 1, \dots, n\}$ spent in state i , assuming that the state occupancy probabilities at time zero are $p0$. If this function is called with two arguments, $M(i)$ is the expected fraction of steps spent in state i until absorption.

See also: `ctmctaexps`.

3.1.5 Mean Time to Absorption

The *mean time to absorption* is defined as the average number of transitions which are required to reach an absorbing state, starting from a transient state (or given an initial state occupancy probability vector $\pi(0)$).

Let t_i be the expected number of transitions before being absorbed in any absorbing state, starting from state i . Vector \mathbf{t} can be computed from the fundamental matrix \mathbf{N} (see [Section 3.1.3 \[Expected number of visits \(DTMC\)\], page 14](#)) as

$$\mathbf{t} = \mathbf{1N}$$

Let $\mathbf{B} = [B_{i,j}]$ be a matrix where $B_{i,j}$ is the probability of being absorbed in state j , starting from transient state i . Again, using matrices \mathbf{N} and \mathbf{R} (see [Section 3.1.3 \[Expected number of visits \(DTMC\)\], page 14](#)) we can write

$$\mathbf{B} = \mathbf{NR}$$

`[t N B] = dtmcmmta (P)` [Function File]

`[t N B] = dtmcmmta (P, p0)` [Function File]

Compute the expected number of steps before absorption for a DTMC with $N \times N$ transition probability matrix P ; compute also the fundamental matrix N for P .

INPUTS

P $N \times N$ transition probability matrix.

OUTPUTS

t	When called with a single argument, t is a vector of size N such that $\mathbf{t}(i)$ is the expected number of steps before being absorbed in any absorbing state, starting from state i ; if i is absorbing, $\mathbf{t}(i) = 0$. When called with two arguments, t is a scalar, and represents the expected number of steps before absorption, starting from the initial state occupancy probability $p0$.
N	When called with a single argument, N is the $N \times N$ fundamental matrix for P . $N(i, j)$ is the expected number of visits to transient state j before absorption, if it is started in transient state i . The initial state is counted if $i = j$. When called with two arguments, N is a vector of size N such that $N(j)$ is the expected number of visits to transient state j before absorption, given initial state occupancy probability $P0$.
B	When called with a single argument, B is a $N \times N$ matrix where $B(i, j)$ is the probability of being absorbed in state j , starting from transient state i ; if j is not absorbing, $B(i, j) = 0$; if i is absorbing, $B(i, i) = 1$ and $B(i, j) = 0$ for all $j \neq i$. When called with two arguments, B is a vector of size N where $B(j)$ is the probability of being absorbed in state j , given initial state occupancy probabilities $p0$.

See also: ctmcmtta.

3.1.6 First Passage Times

The First Passage Time $M_{i,j}$ is the average number of transitions needed to visit state j for the first time, starting from state i . Matrix \mathbf{M} satisfies the property that

$$M_{i,j} = 1 + \sum_{k \neq j} P_{i,k} M_{k,j}$$

To compute $\mathbf{M} = [M_{i,j}]$ a different formulation is used. Let \mathbf{W} be the $N \times N$ matrix having each row equal to the stationary state occupancy probability vector π for \mathbf{P} ; let \mathbf{I} be the $N \times N$ identity matrix. Define \mathbf{Z} as follows:

$$\mathbf{Z} = (\mathbf{I} - \mathbf{P} + \mathbf{W})^{-1}$$

Then, we have that

$$M_{i,j} = \frac{Z_{j,j} - Z_{i,j}}{\pi_j}$$

According to the definition above, $M_{i,i} = 0$. We arbitrarily let $M_{i,i}$ to be the *mean recurrence time* r_i for state i , that is the average number of transitions needed to return to state i starting from it. r_i is:

$$r_i = \frac{1}{\pi_i}$$

`M = dtmcfpt (P)` [Function File]

Compute mean first passage times and mean recurrence times for an irreducible discrete-time Markov chain.

INPUTS

`P` $P(i, j)$ is the transition probability from state i to state j . P must be an irreducible stochastic matrix, which means that the sum of each row must be 1 ($\sum_{j=1}^N P_{ij} = 1$), and the rank of P must be equal to its dimension.

OUTPUTS

`M` For all $i \neq j$, $M(i, j)$ is the average number of transitions before state j is reached for the first time, starting from state i . $M(i, i)$ is the *mean recurrence time* of state i , and represents the average time needed to return to state i .

See also: `ctmcfpt`.

3.2 Continuous-Time Markov Chains

A stochastic process $\{X(t), t \geq 0\}$ is a continuous-time Markov chain if, for all integers n , and for any sequence $t_0, t_1, \dots, t_n, t_{n+1}$ such that $t_0 < t_1 < \dots < t_n < t_{n+1}$, we have

$$P(X(t_{n+1}) = x_{n+1} \mid X(t_n) = x_n, X(t_{n-1}) = x_{n-1}, \dots, X(t_0) = x_0) = P(X(t_{n+1}) = x_{n+1} \mid X(t_n) = x_n)$$

A continuous-time Markov chain is defined according to an *infinitesimal generator matrix* $\mathbf{Q} = [Q_{i,j}]$, where for each $i \neq j$, $Q_{i,j}$ is the transition rate from state i to state j . The matrix \mathbf{Q} must satisfy the property that, for all i , $\sum_{j=1}^N Q_{i,j} = 0$.

`[result err] = ctmchkQ (Q)` [Function File]

If Q is a valid infinitesimal generator matrix, return the size (number of rows or columns) of Q . If Q is not an infinitesimal generator matrix, set *result* to zero, and *err* to an appropriate error string.

3.2.1 State occupancy probabilities

Similarly to the discrete case, we denote with $\pi(t) = (\pi_1(t), \pi_2(t), \dots, \pi_N(t))$ the *state occupancy probability vector* at time t . $\pi_i(t)$ is the probability that the system is in state i at time $t \geq 0$.

Given the infinitesimal generator matrix \mathbf{Q} and the initial state occupancy probabilities $\pi(0) = (\pi_1(0), \pi_2(0), \dots, \pi_N(0))$, the state occupancy probabilities $\pi(t)$ at time t can be computed as:

$$\pi(t) = \pi(0) \exp(\mathbf{Q}t)$$

where $\exp(\mathbf{Q}t)$ is the matrix exponential of $\mathbf{Q}t$. Under certain conditions, there exists a *stationary state occupancy probability* $\pi = \lim_{t \rightarrow +\infty} \pi(t)$, which is independent from $\pi(0)$. π is the solution of the following linear system:

$$\begin{cases} \pi \mathbf{Q} = \mathbf{0} \\ \pi \mathbf{1}^T = 1 \end{cases}$$

$p = \text{ctmc}(Q)$ [Function File]

$p = \text{ctmc}(Q, t, p0)$ [Function File]

Compute stationary or transient state occupancy probabilities for a continuous-time Markov chain.

With a single argument, compute the stationary state occupancy probability vector $p(1), \dots, p(N)$ for a continuous-time Markov chain with state space $\{1, 2, \dots, N\}$ and $N \times N$ infinitesimal generator matrix Q . With three arguments, compute the state occupancy probabilities $p(1), \dots, p(N)$ that the system is in state i at time t , given initial state occupancy probabilities $p0(1), \dots, p0(N)$ at time 0.

INPUTS

Q Infinitesimal generator matrix. Q is a $N \times N$ square matrix where $Q(i, j)$ is the transition rate from state i to state j , for $1 \leq i \neq j \leq N$. #varQ must satisfy the property that $\sum_{j=1}^N Q_{i,j} = 0$

t Time at which to compute the transient probability ($t \geq 0$). If omitted, the function computes the steady state occupancy probability vector.

$p0$ $p0(i)$ is the probability that the system is in state i at time 0.

OUTPUTS

p If this function is invoked with a single argument, $p(i)$ is the steady-state probability that the system is in state i , $i = 1, \dots, N$. If this function is invoked with three arguments, $p(i)$ is the probability that the system is in state i at time t , given the initial occupancy probabilities $p0(1), \dots, p0(N)$.

See also: dtmc.

EXAMPLE

Consider a two-state CTMC such that transition rates between states are equal to 1. This can be solved as follows:

```
Q = [ -1  1; \
      1 -1 ];
q = ctmc(Q)
⇒ q = 0.50000  0.50000
```

3.2.2 Birth-Death Process

$Q = \text{ctmc}(\text{bd}(b, d))$ [Function File]

Returns the infinitesimal generator matrix Q for a continuous birth-death process over state space $1, 2, \dots, N$. $b(i)$ is the transition rate from state i to $i + 1$, and $d(i)$ is the transition rate from state $i + 1$ to state i , $i = 1, 2, \dots, N - 1$.

Matrix Q is therefore defined as:

$$\begin{pmatrix} -\lambda_1 & \lambda_1 & & & \\ \mu_1 & -(\mu_1 + \lambda_2) & \lambda_2 & & \\ & \mu_2 & -(\mu_2 + \lambda_3) & \lambda_3 & \\ & & \ddots & \ddots & \ddots \\ & & & \mu_{N-2} & -(\mu_{N-2} + \lambda_{N-1}) & \lambda_{N-1} \\ & & & & \mu_{N-1} & -\mu_{N-1} \end{pmatrix}$$

where λ_i and μ_i are the birth and death rates, respectively.

See also: dtmcbd.

3.2.3 Expected Sojourn Times

Given a N state continuous-time Markov Chain with infinitesimal generator matrix \mathbf{Q} , we define the vector $\mathbf{L}(t) = (L_1(t), L_2(t), \dots, L_N(t))$ such that $L_i(t)$ is the expected sojourn time in state i during the interval $[0, t]$, assuming that the initial occupancy probability at time 0 was $\pi(0)$. $\mathbf{L}(t)$ can be expressed as the solution of the following differential equation:

$$\frac{d\mathbf{L}(t)}{dt} = \mathbf{L}(t)\mathbf{Q} + \pi(0), \quad \mathbf{L}(0) = \mathbf{0}$$

Alternatively, $\mathbf{L}(t)$ can also be expressed in integral form as:

$$\mathbf{L}(t) = \int_0^t \pi(u) du$$

where $\pi(t) = \pi(0) \exp(\mathbf{Q}t)$ is the state occupancy probability at time t ; $\exp(\mathbf{Q}t)$ is the matrix exponential of $\mathbf{Q}t$.

If there are absorbing states, we can define the vector *expected sojourn times until absorption* $\mathbf{L}(\infty)$, where for each transient state i , $L_i(\infty)$ is the expected total time spent in state i until absorption, assuming that the system started with a given state occupancy probability vector $\pi(0)$. Let τ be the set of transient (i.e., non absorbing) states; let \mathbf{Q}_τ be the restriction of \mathbf{Q} to the transient substates only. Similarly, let $\pi_\tau(0)$ be the restriction of the initial probability vector $\pi(0)$ to transient states τ .

The expected time to absorption $\mathbf{L}_\tau(\infty)$ is defined as the solution of the following equation:

$$\mathbf{L}_\tau(\infty)\mathbf{Q}_\tau = -\pi_\tau(0)$$

$L = \text{ctmcexps}(Q, t, p)$ [Function File]

$L = \text{ctmcexps}(Q, p)$ [Function File]

With three arguments, compute the expected times $L(i)$ spent in each state i during the time interval $[0, t]$, assuming that the initial occupancy vector is p . With two arguments, compute the expected time $L(i)$ spent in each transient state i until absorption.

INPUTS

Q	$N \times N$ infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , $1 \leq i \neq j \leq N$. The matrix Q must also satisfy the condition $\sum_{j=1}^N Q_{ij} = 0$.
t	If given, compute the expected sojourn times in $[0, t]$
p	Initial occupancy probability vector; $p(i)$ is the probability the system is in state i at time 0, $i = 1, \dots, N$

OUTPUTS

L	If this function is called with three arguments, $L(i)$ is the expected time spent in state i during the interval $[0, t]$. If this function is called with two arguments $L(i)$ is the expected time spent in transient state i until absorption; if state i is absorbing, $L(i)$ is zero.
-----	--

See also: dtmcexps.

EXAMPLE

Let us consider a pure-birth, 4-states CTMC such that the transition rate from state i to state $i + 1$ is $\lambda_i = i\lambda$ ($i = 1, 2, 3$), with $\lambda = 0.5$. The following code computes the expected sojourn time in state i , given the initial occupancy probability $\pi_0 = (1, 0, 0, 0)$.

```
lambda = 0.5;
N = 4;
b = lambda*[1:N-1];
d = zeros(size(b));
Q = ctmcabd(b,d);
t = linspace(0,10,100);
p0 = zeros(1,N); p0(1)=1;
L = zeros(length(t),N);
for i=1:length(t)
    L(i,:) = ctmcexps(Q,t(i),p0);
endfor
plot( t, L(:,1), ";State 1;", "linewidth", 2, \
      t, L(:,2), ";State 2;", "linewidth", 2, \
      t, L(:,3), ";State 3;", "linewidth", 2, \
      t, L(:,4), ";State 4;", "linewidth", 2 );
legend("location","northwest");
xlabel("Time");
ylabel("Expected sojourn time");
```

3.2.4 Time-Averaged Expected Sojourn Times

$M = \text{ctmctaexps}(Q, t, p)$ [Function File]
 $M = \text{ctmctaexps}(Q, p)$ [Function File]

Compute the *time-averaged sojourn time* $M(i)$, defined as the fraction of the time interval $[0, t]$ (or until absorption) spent in state i , assuming that the state occupancy probabilities at time 0 are p .

INPUTS

Q	Infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , $1 \leq i \neq j \leq N$. The matrix Q must also satisfy the condition $\sum_{j=1}^N Q_{ij} = 0$
t	Time. If omitted, the results are computed until absorption.
p	$p(i)$ is the probability that, at time 0, the system was in state i , for all $i = 1, \dots, N$

OUTPUTS

M	When called with three arguments, $M(i)$ is the expected fraction of the interval $[0, t]$ spent in state i assuming that the state occupancy probability at time zero is p . When called with two arguments, $M(i)$ is the expected fraction of time until absorption spent in state i ; in this case the mean time to absorption is <code>sum(M)</code> .
-----	---

See also: `dtmctaexps`.

EXAMPLE

```
lambda = 0.5;
N = 4;
birth = lambda*linspace(1,N-1,N-1);
death = zeros(1,N-1);
Q = diag(birth,1)+diag(death,-1);
Q -= diag(sum(Q,2));
t = linspace(1e-5,30,100);
p = zeros(1,N); p(1)=1;
M = zeros(length(t),N);
for i=1:length(t)
    M(i,:) = ctmctaexps(Q,t(i),p);
endfor
clf;
plot(t, M(:,1), ";State 1;", "linewidth", 2, \
      t, M(:,2), ";State 2;", "linewidth", 2, \
      t, M(:,3), ";State 3;", "linewidth", 2, \
      t, M(:,4), ";State 4 (absorbing);", "linewidth", 2 );
legend("location","east");
xlabel("Time");
ylabel("Time-averaged Expected sojourn time");
```

3.2.5 Mean Time to Absorption

$t = \text{ctmcmmtta}(Q, p)$ [Function File]
 Compute the Mean-Time to Absorption (MTTA) of the CTMC described by the infinitesimal generator matrix Q , starting from initial occupancy probabilities p . If there are no absorbing states, this function fails with an error.

