# HILOGLINEAR

# The Model Minimum Configuration

Consider an  $I \times J \times K$  table. Let  $n_{ijk}$  be the observed frequency and  $m_{ijk}$  the expected frequency for cell (i, j, k). A simple way to construct a linear model in the natural logarithms of the expected cell frequencies is by analogy with analysis of variance (ANOVA) models:

$$L_{ijk} \equiv \log(m_{ijk}) = u + u_i^A + u_j^B + u_k^C + u_{ij}^{AB} + u_{ik}^{AC} + u_{jk}^{BC} + u_{ijk}^{ABC}$$
(1)

where  $1 \le i \le I$ ,  $1 \le j \le J$ , and  $1 \le k \le K$ . In general, each of the seven subscripted *u*-terms sums to zero over each lettered subscript.

It can be shown (Bishop et al. (1975), p. 65) that, under the commonly encountered sampling plans, the log-likelihood is

$$\Phi + Nu + \sum_{i} n_{i++} u_i^A + \sum_{j} n_{+j+} u_j^B + \sum_{k} n_{++k} u_k^C + \sum_{i,j} n_{ij+} u_{ij}^{AB} + \sum_{i,k} n_{i+k} u_{ik}^{AC} + \sum_{j,k} n_{+jk} u_{jk}^{BC} + \sum_{i,j,k} n_{ijk} u_{ijk}^{ABC}$$

where  $\Phi$  is independent of any parameters and *N* is total number of observations. Also, the *n*-terms adjacent to the unknown parameters are the sufficient statistics. The formulation of the above log likelihood is based on the saturated model (1). When we consider unsaturated models, terms drop out and those that remain give the sufficient statistics. For instance, if we assume that there is no three-factor effect, that is,  $u_{ijk}^{ABC} = 0$  for all *i*, *j*, and *k*, or more briefly  $u_{ijk} = 0$ , then

$$\log(m_{ijk}) = u + u_i^A + u_j^B + u_k^C + u_{ij}^{AB} + u_{ik}^{AC} + u_{jk}^{BC}$$
(2)

and  $n_{i++}, n_{+j+}, n_{++k}, n_{ij+}, n_{i+k}$  and  $n_{+jk}$  are the sufficient statistics for this reduced model. These statistics can be considered as *tables of sums configurations* and denoted by C with proper subscripts. For example,  $\{n_{ij+}\}$ is the configuration  $C_{12}$  and  $\{n_{++k}\}$  is the configuration  $C_3$ . Note that  $\{n_{i++}\}, \{n_{+j+}\}, \text{ and } \{n_{++k}\}$  can be obtained from  $\{n_{ij+}\}, \{n_{i+k}\}$  and  $\{n_{+jk}\}$ . We then call the last three configurations  $C_{12}, C_{13}$  and  $C_{23}$  minimal configurations or minimal statistics.

### Notation for Unlimited Number of Dimensions

To generalize results, we denote the complete set of subscripts by a single symbol  $\theta$ . Thus,  $n_{\theta}$  is the observed frequency in an elementary cell and  $w_{\theta}$  is the cell weight. We add a subscript to  $\theta$  to denote a reduced dimensionality so that  $n_{\theta i}$  is the observed sum in a cell of  $C_{\theta i}$ . We use the second subscript, *i*, solely to distinguish between different configurations.

### Iterative Proportional Fitting Procedure (IPFP)

We can obtain MLEs for the elementary cells under any hierarchical model by iterative fitting of the minimal sufficient configurations. To illustrate the algorithm, we consider model (2). The MLEs must fit the configurations  $C_{12}$ ,  $C_{13}$  and  $C_{23}$ . The basic IPFP chooses an initial table  $m_{ijk}^{(0)}$  and then sequentially adjusts the preliminary estimates to fit  $C_{12}$ ,  $C_{13}$ , and  $C_{23}$ . Fitting to  $C_{12}$  gives

$$\hat{m}_{ijk}^{(1)} = \hat{m}_{ijk}^{(0)} \frac{n_{ij+1}}{\hat{m}_{ij+1}^{(0)}}$$