INPUTS

Q	$N \times N$ infinitesimal generator matrix. $Q(i, j)$ is the transition rate from state i to state j , $i \neq j$. The matrix Q must satisfy the condition $\sum_{j=1}^N Q_{ij} = 0$
p	$p(i)$ is the probability that the system is in state i at time 0, for each $i = 1, \dots, N$

OUTPUTS

t	Mean time to absorption of the process represented by matrix Q . If there are no absorbing states, this function fails.
-----	---

See also: dtmcmmtta.

EXAMPLE

Let us consider a simple model of a redundant disk array. We assume that the array is made of 5 independent disks, such that the array can tolerate up to 2 disk failures without losing data. If three or more disks break, the array is dead and unrecoverable. We want to estimate the Mean-Time-To-Failure (MTTF) of the disk array.

We model this system as a 4 states Markov chain with state space $\{2, 3, 4, 5\}$. State i denotes the fact that exactly i disks are active; state 2 is absorbing. Let μ be the failure rate of a single disk. The system starts in state 5 (all disks are operational). We use a pure death process, with death rate from state i to state $i - 1$ is μi , for $i = 3, 4, 5$.

The MTTF of the disk array is the MTTA of the Markov Chain, and can be computed with the following expression:

```
mu = 0.01;
death = [ 3 4 5 ] * mu;
birth = 0*death;
Q = ctmcibd(birth,death);
t = dtmcmmtta(Q,[0 0 0 1])
⇒ t = 78.333
```

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998.

3.2.6 First Passage Times

$M = \text{ctmcfpt}(Q)$ [Function File]
 $m = \text{ctmcfpt}(Q, i, j)$ [Function File]

Compute mean first passage times for an irreducible continuous-time Markov chain.

INPUTS

Q	Infinitesimal generator matrix. Q is a $N \times N$ square matrix where $Q(i, j)$ is the transition rate from state i to state j , for $1 \leq i \neq j \leq N$. Transition rates must be nonnegative, and $\sum_{j=1}^N Q_{ij} = 0$
i	Initial state.
j	Destination state.

OUTPUTS

M $M(i, j)$ is the average time before state j is visited for the first time, starting from state i . We set $M(i, i) = 0$.

m m is the average time before state j is visited for the first time, starting from state i .

See also: dtmcfpt.

4 Single Station Queueing Systems

Single Station Queueing Systems contain a single station, and are thus quite easy to analyze. The `queueing` package contains functions for handling the following types of queues:

- $M/M/1$ single-server queueing station;
- $M/M/m$ multiple-server queueing station;
- Asymmetric $M/M/m$;
- $M/M/\infty$ infinite-server station (delay center);
- $M/M/1/K$ single-server, finite-capacity queueing station;
- $M/M/m/K$ multiple-server, finite-capacity queueing station;
- $M/G/1$ single-server with general service time distribution;
- $M/H_m/1$ single-server with hyperexponential service time distribution.

4.1 The $M/M/1$ System

The $M/M/1$ system is made of a single server connected to an unlimited FCFS queue. Requests arrive according to a Poisson process with rate λ ; the service time is exponentially distributed with average service rate μ . The system is stable if $\lambda < \mu$.

`[U, R, Q, X, p0] = qsmm1 (lambda, mu)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/1$ queue.

The steady-state probability π_k that there are k jobs in the system, $k \geq 0$, can be computed as:

$$\pi_k = (1 - \rho)\rho^k$$

where $\rho = \lambda/\mu$ is the server utilization.

INPUTS

`lambda` Arrival rate (`lambda > 0`).

`mu` Service rate (`mu > lambda`).

OUTPUTS

`U` Server utilization

`R` Service center response time

`Q` Average number of requests in the system

`X` Service center throughput. If the system is ergodic, we will always have `X = lambda`

`p0` Steady-state probability that there are no requests in the system.

`lambda` and `mu` can be vectors of the same size. In this case, the results will be vectors as well.

See also: `qsmmm`, `qsmminf`, `qsmmmk`.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.3.

4.2 The $M/M/m$ System

The $M/M/m$ system is similar to the $M/M/1$ system, except that there are $m \geq 1$ identical servers connected to a shared FCFS queue. Thus, at most m requests can be served at the same time. The $M/M/m$ system can be seen as a single server with load-dependent service rate $\mu(n)$, which is a function of the number n of requests in the system:

$$\mu(n) = \min(m, n)\mu$$

where μ is the service rate of each individual server.

`[U, R, Q, X, p0, pm] = qsmmm (lambda, mu)` [Function File]

`[U, R, Q, X, p0, pm] = qsmmm (lambda, mu, m)` [Function File]

Compute utilization, response time, average number of requests in service and throughput for a $M/M/m$ queue, a queueing system with m identical service centers connected to a single FCFS queue.

The steady-state probability π_k that there are k jobs in the system, $k \geq 0$, can be computed as:

$$\pi_k = \begin{cases} \pi_0 \frac{(m\rho)^k}{k!} & 0 \leq k \leq m; \\ \pi_0 \frac{\rho^k m^m}{m!} & k > m. \end{cases}$$

where $\rho = \lambda/(m\mu)$ is the individual server utilization. The steady-state probability π_0 that there are no jobs in the system can be computed as:

$$\pi_0 = \left[\sum_{k=0}^{m-1} \frac{(m\rho)^k}{k!} + \frac{(m\rho)^m}{m!} \frac{1}{1-\rho} \right]^{-1}$$

INPUTS

`lambda` Arrival rate (`lambda>0`).

`mu` Service rate (`mu>lambda`).

`m` Number of servers ($m \geq 1$). If omitted, it is assumed $m=1$.

OUTPUTS

`U` Service center utilization, $U = \lambda/(m\mu)$.

`R` Service center response time

`Q` Average number of requests in the system

`X` Service center throughput. If the system is ergodic, we will always have $X = \text{lambda}$

$p0$	Steady-state probability that there are 0 requests in the system
pm	Steady-state probability that an arriving request has to wait in the queue

$lambda$, mu and m can be vectors of the same size. In this case, the results will be vectors as well.

See also: `qsmm1`, `qsmminf`, `qsmmmk`.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.5.

4.3 The $M/M/\text{inf}$ System

The $M/M/\infty$ system is similar to the $M/M/m$ system, except that there are infinitely many identical servers (that is, $m = \infty$). Each new request is assigned to a new server, so that queueing never occurs. The $M/M/\infty$ system is always stable.

`[U, R, Q, X, p0] = qsmminf (lambda, mu)` [Function File]
 Compute utilization, response time, average number of requests and throughput for a $M/M/\infty$ queue.

The $M/M/\infty$ system has an infinite number of identical servers; this kind of system is always stable for every arrival and service rates.

The steady-state probability π_k that there are k requests in the system, $k \geq 0$, can be computed as:

$$\pi_k = \frac{1}{k!} \left(\frac{\lambda}{\mu} \right)^k e^{-\lambda/\mu}$$

INPUTS

<i>lambda</i>	Arrival rate (<i>lambda</i> >0).
---------------	-----------------------------------

μ	Service rate ($\mu>0$).
-------	---------------------------

OUTPUTS

U Traffic intensity (defined as λ/μ). Note that this is different from the utilization, which in the case of $M/M/\infty$ centers is always zero.

R	Service center response time.
-----	-------------------------------

Q	Average number of requests in the system (which is equal to the traffic intensity λ/μ).
-----	--

X Throughput (which is always equal to $X = \text{lambda}$).

$p0$ Steady-state probability that there are no requests in the system

$lambda$ and mu can be vectors of the same size. In this case, the results will be vectors as well.

See also: qsmm1,qsmmm,qsmmmk.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.4.

4.4 The $M/M/1/K$ System

In a $M/M/1/K$ finite capacity system there can be at most k jobs at any time. If a new request tries to join the system when there are already K other requests, the arriving request is lost. The queue has $K - 1$ slots. The $M/M/1/K$ system is always stable, regardless of the arrival and service rates λ and μ .

`[U, R, Q, X, p0, pK] = qsmm1k (lambda, mu, K)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/1/K$ finite capacity system. In a $M/M/1/K$ queue there is a single server; the maximum number of requests in the system is K , and the maximum queue length is $K - 1$.

The steady-state probability π_k that there are k jobs in the system, $0 \leq k \leq K$, can be computed as:

$$\pi_k = \frac{(1 - a)a^k}{1 - a^{K+1}}$$

where $a = \lambda/\mu$.

INPUTS

lambda Arrival rate (*lambda*>0).

mu Service rate (*mu*>0).

K Maximum number of requests allowed in the system ($K \geq 1$).

OUTPUTS

U Service center utilization, which is defined as $U = 1 - p0$

R Service center response time

Q Average number of requests in the system

X Service center throughput

p0 Steady-state probability that there are no requests in the system

pK Steady-state probability that there are K requests in the system (i.e., that the system is full)

lambda, *mu* and *K* can be vectors of the same size. In this case, the results will be vectors as well.

See also: qsmm1, qsmminf, qsmmm.

4.5 The $M/M/m/K$ System

The $M/M/m/K$ finite capacity system is similar to the $M/M/1/k$ system except that the number of servers is m , where $1 \leq m \leq K$. The queue is made of $K - m$ slots. The $M/M/m/K$ system is always stable.

`[U, R, Q, X, p0, pK] = qsmmmk (lambda, mu, m, K)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/M/m/K$ finite capacity system. In a $M/M/m/K$ system there are $m \geq 1$ identical service centers sharing a fixed-capacity queue. At any time, at most $K \geq m$ requests can be in the system. The maximum queue length is $K - m$. This function generates and solves the underlying CTMC.

The steady-state probability π_k that there are k jobs in the system, $0 \leq k \leq K$ can be expressed as:

$$\pi_k = \begin{cases} \frac{\rho^k}{k!} \pi_0 & \text{if } 0 \leq k \leq m; \\ \frac{\rho^m}{m!} \left(\frac{\rho}{m}\right)^{k-m} \pi_0 & \text{if } m < k \leq K \end{cases}$$

where $\rho = \lambda/\mu$ is the offered load. The probability π_0 that the system is empty can be computed by considering that all probabilities must sum to one: $\sum_{k=0}^K \pi_k = 1$, which gives:

$$\pi_0 = \left[\sum_{k=0}^m \frac{\rho^k}{k!} + \frac{\rho^m}{m!} \sum_{k=m+1}^K \left(\frac{\rho}{m}\right)^{k-m} \right]^{-1}$$

INPUTS

<i>lambda</i>	Arrival rate (<i>lambda</i> >0).
<i>mu</i>	Service rate (<i>mu</i> >0).
<i>m</i>	Number of servers (<i>m</i> ≥ 1).
<i>K</i>	Maximum number of requests allowed in the system, including those inside the service centers (<i>K</i> ≥ <i>m</i>).

OUTPUTS

<i>U</i>	Service center utilization
<i>R</i>	Service center response time
<i>Q</i>	Average number of requests in the system
<i>X</i>	Service center throughput
<i>p0</i>	Steady-state probability that there are no requests in the system.
<i>pK</i>	Steady-state probability that there are <i>K</i> requests in the system (i.e., probability that the system is full).

lambda, *mu*, *m* and *K* can be either scalars, or vectors of the same size. In this case, the results will be vectors as well.

See also: qsmm1, qsmminf, qsmmm.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 6.6.

4.6 The Asymmetric $M/M/m$ System

The Asymmetric $M/M/m$ system contains m servers connected to a single queue. Differently from the $M/M/m$ system, in the asymmetric $M/M/m$ each server may have a different service time.

`[U, R, Q, X] = qsamm (lambda, mu)` [Function File]

Compute *approximate* utilization, response time, average number of requests in service and throughput for an asymmetric $M/M/m$ queue. In this system there are m different service centers connected to a single queue. Each server has its own (possibly different) service rate. If there is more than one server available, requests are routed to a randomly-chosen one.

INPUTS

lambda Arrival rate (*lambda*>0).

mu *mu*(*i*) is the service rate of server *i*, $1 \leq i \leq m$. The system must be ergodic (*lambda* < sum(*mu*)).

OUTPUTS

U Approximate service center utilization, $U = \lambda / (\sum_i \mu_i)$.

R Approximate service center response time

Q Approximate number of requests in the system

X Approximate service center throughput. If the system is ergodic, we will always have *X* = *lambda*

See also: qsmmm.

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998

4.7 The $M/G/1$ System

`[U, R, Q, X, p0] = qsmg1 (lambda, xavg, x2nd)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/G/1$ system. The service time distribution is described by its mean *xavg*, and by its second moment *x2nd*. The computations are based on results from L. Kleinrock, *Queueing Systems*, Wiley, Vol 2, and Pollaczek-Khinchine formula.

INPUTS

lambda Arrival rate.

xavg Average service time

x2nd Second moment of service time distribution

OUTPUTS

U Service center utilization

R Service center response time

Q Average number of requests in the system

X Service center throughput

p0 probability that there is not any request at system

lambda, *xavg*, *t2nd* can be vectors of the same size. In this case, the results will be vectors as well.

See also: *qsmh1*.

4.8 The $M/H_m/1$ System

`[U, R, Q, X, p0] = qsmh1 (lambda, mu, alpha)` [Function File]

Compute utilization, response time, average number of requests and throughput for a $M/H_m/1$ system. In this system, the customer service times have hyper-exponential distribution:

$$B(x) = \sum_{j=1}^m \alpha_j (1 - e^{-\mu_j x}), \quad x > 0$$

where α_j is the probability that the request is served at phase j , in which case the average service rate is μ_j . After completing service at phase j , for some j , the request exits the system.

INPUTS

lambda Arrival rate.

mu *mu(j)* is the phase j service rate. The total number of phases m is `length(mu)`.

alpha *alpha(j)* is the probability that a request is served at phase j . *alpha* must have the same size as *mu*.

OUTPUTS

U Service center utilization

R Service center response time

Q Average number of requests in the system

X Service center throughput

5 Queueing Networks

5.1 Introduction to QNs

Queueing Networks (QN) are a very simple yet powerful modeling tool which can be used to analyze many kind of systems. In its simplest form, a QN is made of K service centers. Each center k has a queue, which is connected to m_k (generally identical) *servers*. Arriving customers (requests) join the queue if there is a slot available. Then, requests are served according to a (de)queueing policy (e.g., FIFO). After service completes, requests leave the server and can join another queue or exit from the system.

Service centers for which $m_k = \infty$ are called *delay centers* or *infinite servers*. In this kind of centers, every request always finds one available server, so queueing never occurs.

Requests join the queue according to a *queueing policy*, such as:

FCFS	First-Come-First-Served
LCFS-PR	Last-Come-First-Served, Preemptive Resume
PS	Processor Sharing
IS	Infinite Server (for which $m_k = \infty$).

Queueing models can be *open* or *closed*. In open models there is an infinite population of requests; new customers are generated outside the system, and eventually leave the system. In closed systems there is a fixed population of request.

Queueing models can have a single request class (*single class models*), meaning that all requests behave in the same way (e.g., they spend the same average time on each particular server). In *multiple class models* there are multiple request classes, each one with its own parameters. Furthermore, in multiclass models there can be open and closed classes of requests within the same system.

A particular class of QN models, *product-form* QNs, is of particular interest. Product-form networks fulfill the following assumptions:

- The network can consist of open and closed job classes.
- The following queueing disciplines are allowed: FCFS, PS, LCFS-PR and IS.
- Service times for FCFS nodes must be exponentially distributed and class-independent. Service centers at PS, LCFS-PR and IS nodes can have any kind of service time distribution with a rational Laplace transform. Furthermore, for PS, LCFS-PR and IS nodes, different classes of customers can have different service times.
- The service rate of an FCFS node is only allowed to depend on the number of jobs at this node; in a PS, LCFS-PR and IS node the service rate for a particular job class can also depend on the number of jobs of that class at the node.
- In open networks two kinds of arrival processes are allowed: i) the arrival process is Poisson, with arrival rate λ which can depend on the number of jobs in the network. ii) the arrival process consists of U independent Poisson arrival streams where the U job sources are assigned to the U chains; the arrival rate can be load dependent.

Product-form networks are attractive because they be efficiently analyzed to compute steady-state performance measures.

5.2 Single Class Models

In single class models, all requests are indistinguishable and belong to the same class. This means that every request has the same average service time, and all requests move through the system with the same routing probabilities.

Model Inputs

λ_k	(Open models only) External arrival rate to service center k .
λ	(Open models only) Overall external arrival rate to the system as a whole: $\lambda = \sum_k \lambda_k$.
N	(Closed models only) Total number of requests in the system.
S_k	Average service time. S_k is the average service time on service center k . In other words, S_k is the average time from the instant in which a request is extracted from the queue and starts being service, and the instant at which service finishes and the request moves to another queue (or exits the system).
$P_{i,j}$	Routing probability matrix. $\mathbf{P} = [P_{i,j}]$ is a $K \times K$ matrix such that $P_{i,j}$ is the probability that a request completing service at server i will move directly to server j . The probability that a request leaves the system after service at service center i is $1 - \sum_{j=1}^K P_{i,j}$.
V_k	Average number of visits. V_k is the average number of visits to the service center k . This quantity will be described shortly.

Model Outputs

U_k	Service center utilization. U_k is the utilization of service center k . The utilization is defined as the fraction of time in which the resource is busy (i.e., the server is processing requests). If center k is a single-server or multiserver node, then $0 \leq U_k \leq 1$. If center k is an infinite server node (delay center), then U_k denotes the <i>traffic intensity</i> and is defined as $U_k = X_k S_k$; in this case the utilization may be greater than one.
R_k	Average response time. R_k is the average response time of service center k . The average response time is defined as the average time between the arrival of a customer in the queue, and the completion of service.
Q_k	Average number of customers. Q_k is the average number of requests in service center k . This includes both the requests in the queue, and the request being served.
X_k	Throughput. X_k is the throughput of service center k . The throughput is defined as the ratio of job completions (i.e., average number of jobs completed over a fixed interval of time).

Given these output parameters, additional performance measures can be computed as follows:

X	System throughput, $X = X_1/V_1$
R	System response time, $R = \sum_{k=1}^K R_k V_k$

Q Average number of requests in the system, $Q = \sum_{k=1} Q_k$; for closed systems, this can be written as $Q = N - XZ$;

For open, single class models, the scalar λ denotes the external arrival rate of requests to the system. The average number of visits satisfy the following equation:

$$V_j = P_{0,j} + \sum_{i=1}^K V_i P_{i,j} \quad j = 1, \dots, K$$

where $P_{0,j}$ is the probability that an external arrival goes to service center j . If λ_j is the external arrival rate to service center j , and $\lambda = \sum_j \lambda_j$ is the overall external arrival rate, then $P_{0,j} = \lambda_j / \lambda$.

For closed models, the visit ratios satisfy the following equation:

$$\begin{cases} V_j = \sum_{i=1}^K V_i P_{i,j} & j = 1, \dots, K \\ V_r = 1 & \text{for a selected reference station } r \end{cases}$$

Note that the set of traffic equations $V_j = \sum_{i=1}^K V_i P_{i,j}$ alone can only be solved up to a multiplicative constant; to get a unique solution we impose an additional constraint $V_r = 1$. This constraint is equivalent to defining station r as the *reference station*; the default is $r = 1$, see [doc-qncsvisits], page 35. A job that returns to the reference station is assumed to have completed its activity cycle. The network throughput is set to the throughput of the reference station.

$V = \text{qncsvisits}(P)$ [Function File]

$V = \text{qncsvisits}(P, r)$ [Function File]

Compute the mean number of visits to the service centers of a single class, closed network with K service centers.

INPUTS

P $P(i,j)$ is the probability that a request which completed service at center i is routed to center j . For closed networks it must hold that $\text{sum}(P,2)=1$. The routing graph must be strongly connected, meaning that each node must be reachable from every other node.

r Index of the reference station, $r \in \{1, \dots, K\}$; Default $r=1$. The traffic equations are solved by imposing the condition $V(r) = 1$. A request returning to the reference station completes its activity cycle.

OUTPUTS

V $V(i)$ is the average number of visits to service center i , assuming center r as the reference station.

$V = \text{qnosvisits}(P, \text{lambda})$ [Function File]

Compute the average number of visits to the service centers of a single class open Queueing Network with K service centers.

INPUTS

P $P(i, j)$ is the probability that a request which completed service at center i is routed to center j .

λ $\lambda(i)$ is the external arrival rate to center i .

OUTPUTS

V $V(i)$ is the average number of visits to server i .

EXAMPLE

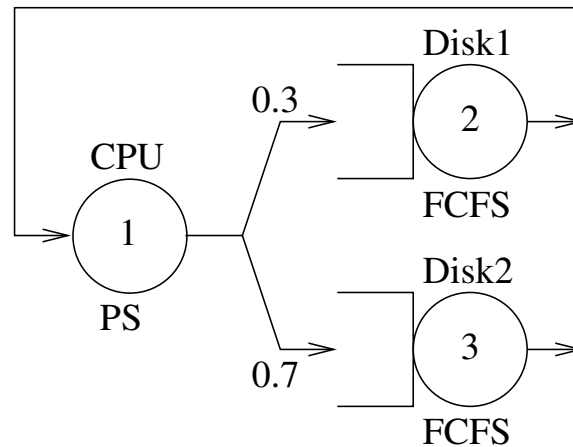


Figure 5.1: Closed network with a single class of requests

Figure 5.1 shows a closed QN with a single class of requests. The network has three service centers, labeled *CPU*, *Disk1*, *Disk2*. and represents the so called *central server* model of a computer system. Requests spend some time at the CPU, which is represented by a PS (Processor Sharing) node. After that, requests are routed to node *Disk1* with probability 0.3, and to node *Disk2* with probability 0.7. Both *Disk1* and *Disk2* are modeled as FCFS nodes.

If we enumerate the servers as CPU=1, Disk1=2, Disk2=3, we can define the routing matrix as follows:

$$P = \begin{pmatrix} 0 & 0.3 & 0.7 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

The visit ratios V using station 1 as the reference station can be computed with:

```
P = [0 0.3 0.7; \
      1 0   0   ; \
      1 0   0   ];
V = qncsvisits(P)
⇒ V = 1.00000    0.30000    0.70000
```

EXAMPLE

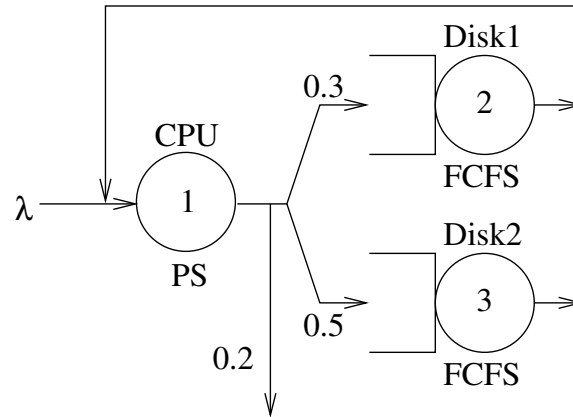


Figure 5.2: Open Queueing Network with a single class of requests

Figure 5.2 shows a open QN with a single class of requests. The network has the same structure as the one in Figure 5.1, with the difference that here we have a stream of jobs arriving from outside the system, at a rate λ . After service completion at the CPU, a job can leave the system with probability 0.2, or be transferred to other nodes with the probabilities shown in the figure.

The routing matrix of this network is

$$P = \begin{pmatrix} 0 & 0.3 & 0.5 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

If we let $\lambda = 1.2$, we can compute the visit ratios V as follows:

```
p = 0.3;
lambda = 1.2
P = [0 0.3 0.5; \
      1 0   0   ; \
      1 0   0   ];
V = qnosvisits(P,[1.2 0 0])
⇒ V = 5.0000  1.5000  2.5000
```

Function `qnosvisits` expects a vector with K elements as a second parameter, for open networks only. The vector contains the arrival rates at each individual node; since in our example external arrivals exist only for node S_1 with rate $\lambda = 1.2$, the second parameter is $[1.2, 0, 0]$.

5.2.1 Open Networks

Jackson networks satisfy the following conditions:

- There is only one job class in the network; the overall number of jobs in the system is unlimited.
- There are N service centers in the network. Each service center may have Poisson arrivals from outside the system. A job can leave the system from any node.

- Arrival rates as well as routing probabilities are independent from the number of nodes in the network.
- External arrivals and service times at the service centers are exponentially distributed, and in general can be load-dependent.
- Service discipline at each node is FCFS

We define the *joint probability vector* $\pi(k_1, k_2, \dots, k_N)$ as the steady-state probability that there are k_i requests at service center i , for all $i = 1, 2, \dots, N$. Jackson networks have the property that the joint probability is the product of the marginal probabilities π_i :

$$\pi(k_1, k_2, \dots, k_N) = \prod_{i=1}^N \pi_i(k_i)$$

where $\pi_i(k_i)$ is the steady-state probability that there are k_i requests at service center i .

`[U, R, Q, X] = qnos (lambda, S, V)` [Function File]
`[U, R, Q, X] = qnos (lambda, S, V, m)` [Function File]

Analyze open, single class BCMP queueing networks.

This function works for a subset of BCMP single-class open networks satisfying the following properties:

- The allowed service disciplines at network nodes are: FCFS, PS, LCFS-PR, IS (infinite server);
- Service times are exponentially distributed and load-independent;
- Service center i can consist of $m(i) \geq 1$ identical servers.
- Routing is load-independent

INPUTS

lambda Overall external arrival rate (*lambda*>0).
S $S(k)$ is the average service time at center i ($S(k)>0$).
V $V(k)$ is the average number of visits to center k ($V(k) \geq 0$).
m $m(k)$ is the number of servers at center i . If $m(k) < 1$, enter k is a delay center (IS); otherwise it is a regular queueing center with $m(k)$ servers. Default is $m(k) = 1$ for all k .

OUTPUTS

U If k is a queueing center, $U(k)$ is the utilization of center k . If k is an IS node, then $U(k)$ is the *traffic intensity* defined as $X(k)*S(k)$.
R $R(k)$ is the average response time of center k .
Q $Q(k)$ is the average number of requests at center k .
X $X(k)$ is the throughput of center k .

See also: qnopen, qnclosed, qnosvisits.

From the results computed by this function, it is possible to derive other quantities of interest as follows:

- **System Response Time:** The overall system response time can be computed as $R_s = \sum_{i=1}^K V_i R_i$
- **Average number of requests:** The average number of requests in the system can be computed as: $Q_s = \sum_{i=1}^K Q(i)$

EXAMPLE

```
lambda = 3;
V = [16 7 8];
S = [0.01 0.02 0.03];
[U R Q X] = qnos( lambda, S, V );
R_s = dot(R,V) # System response time
N = sum(Q) # Average number in system
+ R_s = 1.4062
+ N = 4.2186
```

REFERENCES

G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998.

5.2.2 Closed Networks

<code>[U, R, Q, X, G] = qncsmva (N, S, V)</code>	[Function File]
<code>[U, R, Q, X, G] = qncsmva (N, S, V, m)</code>	[Function File]
<code>[U, R, Q, X, G] = qncsmva (N, S, V, m, Z)</code>	[Function File]

Analyze closed, single class queueing networks using the exact Mean Value Analysis (MVA) algorithm.

The following queueing disciplines are supported: FCFS, LCFS-PR, PS and IS (Infinite Server). This function supports fixed-rate service centers or multiple server nodes. For general load-dependent service centers, use the function `qncsmvald` instead.

Additionally, the normalization constant $G(n)$, $n = 0, \dots, N$ is computed; $G(n)$ can be used in conjunction with the BCMP theorem to compute steady-state probabilities.

INPUTS

N	Population size (number of requests in the system, $N \geq 0$). If $N == 0$, this function returns $U = R = Q = X = 0$
S	$S(k)$ is the mean service time at center k ($S(k) \geq 0$).
V	$V(k)$ is the average number of visits to service center k ($V(k) \geq 0$).
Z	External delay for customers ($Z \geq 0$). Default is 0.
m	$m(k)$ is the number of servers at center k (if m is a scalar, all centers have that number of servers). If $m(k) < 1$, center k is a delay center (IS); otherwise it is a regular queueing center (FCFS, LCFS-PR or PS) with $m(k)$ servers. Default is $m(k) = 1$ for all k (each service center has a single server).

OUTPUTS

U	If k is a FCFS, LCFS-PR or PS node ($m(k) \geq 1$), then $U(k)$ is the utilization of center k , $0 \leq U(k) \leq 1$. If k is an IS node ($m(k) < 1$), then $U(k)$ is the <i>traffic intensity</i> defined as $X(k)*S(k)$. In this case the value of $U(k)$ may be greater than one.
R	$R(k)$ is the response time at center k . The <i>Residence Time</i> at center k is $R(k) * V(k)$. The system response time R_{sys} can be computed either as $R_{sys} = N/X_{sys} - Z$ or as $R_{sys} = \text{dot}(R, V)$
Q	$Q(k)$ is the average number of requests at center k . The number of requests in the system can be computed either as $\text{sum}(Q)$, or using the formula $N - X_{sys} * Z$.
X	$X(k)$ is the throughput of center k . The system throughput X_{sys} can be computed as $X_{sys} = X(1) / V(1)$
G	Normalization constants. $G(n+1)$ corresponds to the value of the normalization constant $G(n)$, $n = 0, \dots, N$ as array indexes in Octave start from 1. $G(n)$ can be used in conjunction with the BCMP theorem to compute steady-state probabilities.

Note on numerical stability: In presence of load-dependent servers (e.g., if $m(i) > 1$ for some i), the MVA algorithm is known to be numerically unstable. Generally this problem manifests itself as negative response times or utilizations. This is not a problem with the `queueing` toolbox, but with the Mean Value Analysis algorithm, and therefore has currently no easy workaround (apart from using a different solution technique, if available). This function prints a warning if it detects numerical problems; you can disable the warning with the command `warning("off", "qn:numerical-instability")`.

See also: `qncsmvald`, `qncsmva`.

REFERENCES

M. Reiser and S. S. Lavenberg, *Mean-Value Analysis of Closed Multichain Queuing Networks*, Journal of the ACM, vol. 27, n. 2, April 1980, pp. 313–322. [10.1145/322186.322195](#)

This implementation is described in R. Jain, *The Art of Computer Systems Performance Analysis*, Wiley, 1991, p. 577. Multi-server nodes are treated according to G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 8.2.1, "Single Class Queueing Networks".