Subsequent fitting to  $C_{13}$  gives

$$\hat{m}_{ijk}^{(2)} = \hat{m}_{ijk}^{(1)} \frac{n_{i+k}}{\hat{m}_{i+k}^{(1)}}$$

and similarly, after fitting  $C_{23}$  we have

$$\hat{m}_{ijk}^{(3)} = \hat{m}_{ijk}^{(2)} \frac{n_{+jk}}{\hat{m}_{+jk}^{(2)}}$$

We repeat this three-step cycle until convergence to the desired accuracy is attained. The extension of the above procedure to the general procedure for fitting *s* configurations is straightforward. Let the minimal configurations be  $C_{\theta i}$  for i = 1, 2, ..., s, with cell entries  $n_{\theta i}$ , respectively. The procedure is as follows:

#### **Initial Cell Estimates**

To start the iterations, if CWEIGHT is not specified, set

$$m_{\theta}^{(0)} = \begin{cases} 1 & \text{if } n_{\theta} \ge 0\\ 0 & \text{otherwise} \end{cases}$$

If CWEIGHT is specified, set

$$m_{\theta}^{(0)} = \begin{cases} 1 & \text{if } CWEIGHT \ge 1 \\ 0 & \text{if } CWEIGHT \le 0 \\ CWEIGHT & \text{if } 0 < CWEIGHT < 1 \end{cases}$$

#### Intermediate Computations

After obtaining the initial cell estimates, the algorithm proceeds to fit each of these configurations in turn. After r cycles, the relations are

$$\hat{m}_{\theta}^{(sr+i)} = \hat{m}_{\theta}^{(sr+i-1)} \frac{n_{\theta_i}}{\hat{m}_{\theta_i}^{(sr+i-1)}} \quad \text{for } 1 \le i \le s; r \ge 0$$

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#### **Convergence Criteria**

The computations stop either when a complete cycle, which consists of *s* steps, does not cause any cell to change by more than a preset amount  $\varepsilon$ ; that is,

$$\left| \hat{m}_{\theta}^{(sr)} - \hat{m}_{\theta}^{(sr-s)} \right| < \varepsilon$$
 for all  $\theta$ 

or the number of cycles is larger than a preset integer max. Both  $\varepsilon$  and max can be specified. The default for  $\varepsilon$  is

$$\varepsilon = \max_{\theta} \left\{ 0.25; \frac{n_{\theta} w_{\theta}}{1000} \right\}$$

and the default for max is 20.

# **Goodness of Fit Tests**

The Pearson chi-square statistic is

$$\chi^2 = \sum_{\theta} \frac{\left(n_{\theta} - \hat{m}_{\theta}\right)^2}{\hat{m}_{\theta}}$$

and the likelihood-ratio chi-square statistic is

$$L^2 = 2\sum_{\theta} n_{\theta} \ln(n_{\theta}/\hat{m}_{\theta})$$

where the first summation is done over the cells with nonzero estimated cell frequencies while the second summation is done over cells with positive observed and estimated cell frequencies. The degrees of freedom for the above two statistics are computed as follows:

#### Adjusted Degrees of Freedom

Let  $T_c$  be the total number of the cells and P the number of parameters in the model. Also, let  $z_c$  be the number of cells such that  $\hat{m}_{\theta} = 0$ . The adjusted degrees of freedom is

adjusted df =  $T_c - P - z_c$ 

Unadjusted Degrees of Freedom

unadjusted df =  $T_c - P$ 

### Parameter Estimates and Standard Errors

If a saturated model is fitted and neither  $n_{\theta} + \delta$  nor  $w_{\theta}$  is equal to zero for all cells, then the parameter estimates and their standard errors will be computed. Each estimate of the parameters in the saturated model can be expressed as a linear combination of the logarithms of the observed cell frequencies plus user-specified  $\delta$ , where the coefficients used in the linear combination add to zero. We discuss the rule of obtaining the coefficients. Consider, in general case, a  $J_1 \times J_2 \times \ldots \times J_M$  frequency table with defining variables  $X_1, \ldots, X_M$ . Let  $u_{j_{s1}, \ldots, j_{sL}}^{X_{s1}, \ldots, X_{sL}}$  denote an *L*-term interaction involving  $X_{s1}, \ldots, X_{sL}$  at level  $j_{s1}, \ldots, j_{sL}$  respectively. Denote *A* as a vector that is constructed in the way that its nonzero components correspond to the variables in the parameter to be estimated and are set to the level of the variable. Let  $C_{j_1, \ldots, j_M}$  be a *M*-dim vector with components equal to cell IDs. That is,