EXAMPLE

```
S = [ 0.125 0.3 0.2 ];
V = [ 16 10 5 ];
N = 20;
m = ones(1,3);
Z = 4;
[U R Q X] = qncsmva(N,S,V,m,Z);
X_s = X(1)/V(1); # System throughput
R_s = dot(R,V); # System response time
```

```

printf("\t      Util      Qlen      RespT      Tput\n");
printf("\t-----  -----  -----  -----\n");
for k=1:length(S)
    printf("Dev%d\t%8.4f  %8.4f  %8.4f  %8.4f\n", k, U(k), Q(k), R(k), X(k) );
endfor
printf("\nSystem\t      %8.4f  %8.4f  %8.4f\n\n", N-X_s*Z, R_s, X_s );

```

`[U, R, Q, X] = qncsmvald (N, S, V)` [Function File]

`[U, R, Q, X] = qncsmvald (N, S, V, Z)` [Function File]

Exact MVA algorithm for closed, single class queueing networks with load-dependent service centers. This function supports FCFS, LCFS-PR, PS and IS nodes. For networks with only fixed-rate service centers and multiple-server nodes, the function `qncsmva` is more efficient.

INPUTS

N Population size (number of requests in the system, $N \geq 0$). If $N == 0$, this function returns $U = R = Q = X = 0$

S $S(k, n)$ is the mean service time at center k where there are n requests, $1 \leq n \leq N$. $S(k, n) = 1/\mu_{k,n}$, where $\mu_{k,n}$ is the service rate of center k when there are n requests.

V $V(k)$ is the average number of visits to service center k ($V(k) \geq 0$).

Z external delay ("think time", $Z \geq 0$); default 0.

OUTPUTS

U $U(k)$ is the utilization of service center k . The utilization is defined as the probability that service center k is not empty, that is, $U_k = 1 - \pi_k(0)$ where $\pi_k(0)$ is the steady-state probability that there are 0 jobs at service center k .

R $R(k)$ is the response time on service center k .

Q $Q(k)$ is the average number of requests in service center k .

X $X(k)$ is the throughput of service center k .

Note: In presence of load-dependent servers, the MVA algorithm is known to be numerically unstable. Generally this problem manifests itself as negative response times produced by this function.

REFERENCES

M. Reiser and S. S. Lavenberg, *Mean-Value Analysis of Closed Multichain Queueing Networks*, Journal of the ACM, vol. 27, n. 2, April 1980, pp. 313–322. [10.1145/322186.322195](#)

This implementation is described in G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, Section 8.2.4.1, "Networks with Load-Dependent Service: Closed Networks".

`[U, R, Q, X] = qncscmva (N, S, Sld, V)` [Function File]

`[U, R, Q, X] = qncscmva (N, S, Sld, V, Z)` [Function File]

This is the implementation of the original Conditional MVA (CMVA) algorithm, a numerically stable variant of MVA, as described in G. Casale, *A Note on Stable Flow-Equivalent Aggregation in Closed Networks*. This function supports a network of $M \geq 1$ service centers and a single delay center. Servers $1, \dots, M-1$ are load-independent; server M is load-dependent.

INPUTS

- N Number of requests in the system, $N \geq 0$. If $N == 0$, this function returns $U = R = Q = X = 0$
- S Vector of mean service times for load-independent (fixed rate) servers. Specifically, $S(k)$ is the mean service time on server $k = 1, \dots, M-1$ ($S(k) > 0$). If there are no fixed-rate servers, then $S = []$
- Sld $Sld(n)$ is the inverse service rate at server M (the load-dependent server) when there are n requests, $n = 1, \dots, N$. $Sld(n) = 1/\mu(n)$.
- V $V(k)$ is the average number of visits to service center $k = 1, \dots, M$, where $V(k) \geq 0$. $V(1:M-1)$ are the visit rates to the fixed rate servers; $V(M)$ is the visit rate to the load dependent server.
- Z External delay for customers ($Z \geq 0$). Default is 0.

OUTPUTS

- U $U(k)$ is the utilization of center k ($k = 1, \dots, M$)
- R $R(k)$ is the response time of center k , ($k = 1, \dots, M$). The system response time R_{sys} can be computed as $R_{sys} = N/X_{sys} - Z$
- Q $Q(k)$ is the average number of requests at center k , ($k = 1, \dots, M$).
- X $X(k)$ is the throughput of center k , ($k = 1, \dots, M$).

REFERENCES

G. Casale. *A note on stable flow-equivalent aggregation in closed networks*. Queueing Syst. Theory Appl., 60:193-202, December 2008, [10.1007/s11134-008-9093-6](https://doi.org/10.1007/s11134-008-9093-6)

`[U, R, Q, X] = qncsmvaap (N, S, V)` [Function File]

`[U, R, Q, X] = qncsmvaap (N, S, V, m)` [Function File]

`[U, R, Q, X] = qncsmvaap (N, S, V, m, Z)` [Function File]

`[U, R, Q, X] = qncsmvaap (N, S, V, m, Z, tol)` [Function File]

`[U, R, Q, X] = qncsmvaap (N, S, V, m, Z, tol, iter_max)` [Function File]

Analyze closed, single class queueing networks using the Approximate Mean Value Analysis (MVA) algorithm. This function is based on approximating the number of customers seen at center k when a new request arrives as $Q_k(N) \times (N-1)/N$. This function only handles single-server and delay centers; if your network contains general load-dependent service centers, use the function `qncsmvald` instead.

INPUTS

- N Population size (number of requests in the system, $N > 0$).

S	$S(k)$ is the mean service time on server k ($S(k) > 0$).
V	$V(k)$ is the average number of visits to service center k ($V(k) \geq 0$).
m	$m(k)$ is the number of servers at center k (if m is a scalar, all centers have that number of servers). If $m(k) < 1$, center k is a delay center (IS); if $m(k) == 1$, center k is a regular queueing center (FCFS, LCFS-PR or PS) with one server (default). This function does not support multiple server nodes ($m(k) > 1$).
Z	External delay for customers ($Z \geq 0$). Default is 0.
tol	Stopping tolerance. The algorithm stops when the maximum relative difference between the new and old value of the queue lengths Q becomes less than the tolerance. Default is 10^{-5} .
$iter_max$	Maximum number of iterations ($iter_max > 0$). The function aborts if convergence is not reached within the maximum number of iterations. Default is 100.

OUTPUTS

U	If k is a FCFS, LCFS-PR or PS node ($m(k) == 1$), then $U(k)$ is the utilization of center k . If k is an IS node ($m(k) < 1$), then $U(k)$ is the <i>traffic intensity</i> defined as $X(k) * S(k)$.
R	$R(k)$ is the response time at center k . The system response time R_{sys} can be computed as $R_{sys} = N / X_{sys} - Z$
Q	$Q(k)$ is the average number of requests at center k . The number of requests in the system can be computed either as $\text{sum}(Q)$, or using the formula $N - X_{sys} * Z$.
X	$X(k)$ is the throughput of center k . The system throughput X_{sys} can be computed as $X_{sys} = X(1) / V(1)$

See also: `qncsmva`, `qncsmvald`.

REFERENCES

This implementation is based on Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 6.4.2.2 ("Approximate Solution Techniques").

According to the BCMP theorem, the state probability of a closed single class queueing network with K nodes and N requests can be expressed as:

$$\pi(k_1, k_2, \dots, k_K) = \frac{1}{G(N)} \prod_{i=1}^N F_i(k_i)$$

Here $\pi(k_1, k_2, \dots, k_K)$ is the joint probability of having k_i requests at node i , for all $i = 1, 2, \dots, K$.

The *convolution algorithms* computes the normalization constants $\mathbf{G} = (G(0), G(1), \dots, G(N))$ for single-class, closed networks with N requests. The normalization constants are returned as vector $\mathbf{G}=[G(1), G(2), \dots, G(N+1)]$ where $G(i+1)$ is the value of $G(i)$ (remember that Octave uses 1-base vectors). The normalization constant can be used to compute all performance measures of interest (utilization, average response time and so on).

`queueing` implements the convolution algorithm, in the function `qncsconv` and `qncsconvld`. The first one supports single-station nodes, multiple-station nodes and IS nodes. The second one supports networks with general load-dependent service centers.

`[U, R, Q, X, G] = qncsconv (N, S, V)` [Function File]

`[U, R, Q, X, G] = qncsconv (N, S, V, m)` [Function File]

Analyze product-form, single class closed networks using the convolution algorithm.

Load-independent service centers, multiple servers ($M/M/m$ queues) and IS nodes are supported. For general load-dependent service centers, use `qncsconvld` instead.

INPUTS

N Number of requests in the system ($N > 0$).

S $S(k)$ is the average service time on center k ($S(k) \geq 0$).

V $V(k)$ is the visit count of service center k ($V(k) \geq 0$).

m $m(k)$ is the number of servers at center k . If $m(k) < 1$, center k is a delay center (IS); if $m(k) \geq 1$, center k it is a regular $M/M/m$ queueing center with $m(k)$ identical servers. Default is $m(k) = 1$ for all k .

OUTPUT

U $U(k)$ is the utilization of center k . For IS nodes, $U(k)$ is the *traffic intensity*.

R $R(k)$ is the average response time of center k .

Q $Q(k)$ is the average number of customers at center k .

X $X(k)$ is the throughput of center k .

G Vector of normalization constants. $G(n+1)$ contains the value of the normalization constant with n requests $G(n)$, $n = 0, \dots, N$.

See also: `qncsconvld`.

NOTE

For a network with K service centers and N requests, this implementation of the convolution algorithm has time and space complexity $O(NK)$.

REFERENCES

Jeffrey P. Buzen, *Computational Algorithms for Closed Queueing Networks with Exponential Servers*, Communications of the ACM, volume 16, number 9, september 1973, pp. 527–531. [10.1145/362342.362345](#)

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, pp. 313–317.

EXAMPLE

The normalization constant G can be used to compute the steady-state probabilities for a closed single class product-form Queueing Network with K nodes. Let $\mathbf{k}=[k_1, k_2, \dots, k_K]$ be a valid population vector. Then, the steady-state probability $p(i)$ to have $k(i)$ requests at service center i can be computed as:

$$p_i(k_i) = \frac{(V_i S_i)^{k_i}}{G(K)} (G(K - k_i) - V_i S_i G(K - k_i - 1)), \quad i = 1, 2, \dots, K$$

```

k = [1 2 0];
K = sum(k); # Total population size
S = [ 1/0.8 1/0.6 1/0.4 ];
m = [ 2 3 1 ];
V = [ 1 .667 .2 ];
[U R Q X G] = qncsconv( K, S, V, m );
p = [0 0 0]; # initialize p
# Compute the probability to have k(i) jobs at service center i
for i=1:3
    p(i) = (V(i)*S(i))^(k(i)) / G(K+1) * \
            (G(K-k(i)+1) - V(i)*S(i)*G(K-k(i))) );
    printf("k(%d)=%d prob=%f\n", i, k(i), p(i) );
endfor
+ k(1)=1 prob=0.17975
+ k(2)=2 prob=0.48404
+ k(3)=0 prob=0.52779

```

`[U, R, Q, X, G] = qncsconvld (N, S, V)` [Function File]

This function implements the *convolution algorithm* for product-form, single-class closed queueing networks with general load-dependent service centers.

This function computes steady-state performance measures for single-class, closed networks with load-dependent service centers using the convolution algorithm; the normalization constants are also computed. The normalization constants are returned as vector $\mathbf{G}=[G(1), \dots, G(N+1)]$ where $G(i+1)$ is the value of $G(i)$.

INPUTS

- N Number of requests in the system ($N > 0$).
- S $S(\mathbf{k}, n)$ is the mean service time at center k where there are n requests, $1 \leq n \leq N$. $S(\mathbf{k}, n) = 1/\mu_{k,n}$, where $\mu_{k,n}$ is the service rate of center k when there are n requests.
- V $V(k)$ is the visit count of service center k ($V(k) \geq 0$). The length of V is the number of servers K in the network.

OUTPUT

- U $U(k)$ is the utilization of center k .
- R $R(k)$ is the average response time at center k .
- Q $Q(k)$ is the average number of customers in center k .

X	$X(k)$ is the throughput of center k .
G	Normalization constants (vector). $G(n+1)$ corresponds to $G(n)$, as array indexes in Octave start from 1.

See also: qncsconv.

REFERENCES

Herb Schwetman, *Some Computational Aspects of Queueing Network Models*, Technical Report [CSD-TR-354](#), Department of Computer Sciences, Purdue University, feb, 1981 (revised).

M. Reiser, H. Kobayashi, *On The Convolution Algorithm for Separable Queueing Networks*, In Proceedings of the 1976 ACM SIGMETRICS Conference on Computer Performance Modeling Measurement and Evaluation (Cambridge, Massachusetts, United States, March 29–31, 1976). SIGMETRICS '76. ACM, New York, NY, pp. 109–117. [10.1145/800200.806187](#)

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998, pp. 313–317. Function `qncsconvld` is slightly different from the version described in Bolch et al. because it supports general load-dependent centers (while the version in the book does not). The modification is in the definition of function `F()` in `qncsconvld` which has been made similar to function f_i defined in Schwetman, *Some Computational Aspects of Queueing Network Models*.

5.2.3 Non Product-Form QNs

`[U, R, Q, X] = qncsmvablo (N, S, M, P)` [Function File]

Approximate MVA algorithm for closed queueing networks with blocking.

INPUTS

N	population size, i.e., number of requests in the system. N must be strictly greater than zero, and less than the overall network capacity: $0 < N < \text{sum}(M)$.
S	Average service time. $S(i)$ is the average service time requested on server i ($S(i) > 0$).
M	$M(i)$ is the capacity of center i . The capacity is the maximum number of requests in a service center, including the request currently in service ($M(i) \geq 1$).
P	$P(i, j)$ is the probability that a request which completes service at server i will be transferred to server j .

OUTPUTS

U	$U(i)$ is the utilization of service center i .
R	$R(i)$ is the average response time of service center i .
Q	$Q(i)$ is the average number of requests in service center i (including the request in service).
X	$X(i)$ is the throughput of service center i .

See also: qnopen, qnclosed.

REFERENCES

Ian F. Akyildiz, *Mean Value Analysis for Blocking Queueing Networks*, IEEE Transactions on Software Engineering, vol. 14, n. 2, april 1988, pp. 418–428. [10.1109/32.4663](#)

[*U*, *R*, *Q*, *X*] = qnmarkov (*lambda*, *S*, *C*, *P*) [Function File]
 [*U*, *R*, *Q*, *X*] = qnmarkov (*lambda*, *S*, *C*, *P*, *m*) [Function File]
 [*U*, *R*, *Q*, *X*] = qnmarkov (*N*, *S*, *C*, *P*) [Function File]
 [*U*, *R*, *Q*, *X*] = qnmarkov (*N*, *S*, *C*, *P*, *m*) [Function File]

Compute utilization, response time, average queue length and throughput for open or closed queueing networks with finite capacity. Blocking type is Repetitive-Service (RS). This function explicitly generates and solve the underlying Markov chain, and thus might require a large amount of memory.

More specifically, networks which can be analyzed by this function have the following properties:

- There exists only a single class of customers.
- The network has K service centers. Center i has $m_i > 0$ servers, and has a total (finite) capacity of $C_i \geq m_i$ which includes both buffer space and servers. The buffer space at service center i is therefore $C_i - m_i$.
- The network can be open, with external arrival rate to center i equal to λ_i , or closed with fixed population size N . For closed networks, the population size N must be strictly less than the network capacity: $N < \sum_i C_i$.
- Average service times are load-independent.
- $P_{i,j}$ is the probability that requests completing execution at center i are transferred to center j , $i \neq j$. For open networks, a request may leave the system from any node i with probability $1 - \sum_j P_{i,j}$.
- Blocking type is Repetitive-Service (RS). Service center j is *saturated* if the number of requests is equal to its capacity C_j . Under the RS blocking discipline, a request completing service at center i which is being transferred to a saturated server j is put back at the end of the queue of i and will receive service again. Center i then processes the next request in queue. External arrivals to a saturated servers are dropped.

INPUTS

lambda

N If the first argument is a vector *lambda*, it is considered to be the external arrival rate $\lambda(i) \geq 0$ to service center i of an open network. If the first argument is a scalar, it is considered as the population size N of a closed network; in this case N must be strictly less than the network capacity: $N < \text{sum}(C)$.

S $S(i)$ is the average service time at service center i

C $C(i)$ is the Capacity of service center i . The capacity includes both the buffer and server space $m(i)$. Thus the buffer space is $C(i) - m(i)$.

P $P(i, j)$ is the transition probability from service center i to service center j .

m $m(i)$ is the number of servers at service center i . Note that $m(i) \geq C(i)$ for each i . If m is omitted, all service centers are assumed to have a single server ($m(i) = 1$ for all i).

OUTPUTS

U $U(i)$ is the utilization of service center i .

R $R(i)$ is the response time on service center i .

Q $Q(i)$ is the average number of customers in the service center i , *including* the request in service.

X $X(i)$ is the throughput of service center i .

Note:

The space complexity of this implementation is $O(\prod_{i=1}^K (C_i + 1)^2)$. The time complexity is dominated by the time needed to solve a linear system with $\prod_{i=1}^K (C_i + 1)$ unknowns.

5.3 Multiple Class Models

In multiple class QN models, we assume that there exist C different classes of requests. Each request from class c spends on average time $S_{c,k}$ in service at service center k . For open models, we denote with $\lambda = \lambda_{c,k}$ the arrival rates, where $\lambda_{c,k}$ is the external arrival rate of class c customers at service center k . For closed models, we denote with $\mathbf{N} = (N_1, N_2, \dots, N_C)$ the population vector, where N_c is the number of class c requests in the system.

The transition probability matrix for these kind of networks will be a $C \times K \times C \times K$ matrix $\mathbf{P} = [P_{r,i,s,j}]$ such that $P_{r,i,s,j}$ is the probability that a class r request which completes service at center i will join server j as a class s request.

Model input and outputs can be adjusted by adding additional indexes for the customer classes.

Model Inputs

$\lambda_{c,k}$ External arrival rate of class- c requests to service center k

λ Overall external arrival rate to the whole system: $\lambda = \sum_c \sum_k \lambda_{c,k}$

$S_{c,k}$ Average service time. $S_{c,k}$ is the average service time on service center k for class c requests.

$P_{r,i,s,j}$ Routing probability matrix. $\mathbf{P} = [P_{r,i,s,j}]$ is a $C \times K \times C \times K$ matrix such that $P_{r,i,s,j}$ is the probability that a class r request which completes service at server i will move to server j as a class s request.

$V_{c,k}$ Average number of visits. $V_{c,k}$ is the average number of visits of class c requests to center k .

Model Outputs

$U_{c,k}$ Utilization of service center k by class c requests. The utilization is defined as the fraction of time in which the resource is busy (i.e., the server is processing requests). If center k is a single-server or multiserver node, then $0 \leq U_{c,k} \leq 1$.

If center k is an infinite server node (delay center), then $U_{c,k}$ denotes the *traffic intensity* and is defined as $U_{c,k} = X_{c,k}S_{c,k}$; in this case the utilization may be greater than one.

$R_{c,k}$	Average response time experienced by class c requests on service center k . The average response time is defined as the average time between the arrival of a customer in the queue, and the completion of service.
$Q_{c,k}$	Average number of class c requests on service center k . This includes both the requests in the queue, and the request being served.
$X_{c,k}$	Throughput of service center k for class c requests. The throughput is defined as the rate of completion of class c requests.

It is possible to define aggregate performance measures as follows:

U_k	Utilization of service center k : $U_k = \sum_{c=1}^C U_{c,k}$
R_c	System response time for class c requests: $R_c = \sum_{k=1}^K R_{c,k} V_{c,k}$
Q_c	Average number of class c requests in the system: $Q_c = \sum_{k=1}^K Q_{c,k}$
X_c	Class c throughput: $X_c = X_{c,1}/V_{c,1}$

We can define the visit ratios $V_{s,j}$ for class s customers at service center j as follows:

$$\begin{cases} V_{s,j} = \sum_{r=1}^C \sum_{i=1}^K V_{r,i} P_{r,i,s,j}, & s = 1, \dots, C, j = 1, \dots, K \\ V_{s,r_s} = 1 & s = 1, \dots, C \end{cases}$$

where r_s is the class s reference station. Similarly to single class models, the traffic equation for closed multiclass networks can be solved up to multiplicative constants unless we choose one reference station for each closed chain class and set its visit ratio to 1.

For open networks the traffic equations are as follows:

$$V_{s,j} = P_{0,s,j} + \sum_{r=1}^C \sum_{i=1}^K V_{r,i} P_{r,i,s,j} \quad s = 1, \dots, K, j = 1, \dots, K$$

where $P_{0,s,j}$ is the probability that an external arrival goes to service center j as a class- s request. If $\lambda_{s,j}$ is the external arrival rate of class s requests to service center j , and $\lambda = \sum_s \sum_j \lambda_{s,j}$ is the overall external arrival rate to the whole system, then $P_{0,s,j} = \lambda_{s,j}/\lambda$.

[V ch] = qncmvisits (P) [Function File]
 [V ch] = qncmvisits (P, r) [Function File]

Compute the average number of visits to the service centers of a closed multiclass network with K service centers and C customer classes.

INPUTS

P $P(r,i,s,j)$ is the probability that a class r request which completed service at center i is routed to center j as a class s request. Class switching is allowed.

r $r(c)$ is the index of class c reference station, $r(c) \in \{1, \dots, K\}$, $c \in \{1, @dots, C\}$. The class c visit count to server $r(c)$ ($V(c, r(c))$) is conventionally set to 1. The reference station serves two purposes: (i) its throughput is assumed to be the system throughput, and (ii) a job returning to the reference station is assumed to have completed one cycle. Default is to consider station 1 as the reference station for all classes.

OUTPUTS

V $V(c, i)$ is the number of visits of class c requests at center i .

ch $ch(c)$ is the chain number that class c belongs to. Different classes can belong to the same chain. Chains are numbered sequentially starting from 1 ($1, 2, \dots$). The total number of chains is $\max(ch)$.

$V = \text{qnomvisits}(P, \text{lambda})$ [Function File]
 Compute the average number of visits to the service centers of an open multiclass network with K service centers and C customer classes.

INPUTS

P $P(r, i, s, j)$ is the probability that a class r request which completed service at center i is routed to center j as a class s request. Class switching is supported.

lambda $\text{lambda}(r, i)$ is the arrival rate of class r requests to center i .

OUTPUTS

V $V(r, i)$ is the number of visits of class r requests at center i .

5.3.1 Open Networks

$[U, R, Q, X] = \text{qnom}(\text{lambda}, S, V)$ [Function File]
 $[U, R, Q, X] = \text{qnom}(\text{lambda}, S, V, m)$ [Function File]

Exact analysis of open, multiple-class BCMP networks. The network can be made of *single-server* queueing centers (FCFS, LCFS-PR or PS) or delay centers (IS). This function assumes a network with K service centers and C customer classes.

INPUTS

lambda $\text{lambda}(c)$ is the external arrival rate of class c customers ($\text{lambda}(c) > 0$).

S $S(c, k)$ is the mean service time of class c customers on the service center k ($S(c, k) > 0$). For FCFS nodes, mean service times must be class-independent.

V $V(c, k)$ is the average number of visits of class c customers to service center k ($V(c, k) \geq 0$).

m $m(k)$ is the number of servers at center i . If $m(k) < 1$, enter k is a delay center (IS); otherwise it is a regular queueing center with $m(k)$ servers. Default is $m(k) = 1$ for all k .

OUTPUTS

U	If k is a queueing center, then $U(c,k)$ is the class c utilization of center k . If k is an IS node, then $U(c,k)$ is the class c traffic intensity defined as $X(c,k)*S(c,k)$.
R	$R(c,k)$ is the class c response time at center k . The system response time for class c requests can be computed as <code>dot(R, V, 2)</code> .
Q	$Q(c,k)$ is the average number of class c requests at center k . The average number of class c requests in the system Q_c can be computed as <code>Qc = sum(Q, 2)</code>
X	$X(c,k)$ is the class c throughput at center k .

See also: `qnopen,qnos,qnomvisits`.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.1 ("Open Model Solution Techniques").

5.3.2 Closed Networks

`pop_mix = qncmpopmix(k, N)` [Function File]

Return the set of valid population mixes with exactly k customers, for a closed multiclass Queueing Network with population vector N . More specifically, given a multiclass Queueing Network with C customer classes, such that there are $N(i)$ requests of class i , a k -mix mix is a C -dimensional vector with the following properties:

```
all( mix >= 0 );
all( mix <= N );
sum( mix ) == k;
```

This function enumerates all valid k -mixes, such that `pop_mix(i)` is a C dimensional row vector representing a valid population mix, for all i .

INPUTS

k	Total population size of the requested mix. k must be a nonnegative integer
N	$N(i)$ is the number of class i requests. The condition $k \leq \text{sum}(N)$ must hold.

OUTPUTS

`pop_mix` `pop_mix(i,j)` is the number of class j requests in the i -th population mix. The number of population mixes is `rows(pop_mix)`.

Note that if you are interested in the number of k -mixes and you don't care to enumerate them, you can use the function `qnmvapop`.

See also: `qncmnpop`.

REFERENCES

Herb Schwetman, *Implementing the Mean Value Algorithm for the Solution of Queueing Network Models*, Technical Report **CSD-TR-355**, Department of Computer Sciences, Purdue University, feb 15, 1982,

Note that the slightly different problem of generating all tuples k_1, k_2, \dots, k_N such that $\sum_i k_i = k$ and k_i are nonnegative integers, for some fixed integer $k \geq 0$ has been described in S. Santini, *Computing the Indices for a Complex Summation*, unpublished report, available at http://arantxa.ii.uam.es/~ssantini/writing/notes/s668_summation.pdf

H = qncmnpop (N) [Function File]

Given a network with C customer classes, this function computes the number of valid population mixes $H(\mathbf{r}, \mathbf{n})$ that can be constructed by the multiclass MVA algorithm by allocating n customers to the first r classes.

INPUTS

N Population vector. $N(c)$ is the number of class- c requests in the system. The total number of requests in the network is **sum(N)**.

OUTPUTS

H $H(\mathbf{r}, \mathbf{n})$ is the number of valid populations that can be constructed allocating n customers to the first r classes.

See also: qncmmva, qncmpopmix.

REFERENCES

Zahorjan, J. and Wong, E. *The solution of separable queueing network models using mean value analysis*. SIGMETRICS Perform. Eval. Rev. 10, 3 (Sep. 1981), 80-85. DOI [10.1145/1010629.805477](https://doi.org/10.1145/1010629.805477)

[U, R, Q, X] = qncmmva (N, S) [Function File]
[U, R, Q, X] = qncmmva (N, S, V) [Function File]
[U, R, Q, X] = qncmmva (N, S, V, m) [Function File]
[U, R, Q, X] = qncmmva (N, S, V, m, Z) [Function File]
[U, R, Q, X] = qncmmva (N, S, P) [Function File]
[U, R, Q, X] = qncmmva (N, S, P, r) [Function File]
[U, R, Q, X] = qncmmva (N, S, P, r, m) [Function File]

Compute steady-state performance measures for closed, multiclass queueing networks using the Mean Value Analysis (MVA) algorithm.

Queueing policies at service centers can be any of the following:

FCFS (First-Come-First-Served) customers are served in order of arrival; multiple servers are allowed. For this kind of queueing discipline, average service times must be class-independent.

PS (Processor Sharing) customers are served in parallel by a single server, each customer receiving an equal share of the service rate.

LCFS-PR (Last-Come-First-Served, Preemptive Resume) customers are served in reverse order of arrival by a single server and the last arrival preempts the customer in service who will later resume service at the point of interruption.

IS (Infinite Server) customers are delayed independently of other customers at the service center (there is effectively an infinite number of servers).

Note: If this function is called specifying the visit ratios V , class switching is **not** allowed.

If this function is called specifying the routing probability matrix P , then class switching **is** allowed; however, in this case all nodes are restricted to be fixed rate servers or delay centers: multiple-server and general load-dependent centers are not supported.

INPUTS

- N $N(c)$ is the number of class c requests in the system; $N(c) \geq 0$. If class c has no requests ($N(c) == 0$), then for all k , $U(c,k) = R(c,k) = Q(c,k) = X(c,k) = 0$
- S $S(c,k)$ is the mean service time for class c customers at center k ($S(c,k) \geq 0$). If the service time at center k is class-dependent, i.e., different classes have different service times at center k , then center k is assumed to be of type $-/G/1$ -PS (Processor Sharing). If center k is a FCFS node ($m(k) > 1$), then the service times **must** be class-independent, i.e., all classes **must** have the same service time.
- V $V(c,k)$ is the average number of visits of class c customers to service center k ; $V(c,k) \geq 0$, default is 1. **If you pass this argument, class switching is not allowed**
- P $P(r,i,s,j)$ is the probability that a class r job completing service at center i is routed to center j as a class s job; the reference stations for each class are specified with the parameter r . **If you pass argument P , class switching is allowed**, but you can not specify any external delay (i.e., Z must be zero).
- r $r(c)$ is the reference station for class c . If omitted, station 1 is the reference station for all classes. See `qncmvisits`.
- m If $m(k) < 1$, then center k is assumed to be a delay center (IS node $-/G/\infty$). If $m(k) == 1$, then service center k is a regular queueing center ($M/M/1$ -FCFS, $-/G/1$ -LCFS-PR or $-/G/1$ -PS). Finally, if $m(k) > 1$, center k is a $M/M/m$ -FCFS center with $m(k)$ identical servers. Default is $m(k) = 1$ for each k .
- Z $Z(c)$ is the class c external delay (think time); $Z(c) \geq 0$. Default is 0. This parameter can not be used if you pass a routing matrix as the second parameter of `qncmmva`.

OUTPUTS

- U If k is a FCFS, LCFS-PR or PS node ($m(k) \geq 1$), then $U(c,k)$ is the class c utilization at center k , $0 \leq U(c,k) \leq 1$. If k is an IS node, then $U(c,k)$ is the class c *traffic intensity* at center k , defined as $U(c,k) = X(c,k) * S(c,k)$. In this case the value of $U(c,k)$ may be greater than one.