$$C_{j_1,...,j_M} = (j_1,...,j_M); \quad 1 \le j_1 \le J_1, \quad 1 \le i \le M$$

The coefficient  $\beta_{j_1,...,j_M}$  is determined through the comparison of the components of *A* and  $C_{j_1,...,j_M}$ . Let *s* be the number of nonzero components of *A* that do not match (equal) the corresponding components of  $C_{j_1,...,j_M}$ . Also, let matching occur at component  $i_1,...,i_k$ . Then the coefficient for cell  $(j_1,...,j_M)$  is

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$$\boldsymbol{\beta}_{j_1,\ldots,j_M} = (-1)^s (J_{i_1} - 1) \times \ldots \times (J_{i_k} - 1)$$

The estimate  $\hat{u}_{j_{s1},\ldots,j_{sL}}^{X_{s1},\ldots,X_{sL}}$  of  $u_{j_{s1},\ldots,j_{sL}}^{X_{s1},\ldots,X_{sL}}$  is then

$$\hat{u}_{j_{s1},...,j_{sL}}^{X_{s1},...,X_{sL}} = \sum_{j_{1},...,j_{M}} \beta_{j_{1},...,j_{M}} \ln(n_{j_{1},...,j_{M}} + \delta)$$
(3)

The large-sample variance of the estimate (3) is

$$\sum_{j_1,...,j_M} \beta_{j_1,...,j_M}^2 \left[ \ln \left( n_{j_1,...,j_M} + \delta \right) \right]^{-1}$$
(4)

For a large sample, estimate (3) approximately follows a normal distribution with mean  $u_{j_{s1},...,j_{sL}}^{X_{s1},...,X_{sL}}$  and variance (4) if the sampling model follows a Poisson, multinomial, or product-multinomial distribution. The confidence interval for the parameter can be computed based on the asymptotic normality.

### **Raw Residuals and Standardized Residuals**

Two different residuals are computed:

**Raw Residual** 

raw residual  $= n_{\theta} - \hat{m}_{\theta}$ 

Standardized Residual

standardized residual 
$$= (n_{\theta} - \hat{m}_{\theta}) / \sqrt{\hat{m}_{\theta}}$$

where  $\hat{m}_{\theta}$  must be greater than 0.

### Partial Associations and Partial Chi-squares

Partial associations of effects can be requested when a saturated model is specified. Let  $\chi^2(k)$  be the chi-square for the model that contains the effects up to and including the *k*-interaction terms. The test of the significance of the *k*th-order interaction can be based on

$$\chi^2(k-1)-\chi^2(k)$$

Degrees of freedom are obtained by subtracting the degrees of freedom for the corresponding models.

### Model Selection Via Backward Elimination

The selection process starts with the model specified (either via DESIGN or MAXORDER subcommand). The partial chi-square is calculated for every term in the generating class. Any term with zero partial chi-square is deleted, then the effect with the largest observed significance level for the change in chi-square is deleted, provided the significance level is larger than 0.05, the default. With the removal of a highest-order term, a new model with new generating class is generated. The above process of removing a term is repeated for the new model and is continued until no remaining terms in the model can be deleted.

# References

- Bishop, Y. M. M., Fienberg, S. E., and Holland, P. W. 1975. *Discrete multivariate analysis: Theory and practice*. Cambridge, Mass.: MIT Press.
- Fienberg, S. E. 1977. The analysis of cross-classified categorical data. Cambridge, Mass.: The MIT Press.