R	$R(c, k)$ is the class c response time at center k . The class c residence time at center k is $R(c, k) * C(c, k)$. The total class c system response time is $\text{dot}(R, V, 2)$.
Q	$Q(c, k)$ is the average number of class c requests at center k . The total number of requests at center k is $\text{sum}(Q(:, k))$. The total number of class c requests in the system is $\text{sum}(Q(c, :))$.
X	$X(c, k)$ is the class c throughput at center k . The class c throughput can be computed as $X(c, 1) / V(c, 1)$.

Note on numerical stability: In presence of load-dependent servers (e.g., if $m(i) > 1$ for some i), the MVA algorithm is known to be numerically unstable. Generally this problem manifests itself as negative response times or utilizations. This is not a problem with the `queueing` toolbox, but with the Mean Value Analysis algorithm, and therefore has currently no easy workaround (aoart from using a different solution technique, if available). This function prints a warning if it detects numerical problems; you can disable the warning with the command `warning("off", "qn:numerical-instability")`.

See also: `qnclosed`, `qncmmvaapprox`, `qncmvisits`.

NOTE

Given a network with K service centers, C job classes and population vector $\mathbf{N} = (N_1, N_2, \dots, N_C)$, the MVA algorithm requires space $O(C \prod_i (N_i + 1))$. The time complexity is $O(CK \prod_i (N_i + 1))$. This implementation is slightly more space-efficient (see details in the code). While the space requirement can be mitigated by using some optimizations, the time complexity can not. If you need to analyze large closed networks you should consider the `qncmmvaap` function, which implements the approximate MVA algorithm. Note however that `qncmmvaap` will only provide approximate results.

REFERENCES

M. Reiser and S. S. Lavenberg, *Mean-Value Analysis of Closed Multichain Queuing Networks*, Journal of the ACM, vol. 27, n. 2, April 1980, pp. 313–322. [10.1145/322186.322195](#)

This implementation is based on G. Bolch, S. Greiner, H. de Meer and K. Trivedi, *Queueing Networks and Markov Chains: Modeling and Performance Evaluation with Computer Science Applications*, Wiley, 1998 and Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.2.1 ("Exact Solution Techniques").

$[U, R, Q, X] = \text{qncmmvaap}(N, S, V)$	[Function File]
$[U, R, Q, X] = \text{qncmmvaap}(N, S, V, m)$	[Function File]
$[U, R, Q, X] = \text{qncmmvaap}(N, S, V, m, Z)$	[Function File]
$[U, R, Q, X] = \text{qncmmvaap}(N, S, V, m, Z, tol)$	[Function File]
$[U, R, Q, X] = \text{qncmmvaap}(N, S, V, m, Z, tol, iter_max)$	[Function File]

Analyze closed, multiclass queueing networks with K service centers and C customer classes using the approximate Mean Value Analysis (MVA) algorithm.

This implementation uses Bard and Schweitzer approximation. It is based on the assumption that

$$Q_i(\mathbf{N} - \mathbf{1}_c) \approx \frac{n-1}{n} Q_i(\mathbf{N})$$

where \mathbf{N} is a valid population mix, $\mathbf{N} - \mathbf{1}_c$ is the population mix \mathbf{N} with one class c customer removed, and $n = \sum_c N_c$ is the total number of requests.

This implementation works for networks made of infinite server (IS) nodes and single-server nodes only.

INPUTS

N	$N(c)$ is the number of class c requests in the system ($N(c) > 0$).
S	$S(c, k)$ is the mean service time for class c customers at center k ($S(c, k) \geq 0$).
V	$V(c, k)$ is the average number of visits of class c requests to center k ($V(c, k) \geq 0$).
m	$m(k)$ is the number of servers at service center k . If $m(k) < 1$, then the service center k is assumed to be a delay center (IS). If $m(k) == 1$, service center k is a regular queueing center (FCFS, LCFS-PR or PS) with a single server node. If omitted, each service center has a single server. Note that multiple server nodes are not supported.
Z	$Z(c)$ is the class c external delay. Default is 0.
tol	Stopping tolerance ($tol > 0$). The algorithm stops if the queue length computed on two subsequent iterations are less than tol . Default is 10^{-5} .
$iter_max$	Maximum number of iterations ($iter_max > 0$). The function aborts if convergence is not reached within the maximum number of iterations. Default is 100.

OUTPUTS

U	If k is a FCFS, LCFS-PR or PS node, then $U(c, k)$ is the utilization of class c requests on service center k . If k is an IS node, then $U(c, k)$ is the class c traffic intensity at device k , defined as $U(c, k) = X(c) * S(c, k)$
R	$R(c, k)$ is the response time of class c requests at service center k .
Q	$Q(c, k)$ is the average number of class c requests at service center k .
X	$X(c, k)$ is the class c throughput at service center k .

See also: qncmmva.

REFERENCES

- Y. Bard, *Some Extensions to Multiclass Queueing Network Analysis*, proc. 4th Int. Symp. on Modelling and Performance Evaluation of Computer Systems, feb. 1979, pp. 51–62.
- P. Schweitzer, *Approximate Analysis of Multiclass Closed Networks of Queues*, Proc. Int. Conf. on Stochastic Control and Optimization, jun 1979, pp. 25–29.

This implementation is based on Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.2.2 ("Approximate Solution Techniques"). This implementation is slightly different from the one described above, as it computes the average response times R instead of the residence times.

5.3.3 Mixed Networks

`[U, R, Q, X] = qnmix (lambda, N, S, V, m)` [Function File]

Solution of mixed queueing networks through MVA. The network consists of K service centers (single-server or delay centers) and C independent customer chains. Both open and closed chains are possible. *lambda* is the vector of per-chain arrival rates (open classes); *N* is the vector of populations for closed chains.

Note: In this implementation class switching is **not** allowed. Each customer class *must* correspond to an independent chain.

If the network is made of open or closed classes only, then this function calls `qnom` or `qncmmva` respectively, and prints a warning message.

INPUTS

lambda

N

For each customer chain c :

- if c is a closed chain, then $N(c) > 0$ is the number of class c requests and $\lambda(c)$ must be zero;
- If c is an open chain, $\lambda(c) > 0$ is the arrival rate of class c requests and $N(c)$ must be zero;

In other words, for each class c the following must hold:

$$(\lambda(c) > 0 \ \&\& \ N(c) == 0) \ || \ (\lambda(c) == 0 \ \&\& \ N(c) > 0)$$

S

$S(c, k)$ is the mean class c service time at center k , $S(c, k) \geq 0$. For FCFS nodes, service times must be class-independent.

V

$V(c, k)$ is the average number of visits of class c customers to center k ($V(c, k) \geq 0$).

m

$m(k)$ is the number of servers at center k . Only single-server ($m(k) == 1$) or IS (Infinite Server) nodes ($m(k) < 1$) are supported. If omitted, each center is assumed to be of type $M/M/1$ -FCFS. Queueing discipline for single-server nodes can be FCFS, PS or LCFS-PR.

OUTPUTS

U

$U(c, k)$ is class c utilization at center k .

R

$R(c, k)$ is class c response time at center k .

Q

$Q(c, k)$ is the average number of class c requests at center k .

X

$X(c, k)$ is class c throughput at center k .

See also: `qncmmva`, `qncm`.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 7.4.3 ("Mixed Model Solution Techniques"). Note that in this function we compute the mean response time R instead of the mean residence time as in the reference.

Herb Schwetman, *Implementing the Mean Value Algorithm for the Solution of Queueing Network Models*, Technical Report CSD-TR-355, Department of Computer Sciences, Purdue University, feb 15, 1982,

5.4 Generic Algorithms

The `queueing` package provides a high-level function `qnsolve` for analyzing QN models. `qnsolve` takes as input a high-level description of the queueing model, and delegates the actual solution of the model to one of the lower-level function. `qnsolve` supports single or multiclass models, but at the moment only product-form networks can be analyzed. For non product-form networks See [Non Product-Form QNs], page 46.

`qnsolve` accepts two input parameters. The first one is the list of nodes, encoded as an Octave *cell array*. The second parameter is the vector of visit ratios V , which can be either a vector (for single-class models) or a two-dimensional matrix (for multiple-class models).

Individual nodes in the network are structures build using the `qnmknode` function.

<code>Q = qnmknode ("m/m/m-fcfs", S)</code>	[Function File]
<code>Q = qnmknode ("m/m/m-fcfs", S, m)</code>	[Function File]
<code>Q = qnmknode ("m/m/1-lcfs-pr", S)</code>	[Function File]
<code>Q = qnmknode ("-/g/1-ps", S)</code>	[Function File]
<code>Q = qnmknode ("-/g/1-ps", S, s2)</code>	[Function File]
<code>Q = qnmknode ("-/g/inf", S)</code>	[Function File]
<code>Q = qnmknode ("-/g/inf", S, s2)</code>	[Function File]

Creates a node; this function can be used together with `qnsolve`. It is possible to create either single-class nodes (where there is only one customer class), or multiple-class nodes (where the service time is given per-class). Furthermore, it is possible to specify load-dependent service times.

INPUTS

- | | |
|-----|--------------------|
| S | Mean service time. |
|-----|--------------------|
- If S is a scalar, it is assumed to be a load-independent, class-independent service time.
 - If S is a column vector, then $S(c)$ is assumed to be the load-independent service time for class c customers.
 - If S is a row vector, then $S(n)$ is assumed to be the class-independent service time at the node, when there are n requests.
 - Finally, if S is a two-dimensional matrix, then $S(c, n)$ is assumed to be the class c service time when there are n requests at the node.
- | | |
|-----|---|
| m | Number of identical servers at the node. Default is $m=1$. |
|-----|---|

$s2$ Squared coefficient of variation for the service time. Default is 1.0.

The returned struct Q should be considered opaque to the client.

See also: qnsolve.

After the network has been defined, it is possible to solve it using **qnsolve**.

```
[U, R, Q, X] = qnsolve ("closed", N, QQ, V)           [Function File]
[U, R, Q, X] = qnsolve ("closed", N, QQ, V, Z)       [Function File]
[U, R, Q, X] = qnsolve ("open", lambda, QQ, V)       [Function File]
[U, R, Q, X] = qnsolve ("mixed", lambda, N, QQ, V)   [Function File]
```

High-level function for analyzing QN models.

- For **closed** networks, the following server types are supported: $M/M/m$ -FCFS, $-/G/\infty$, $-/G/1$ -LCFS-PR, $-/G/1$ -PS and load-dependent variants.
- For **open** networks, the following server types are supported: $M/M/m$ -FCFS, $-/G/\infty$ and $-/G/1$ -PS. General load-dependent nodes are *not* supported. Multiclass open networks do not support multiple server $M/M/m$ nodes, but only single server $M/M/1$ -FCFS.
- For **mixed** networks, the following server types are supported: $M/M/1$ -FCFS, $-/G/\infty$ and $-/G/1$ -PS. General load-dependent nodes are *not* supported.

INPUTS

N Number of requests in the system for closed networks. For single-class networks, N must be a scalar. For multiclass networks, $N(c)$ is the population size of closed class c .

$lambda$ External arrival rate (scalar) for open networks. For single-class networks, $lambda$ must be a scalar. For multiclass networks, $lambda(c)$ is the class c overall arrival rate.

QQ List of queues in the network. This must be a cell array with N elements, such that $QQ\{i\}$ is a struct produced by the **qnmknode** function.

Z External delay ("think time") for closed networks. Default 0.

OUTPUTS

U If i is a FCFS node, then $U(i)$ is the utilization of service center i . If i is an IS node, then $U(i)$ is the *traffic intensity* defined as $X(i)*S(i)$.

R $R(i)$ is the average response time of service center i .

Q $Q(i)$ is the average number of customers in service center i .

X $X(i)$ is the throughput of service center i .

Note that for multiclass networks, the computed results are per-class utilization, response time, number of customers and throughput: $U(c,k)$, $R(c,k)$, $Q(c,k)$, $X(c,k)$,

EXAMPLE

Let us consider a closed, multiclass network with $C = 2$ classes and $K = 3$ service center. Let the population be $M = (2, 1)$ (class 1 has 2 requests, and class 2 has 1 request). The nodes are as follows:

- Node 1 is a $M/M/1$ -FCFS node, with load-dependent service times. Service times are class-independent, and are defined by the matrix $[0.2 \ 0.1 \ 0.1; 0.2 \ 0.1 \ 0.1]$. Thus, $S(1,2) = 0.2$ means that service time for class 1 customers where there are 2 requests in 0.2. Note that service times are class-independent;
- Node 2 is a $-/G/1$ -PS node, with service times $S_{1,2} = 0.4$ for class 1, and $S_{2,2} = 0.6$ for class 2 requests;
- Node 3 is a $-/G/\infty$ node (delay center), with service times $S_{1,3} = 1$ and $S_{2,3} = 2$ for class 1 and 2 respectively.

After defining the per-class visit count V such that $V(c,k)$ is the visit count of class c requests to service center k . We can define and solve the model as follows:

```
QQ = { qnmknode( "m/m/m-fcfs", [0.2 0.1 0.1; 0.2 0.1 0.1] ), \
       qnmknode( "-/g/1-ps", [0.4; 0.6] ), \
       qnmknode( "-/g/inf", [1; 2] ) };
V = [ 1 0.6 0.4; \
      1 0.3 0.7 ];
N = [ 2 1 ];
[U R Q X] = qnsolve( "closed", N, QQ, V );
```

`[U, R, Q, X] = qnclosed (N, S, V, ...)` [Function File]

This function computes steady-state performance measures of closed queueing networks using the Mean Value Analysis (MVA) algorithm. The queueing network is allowed to contain fixed-capacity centers, delay centers or general load-dependent centers. Multiple request classes are supported.

This function dispatches the computation to one of `qncsemva`, `qncsmvald` or `qncmmva`.

- If N is a scalar, the network is assumed to have a single class of requests; in this case, the exact MVA algorithm is used to analyze the network. If S is a vector, then $S(k)$ is the average service time of center k , and this function calls `qncsmva` which supports load-independent service centers. If S is a matrix, $S(k,i)$ is the average service time at center k when $i = 1, \dots, N$ jobs are present; in this case, the network is analyzed with the `qncmmvald` function.
- If N is a vector, the network is assumed to have multiple classes of requests, and is analyzed using the exact multiclass MVA algorithm as implemented in the `qncmmva` function.

See also: `qncsmva`, `qncsmvald`, `qncmmva`.

EXAMPLE

```
P = [0 0.3 0.7; 1 0 0; 1 0 0]; # Transition probability matrix
S = [1 0.6 0.2];               # Average service times
m = ones(size(S));             # All centers are single-server
Z = 2;                          # External delay
N = 15;                         # Maximum population to consider
V = qncsvisits(P);              # Compute number of visits
X_bsb_lower = X_bsb_upper = X_ab_lower = X_ab_upper = X_mva = zeros(1,N);
```

```

for n=1:N
    [X_bsb_lower(n) X_bsb_upper(n)] = qncsbsb(n, S, V, m, Z);
    [X_ab_lower(n) X_ab_upper(n)] = qncsaba(n, S, V, m, Z);
    [U R Q X] = qnclosed( n, S, V, m, Z );
    X_mva(n) = X(1)/V(1);
endfor
close all;
plot(1:N, X_ab_lower,"g;Asymptotic Bounds;", \
      1:N, X_bsb_lower,"k;Balanced System Bounds;", \
      1:N, X_mva,"b;MVA;", "linewidth", 2, \
      1:N, X_bsb_upper,"k", 1:N, X_ab_upper,"g" );
axis([1,N,0,1]); legend("location","southeast");
xlabel("Number of Requests n"); ylabel("System Throughput X(n)");

[U, R, Q, X] = qnopen (lambda, S, V, ...) [Function File]

```

Compute utilization, response time, average number of requests in the system, and throughput for open queueing networks. If *lambda* is a scalar, the network is considered a single-class QN and is solved using `qnopensingle`. If *lambda* is a vector, the network is considered as a multiclass QN and solved using `qnopenmulti`.

See also: qnos, qnom.

5.5 Bounds Analysis

```

[Xl, Xu, Rl, Ru] = qnosaba (lambda, D) [Function File]
[Xl, Xu, Rl, Ru] = qnosaba (lambda, S, V) [Function File]
[Xl, Xu, Rl, Ru] = qnosaba (lambda, S, V, m) [Function File]

```

Compute Asymptotic Bounds for open, single-class networks.

INPUTS

lambda Arrival rate of requests ($\lambda \geq 0$).

D $D(k)$ is the service demand at center k . ($D(k) \geq 0$ for all k).

S $S(k)$ is the mean service time at center k . ($S(k) \geq 0$ for all k).

V $V(k)$ is the mean number of visits to center k . ($V(k) \geq 0$ for all k).

m $m(k)$ is the number of servers at center k . This function only supports $M/M/1$ queues, therefore *m* must be `ones(size(S))`.

OUTPUTS

Xl

Xu Lower and upper bounds on the system throughput. *Xl* is always set to 0 since there can be no lower bound on the throughput of open networks.

Rl

Ru Lower and upper bounds on the system response time. *Ru* is always set to `+inf` since there can be no upper bound on the throughput of open networks.

See also: qnopenmultiab.

`[Xl, Xu, Rl, Ru] = qnomaba (lambda, D)` [Function File]

`[Xl, Xu, Rl, Ru] = qnomaba (lambda, S, V)` [Function File]

Compute Asymptotic Bounds for open, multiclass networks.

INPUTS

lambda *lambda*(*c*) is the class *c* arrival rate to the system.

D *D*(*c*, *k*) is class *c* service demand at center *k*. (*D*(*c*, *k*) ≥ 0 for all *k*).

S *S*(*c*, *k*) is the mean service time of class *c* requests at center *k*. (*S*(*c*, *k*) ≥ 0 for all *k*).

V *V*(*c*, *k*) is the mean number of visits of class *c* requests at center *k*. (*V*(*c*, *k*) ≥ 0 for all *k*).

OUTPUTS

Xl

Xu Per-class lower and upper throughput bounds. For example, *Xu*(*c*) is the upper bound for class *c* throughput. *Xl* is always 0 since there can be no lower bound on the throughput of open networks.

Rl

Ru Per-class lower and upper response time bounds. *Ru* is always `+inf` since there can be no upper bound on the response time of open networks.

See also: qnombsb.

`[Xl, Xu, Rl, Ru] = qncsaba (N, D)` [Function File]

`[Xl, Xu, Rl, Ru] = qncsaba (N, S, V)` [Function File]

`[Xl, Xu, Rl, Ru] = qncsaba (N, S, V, m)` [Function File]

`[Xl, Xu, Rl, Ru] = qncsaba (N, S, V, m, Z)` [Function File]

Compute Asymptotic Bounds for throughput and response time of closed, single-class networks.

Single-server and infinite-server nodes are supported. Multiple-server nodes and general load-dependent servers are not supported.

INPUTS

N number of requests in the system (scalar, *N*>0).

D *D*(*k*) is the service demand at center *k* (*D*(*k*) ≥ 0).

S *S*(*k*) is the mean service time at center *k* (*S*(*k*) ≥ 0).

V *V*(*k*) is the average number of visits to center *k* (*V*(*k*) ≥ 0).

m *m*(*k*) is the number of servers at center *k* (if *m* is a scalar, all centers have that number of servers). If *m*(*k*) < 1, center *k* is a delay center (IS); if *m*(*k*) = 1, center *k* is a M/M/1-FCFS server. This function does not support multiple-server nodes. Default is 1.

Z External delay (*Z* ≥ 0). Default is 0.

OUTPUTS

Xl
 Xu Lower and upper system throughput bounds.
 Rl
 Ru Lower and upper response time bounds.

See also: qncmaba.

$[Xl, Xu, Rl, Ru] = \text{qncmaba}(N, D)$ [Function File]
 $[Xl, Xu, Rl, Ru] = \text{qncmaba}(N, S, V)$ [Function File]
 $[Xl, Xu, Rl, Ru] = \text{qncmaba}(N, S, V, m)$ [Function File]
 $[Xl, Xu, Rl, Ru] = \text{qncmaba}(N, S, V, m, Z)$ [Function File]

Compute Asymptotic Bounds for multiclass networks. Single-server and infinite-server nodes are supported. Multiple-server nodes and general load-dependent servers are not supported.

INPUTS

N $N(c)$ is the number of class c requests in the system.
 D $D(c, k)$ is class c service demand at center k ($D(c, k) \geq 0$).
 S $S(c, k)$ is the mean service time of class c requests at center k ($S(c, k) \geq 0$).
 V $V(c, k)$ is the average number of visits of class c requests to center k ($V(c, k) \geq 0$).
 m $m(k)$ is the number of servers at center k (if m is a scalar, all centers have that number of servers). If $m(k) < 1$, center k is a delay center (IS); if $m(k) = 1$, center k is a M/M/1-FCFS server. This function does not support multiple-server nodes. Default is 1.
 Z $Z(c)$ is class c external delay ($Z(c) \geq 0$). Default is 0.

OUTPUTS

Xl
 Xu Lower and upper class c throughput bounds.
 Rl
 Ru Lower and upper class c response time bounds.

See also: qnclosedsingleab.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 5.2 ("Asymptotic Bounds").

$[Xl, Xu, Rl, Ru] = \text{qnosbsb}(\lambda, D)$ [Function File]
 $[Xl, Xu, Rl, Ru] = \text{qnosbsb}(\lambda, S, V)$ [Function File]

Compute Balanced System Bounds for single-class, open networks.

INPUTS

lambda overall arrival rate to the system (scalar). Abort if *lambda* < 0

D $D(k)$ is the service demand at center k . ($D(k) \geq 0$ for all k).

S $S(k)$ is the mean service time at center k . ($S(k) \geq 0$ for all k).

V $V(k)$ is the mean number of visits at center k . ($V(k) \geq 0$ for all k).

m $m(k)$ is the number of servers at center k . This function only supports $M/M/1$ queues, therefore *m* must be `ones(size(S))`.

OUTPUTS

Xl

Xu Lower and upper bounds on the system throughput. *Xl* is always set to 0, since there can be no lower bound on open networks throughput.

Rl

Ru Lower and upper bounds on the system response time.

See also: `qnosaba`.

`[Xl, Xu, Rl, Ru] = qncsbsb (N, D)` [Function File]

`[Xl, Xu, Rl, Ru] = qncsbsb (N, S, V)` [Function File]

`[Xl, Xu, Rl, Ru] = qncsbsb (N, S, V, m)` [Function File]

`[Xl, Xu, Rl, Ru] = qncsbsb (N, S, V, m, Z)` [Function File]

Compute Balanced System Bounds on system throughput and response time for closed, single-class networks.

INPUTS

N number of requests in the system (scalar).

D $D(k)$ is the service demand at center k ($D(k) \geq 0$).

S $S(k)$ is the mean service time at center k ($S(k) \geq 0$).

V $V(k)$ is the average number of visits to center k ($V(k) \geq 0$). Default is 1.

m $m(k)$ is the number of servers at center k . This function supports $m(k) = 1$ only (sing-eserver FCFS nodes). This option is left for compatibility with `qnosaba`, Default is 1.

Z External delay ($Z \geq 0$). Default is 0.

OUTPUTS

Xl

Xu Lower and upper bound on the system throughput.

Rl

Ru Lower and upper bound on the system response time.

See also: `qncmbsb`.

[*Xl*, *Xu*, *Rl*, *Ru*] = qncmbsb (*N*, *D*) [Function File]

[*Xl*, *Xu*, *Rl*, *Ru*] = qncmbsb (*N*, *S*, *V*) [Function File]

Compute Balanced System Bounds for multiclass networks. Only single-server nodes are supported.

INPUTS

N $N(c)$ is the number of class c requests in the system.

D $D(c, k)$ is class c service demand at center k ($D(c, k) \geq 0$).

S $S(c, k)$ is the mean service time of class c requests at center k ($S(c, k) \geq 0$).

V $V(c, k)$ is the average number of visits of class c requests to center k ($V(c, k) \geq 0$).

OUTPUTS

Xl

Xu Lower and upper class c throughput bounds.

Rl

Ru Lower and upper class c response time bounds.

See also: qnclosedsinglebsb.

REFERENCES

Edward D. Lazowska, John Zahorjan, G. Scott Graham, and Kenneth C. Sevcik, *Quantitative System Performance: Computer System Analysis Using Queueing Network Models*, Prentice Hall, 1984. <http://www.cs.washington.edu/homes/lazowska/qsp/>. In particular, see section 5.4 ("Balanced Systems Bounds").

[*Xl*, *Xu*, *Rl*, *Ru*] = qncmcb (*N*, *D*) [Function File]

[*Xl*, *Xu*, *Rl*, *Ru*] = qncmcb (*N*, *S*, *V*) [Function File]

Composite Bound (CB) on throughput and response time for closed multiclass networks.

This function implements the Composite Bound Method described in T. Kerola, *The Composite Bound Method (CBM) for Computing Throughput Bounds in Multiple Class Environments*, Technical Report CSD-TR-475, Purdue University, march 13, 1984 (revised august 27, 1984).

INPUTS

N $N(c)$ is the number of class c requests in the system.

D $D(c, k)$ is class c service demand at center k ($S(c, k) \geq 0$).

S $S(c, k)$ is the mean service time of class c requests at center k ($S(c, k) \geq 0$).

V $V(c, k)$ is the average number of visits of class c requests to center k ($V(c, k) \geq 0$).

OUTPUTS

Xl	
Xu	Lower and upper class c throughput bounds.
Rl	
Ru	Lower and upper class c response time bounds.

REFERENCES

Teemu Kerola, *The Composite Bound Method (CBM) for Computing Throughput Bounds in Multiple Class Environments*, Technical Report CSD-TR-475, Department of Computer Sciences, Purdue University, mar 13, 1984 (Revised aug 27, 1984).

<code>[Xl, Xu, Rl, Ru] = qncspb (N, D)</code>	[Function File]
<code>[Xl, Xu, Rl, Ru] = qncspb (N, S, V)</code>	[Function File]
<code>[Xl, Xu, Rl, Ru] = qncspb (N, S, V, m)</code>	[Function File]
<code>[Xl, Xu, Rl, Ru] = qncspb (N, S, V, m, Z)</code>	[Function File]

Compute PB Bounds (C. H. Hsieh and S. Lam, 1987) for single-class, closed networks.

INPUTS

N	number of requests in the system (scalar). Must be $N > 0$.
D	$D(\mathbf{k})$ is the service demand of service center k ($D(\mathbf{k}) \geq 0$).
S	$S(\mathbf{k})$ is the mean service time at center k ($S(\mathbf{k}) \geq 0$).
V	$V(\mathbf{k})$ is the visit ratio to center k ($V(\mathbf{k}) \geq 0$).
m	$m(\mathbf{k})$ is the number of servers at center k . This function only supports $M/M/1$ queues, therefore m must be <code>ones(size(S))</code> .
Z	external delay (think time, $Z \geq 0$). Default 0.

OUTPUTS

Xl	
Xu	Lower and upper bounds on the system throughput.
Rl	
Ru	Lower and upper bounds on the system response time.

See also: qncsaba, qbcsbsb, qncsgb.

REFERENCES

The original paper describing PB Bounds is C. H. Hsieh and S. Lam, *Two classes of performance bounds for closed queueing networks*, PEVA, vol. 7, n. 1, pp. 3–30, 1987

This function implements the non-iterative variant described in G. Casale, R. R. Muntz, G. Serazzi, *Geometric Bounds: a Non-Iterative Analysis Technique for Closed Queueing Networks*, IEEE Transactions on Computers, 57(6):780-794, June 2008.

<code>[Xl, Xu, Rl, Ru, Ql, Qu] = qncsgb(N, D)</code>	[Function File]
<code>[Xl, Xu, Rl, Ru, Ql, Qu] = qncsgb(N, S, V)</code>	[Function File]
<code>[Xl, Xu, Rl, Ru, Ql, Qu] = qncsgb(N, S, V, m)</code>	[Function File]
<code>[Xl, Xu, Rl, Ru, Ql, Qu] = qncsgb(N, S, V, m, Z)</code>	[Function File]

Compute Geometric Bounds (GB) on system throughput, system response time and server queue lengths for closed, single-class networks.

INPUTS

N	number of requests in the system (scalar, $N > 0$).
D	$D(k)$ is the service demand of service center k ($D(k) \geq 0$).
S	$S(k)$ is the mean service time at center k ($S(k) \geq 0$).
V	$V(k)$ is the visit ratio to center k ($V(k) \geq 0$).
m	$m(k)$ is the number of servers at center k . This function only supports $M/M/1$ queues, therefore m must be <code>ones(size(S))</code> .
Z	external delay (think time, $Z \geq 0$). Default 0.

OUTPUTS

Xl	
Xu	Lower and upper bound on the system throughput. If $Z > 0$, these bounds are computed using <i>Geometric Square-root Bounds</i> (GSB). If $Z = 0$, these bounds are computed using <i>Geometric Bounds</i> (GB)
Rl	
Ru	Lower and upper bound on the system response time. These bounds are derived from Xl and Xu using Little's Law: $Rl = N / Xu - Z$, $Ru = N / Xl - Z$
Ql	
Qu	$Ql(i)$ and $Qu(i)$ are the lower and upper bounds respectively of the queue length for service center i .

REFERENCES

G. Casale, R. R. Muntz, G. Serazzi, *Geometric Bounds: a Non-Iterative Analysis Technique for Closed Queueing Networks*, IEEE Transactions on Computers, 57(6):780-794, June 2008. [10.1109/TC.2008.37](#)

In this implementation we set X^+ and X^- as the upper and lower Asymptotic Bounds as computed by the `qnscab` function, respectively.

5.6 QN Analysis Examples

In this section we illustrate with a few examples how the `queueing` package can be used to evaluate queueing network models. Further examples can be found in the demo blocks of the functions described in this section, and can be accessed with the `demo function` Octave command.

5.6.1 Closed, Single Class Network

We now give a simple example on how the queueing toolbox can be used to analyze a closed network. Let us consider again the network shown in [Figure 5.1](#). We denote with S_k the average service time at center k , $k = 1, 2, 3$. We use $S_1 = 1.0$, $S_2 = 2.0$ and $S_3 = 0.8$. The routing of jobs within the network is described with a *routing probability matrix* \mathbf{P} . Specifically, a request completing service at center i is enqueued at center j with probability $P_{i,j}$. We use the following routing matrix:

$$P = \begin{pmatrix} 0 & 0.3 & 0.7 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

The network above can be analyzed with the `qnclosed` function see [\[doc-qnclosed\]](#), page 59. `qnclosed` requires the following parameters:

- N Number of requests in the network (since we are considering a closed network, the number of requests is fixed)
- S Array of average service times at the centers: $S(k)$ is the average service time at center k .
- V Array of visit ratios: $V(k)$ is the average number of visits to center k .

We can compute V_k from the routing probability matrix $P_{i,j}$ using the `qncsvisits` function see [\[doc-qncsvisits\]](#), page 35. We can analyze the network for a given population size N (for example, $N = 10$) as follows:

```
N = 10;
S = [1 2 0.8];
P = [0 0.3 0.7; 1 0 0; 1 0 0];
V = qncsvisits(P);
[U R Q X] = qnclosed( N, S, V )
⇒ U = 0.99139 0.59483 0.55518
⇒ R = 7.4360 4.7531 1.7500
⇒ Q = 7.3719 1.4136 1.2144
⇒ X = 0.99139 0.29742 0.69397
```

The output of `qnclosed` includes the vector of utilizations U_k at center k , response time R_k , average number of customers Q_k and throughput X_k . In our example, the throughput of center 1 is $X_1 = 0.99139$, and the average number of requests in center 3 is $Q_3 = 1.2144$. The utilization of center 1 is $U_1 = 0.99139$, which is the higher value among the service centers. Thus, center 1 is the *bottleneck device*.

This network can also be analyzed with the `qnsolve` function see [\[doc-qnsolve\]](#), page 58. `qnsolve` can handle open, closed or mixed networks, and allows the network to be described in a very flexible way. First, let $Q1$, $Q2$ and $Q3$ be the variables describing the service centers. Each variable is instantiated with the `qnmknode` function.

```
Q1 = qnmknode( "m/m/m-fcfs", 1 );
Q2 = qnmknode( "m/m/m-fcfs", 2 );
Q3 = qnmknode( "m/m/m-fcfs", 0.8 );
```

The first parameter of `qnmknode` is a string describing the type of the node. Here we use "m/m/m-fcfs" to denote a $M/M/m$ -FCFS center. The second parameter gives the average service time. An optional third parameter can be used to specify the number m of service centers. If omitted, it is assumed $m = 1$ (single-server node).

Now, the network can be analyzed as follows:

```

N = 10;
V = [1 0.3 0.7];
[U R Q X] = qnsolve( "closed", N, { Q1, Q2, Q3 }, V )
⇒ U = 0.99139 0.59483 0.55518
⇒ R = 7.4360 4.7531 1.7500
⇒ Q = 7.3719 1.4136 1.2144
⇒ X = 0.99139 0.29742 0.69397

```

5.6.2 Open, Single Class Network

Open networks can be analyzed in a similar way. Let us consider an open network with $K = 3$ service centers, and routing probability matrix as follows:

$$P = \begin{pmatrix} 0 & 0.3 & 0.5 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

In this network, requests can leave the system from center 1 with probability $1 - (0.3 + 0.5) = 0.2$. We suppose that external jobs arrive at center 1 with rate $\lambda_1 = 0.15$; there are no arrivals at centers 2 and 3.

Similarly to closed networks, we first need to compute the visit counts V_k to center k . We use the `qnosvisits` function as follows:

```

P = [0 0.3 0.5; 1 0 0; 1 0 0];
lambda = [0.15 0 0];
V = qnosvisits(P, lambda)
⇒ V = 5.00000 1.50000 2.50000

```

where `lambda(k)` is the arrival rate at center k , and P is the routing matrix. Assuming the same service times as in the previous example, the network can be analyzed with the `qlopen` function see [\[doc-qlopen\]](#), [page 60](#), as follows:

```

S = [1 2 0.8];
[U R Q X] = qlopen( sum(lambda), S, V )
⇒ U = 0.75000 0.45000 0.30000
⇒ R = 4.0000 3.6364 1.1429
⇒ Q = 3.00000 0.81818 0.42857
⇒ X = 0.75000 0.22500 0.37500

```

The first parameter of the `qlopen` function is the (scalar) aggregate arrival rate.

Again, it is possible to use the `qnsolve` high-level function:

```

Q1 = qnmknode( "m/m/m-fcfs", 1 );
Q2 = qnmknode( "m/m/m-fcfs", 2 );
Q3 = qnmknode( "m/m/m-fcfs", 0.8 );
lambda = [0.15 0 0];
[U R Q X] = qnsolve( "open", sum(lambda), { Q1, Q2, Q3 }, V )
⇒ U = 0.75000 0.45000 0.30000
⇒ R = 4.0000 3.6364 1.1429
⇒ Q = 3.00000 0.81818 0.42857
⇒ X = 0.75000 0.22500 0.37500

```


5.6.3 Closed Multiclass Network/1

The following example is taken from Herb Schwetman, *Implementing the Mean Value Algorithm for the Solution of Queueing Network Models*, Technical Report CSD-TR-355, Department of Computer Sciences, Purdue University, feb 15, 1982.

We consider the following multiclass QN with three servers and two classes

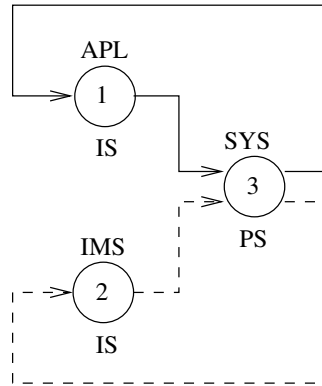


Figure 5.3

Servers 1 and 2 (labeled *APL* and *IMS*, respectively) are infinite server nodes; server 3 (labeled *SYS*) is Processor Sharing (PS). Mean service times are given in the following table:

	APL	IMS	SYS
Class 1	1	-	0.025
Class 2	-	15	0.500

There is no class switching. If we assume a population of 15 requests for class 1, and 5 requests for class 2, then the model can be analyzed as follows:

```

S = [1 0 .025; 0 15 .5];
P = zeros(2,3,2,3);
P(1,1,1,3) = P(1,3,1,1) = 1;
P(2,2,2,3) = P(2,3,2,2) = 1;
V = qncmvisits(P,[3 3]); # reference station is station 3
N = [15 5];
m = [-1 -1 1];
[U R Q X] = qncmmva(N,S,V,m)
⇒
U =

    14.32312    0.00000    0.35808
     0.00000    4.70699    0.15690

R =

    1.00000    0.00000    0.04726

```

$$\begin{array}{ccc}
0.00000 & 15.00000 & 0.93374 \\
\\
Q = & & \\
\\
14.32312 & 0.00000 & 0.67688 \\
0.00000 & 4.70699 & 0.29301 \\
\\
X = & & \\
\\
14.32312 & 0.00000 & 14.32312 \\
0.00000 & 0.31380 & 0.31380
\end{array}$$

5.6.4 Closed Multiclass Network/2

The following example is taken from M. Marzolla, *The qnetworks Toolbox: A Software Package for Queueing Networks Analysis*, Technical Report **UBLCS-2010-04**, Department of Computer Science, University of Bologna, Italy, February 2010.

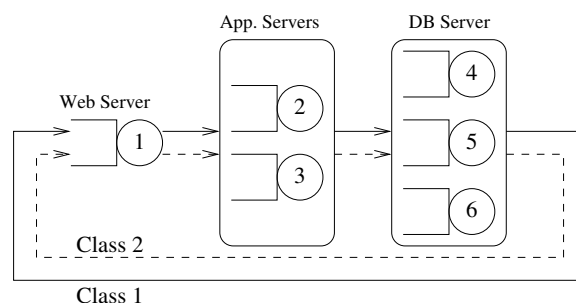


Figure 5.4: Three-tier enterprise system model

The model shown in **Figure 5.4** shows a three-tier enterprise system with $K = 6$ service centers. The first tier contains the *Web server* (node 1), which is responsible for generating Web pages and transmitting them to clients. The application logic is implemented by nodes 2 and 3, and the storage tier is made of nodes 4–6. The system is subject to two workload classes, both represented as closed populations of N_1 and N_2 requests, respectively. Let $D_{c,k}$ denote the service demand of class c requests at center k . We use the parameter values:

Serv. no.	Name	Class	Class
		1	2
1	Web Server	12	2
2	App. Server 1	14	20
3	App. Server 2	23	14
4	DB Server 1	20	90
5	DB Server 2	80	30
6	DB Server 3	31	33

We set the total number of requests to 100, that is $N_1 + N_2 = N = 100$, and we study how different population mixes (N_1, N_2) affect the system throughput and response time.

Let $\beta_1 \in (0,1)$ denote the fraction of class 1 requests: $N_1 = \beta_1 N$, $N_2 = (1 - \beta_1)N$. The following Octave code defines the model for $\beta_1 = 0.1$:

```
N = 100;      # total population size
beta1 = 0.1; # fraction of class 1 reqs.
S = [12 14 23 20 80 31; \
     2 20 14 90 30 33 ];
V = ones(size(S));
pop = [fix(beta1*N) N-fix(beta1*N)];
[U R Q X] = qncmmva(pop, S, V);
```

The `qncmmva(pop, S, V)` function invocation (line 7) uses the multiclass MVA algorithm to compute per-class utilizations $U_{c,k}$, response times $R_{c,k}$, mean queue lengths $Q_{c,k}$ and throughputs $X_{c,k}$ at each service center k , given a population vector `pop`, mean service times `S` and visit ratios `V`. Since we are given the service demands $D_{c,k} = S_{c,k}V_{c,k}$, but function `qncmmva()` requires separate service times and visit ratios, we set the service times equal to the demands (line 3–4), and all visit ratios equal to one (line 5). Overall class and system throughputs and response times can also be computed:

```
X1 = X(1,1) / V(1,1)      # class 1 throughput
    ⇒ X1 = 0.0044219
X2 = X(2,1) / V(2,1)      # class 2 throughput
    ⇒ X2 = 0.010128
XX = X1 + X2              # system throughput
    ⇒ XX = 0.014550
R1 = dot(R(1,:), V(1,:)) # class 1 resp. time
    ⇒ R1 = 2261.5
R2 = dot(R(2,:), V(2,:)) # class 2 resp. time
    ⇒ R2 = 8885.9
RR = N / XX               # system resp. time
    ⇒ RR = 6872.7
```

`dot(X,Y)` computes the dot product of two vectors. `R(1,:)` is the first row of matrix `R` and `V(1,:)` is the first row of matrix `V`, so `dot(R(1,:), V(1,:))` computes $\sum_k R_{1,k}V_{1,k}$.

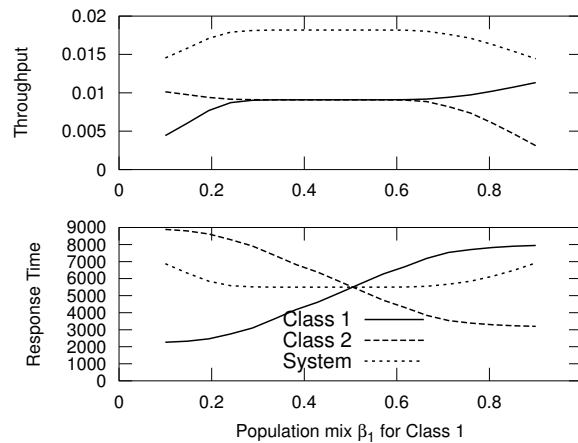


Figure 5.5: Throughput and Response Times as a function of the population mix

We can also compute the system power $\Phi = X/R$, which defines how efficiently resources are being used: high values of Φ denote the desirable situation of high throughput and low response time. Figure 5.6 shows Φ as a function of β_1 . We observe a “plateau” of the global system power, corresponding to values of β_1 which approximately lie between 0.3 and 0.7. The per-class power exhibits an interesting (although not completely surprising) pattern, where the class with higher population exhibits worst efficiency as it produces higher contention on the resources.

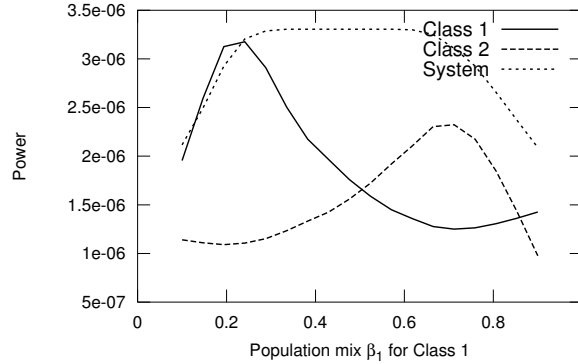


Figure 5.6: System Power as a function of the population mix

5.6.5 Closed Multiclass Network/3

We now consider an example of multiclass network with class switching. The example is taken from [Sch82], page 76, and is shown in Figure Figure 5.7.

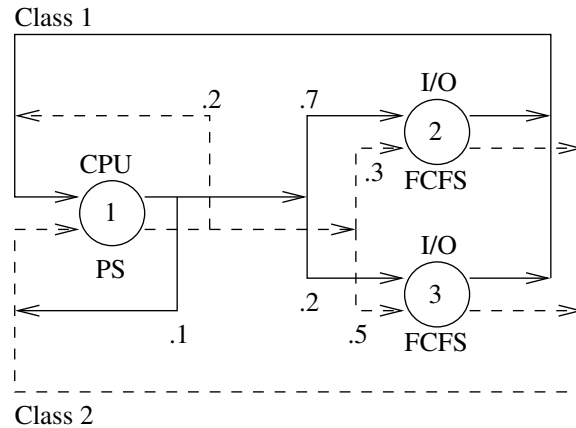


Figure 5.7: Multiclass Model with Class Switching

The system consists of three devices and two job classes. The CPU node is a PS server, while the two nodes labeled I/O are FCFS. Class 1 mean service time at the CPU is 0.01; class 2 mean service time at the CPU is 0.05. The mean service time at node 2 is 0.1, and is class-independent. Similarly, the mean service time at node 3 is 0.07. Jobs in class 1 leave the CPU and join class 2 with probability 0.1; jobs of class 2 leave the CPU and join

class 1 with probability 0.2. There are $N = 3$ jobs, which are initially allocated to class 1. However, note that since class switching is allowed, the total number of jobs in each class does not remain constant; however the total number of jobs does.

```

C = 2; K = 3;
S = [.01 .07 .10; \
      .05 .07 .10 ];
P = zeros(C,K,C,K);
P(1,1,1,2) = .7; P(1,1,1,3) = .2; P(1,1,2,1) = .1;
P(2,1,2,2) = .3; P(2,1,2,3) = .5; P(2,1,1,1) = .2;
P(1,2,1,1) = P(2,2,2,1) = 1;
P(1,3,1,1) = P(2,3,2,1) = 1;
N = [3 0];
[U R Q X] = qncmmva(N, S, P)
⇒
U =

    0.12609    0.61784    0.25218
    0.31522    0.13239    0.31522

R =

    0.014653    0.133148    0.163256
    0.073266    0.133148    0.163256

Q =

    0.18476    1.17519    0.41170
    0.46190    0.25183    0.51462

X =

    12.6089     8.8262     2.5218
     6.3044     1.8913     3.1522

```


6 References

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Version 3, 29 June 2007

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