NLR

NLR produces the least square estimates of the parameters for models that are not linear in their parameters. Unlike in other procedures, the weight function is not treated as a case replicate in NLR.

Model

Consider the model

 $f = f(\mathbf{x}, \Theta)$

where Θ is a $p \times 1$ parameter vector, **x** is a vector of independent variables, and *f* is a function of **x** and Θ .

Goal

Find the least square estimate Θ^* of Θ such that Θ^* minimizes the objective function

$$F(\Theta) = \mathbf{R}' \mathbf{W} \mathbf{R} \tag{1}$$

where

$$\mathbf{R}' = (R_1, \dots, R_n)$$

$$R_i = y_i - f_i$$

$$f_i = f(x_i, \Theta^*), \quad i = 1, \dots, n$$

$$\mathbf{W} = \text{Diag}(W_1, \dots, W_n)$$

and *n* is the number of cases. For case *i*, y_i is the observed dependent variable, x_i is the vector of observed independent variables, W_i is the weight function which can be a function of Θ .

The gradient of F at Θ_i is defined as

$$\nabla F = 2\mathbf{J}'_{j}\mathbf{W}\mathbf{R}$$

where $\mathbf{J}_{.j}$ is the *j*th column of the $n \times p$ Jacobian matrix \mathbf{J} whose (i, j) th element J_{ij} is defined by

$$J_{ij} = \frac{R_i}{2W_i} \frac{\partial W_i}{\partial \Theta_j} - \frac{\partial f_i}{\partial \Theta_j}$$

Estimation

The modified Levenberg-Marquardt algorithm that was proposed by Moré (1977) and is contained in MINPACK is used in NLR to solve equation (1).

Given an initial value $\Theta^{(0)}$ for Θ , the algorithm is as follows:

At stage k + 1, k = 0, 1, 2, ...

• Compute

$$f_i^{(k)} = f_i(\Theta^{(F)}), \ R_i^{(k)} = y_i - f_i^{(k)}, \ F_k = F(\Theta^{(k)}), \text{ and } J^{(k)} = J(\Theta^{(k)})$$

• Choose an appropriate non-negative scalar such that

$$F\left(\Theta^{k} + h_{k}\right) < F_{k}$$

where

$$h_k = -\left(\mathbf{J}^{(k)'}\mathbf{J}^{(k)} + \boldsymbol{\alpha}_k \mathbf{I}\right)^{-1} \mathbf{J}^{(k)'}\mathbf{R}^{(k)}$$

• Set

$$\Theta^{(k+1)} = \Theta^{(k)} + h_k$$

and compute $\mathbf{J}^{(k+1)}, \mathbf{R}^{(k+1)}, \mathbf{W}^{(k+1)}$, and F_{k+1} .

- Check the following conditions:
 - (1) $1 (F_{k-1}/F_k) < \varepsilon_1(SSCON)$
 - (2) For every element of h_k ,

$$\left|h_{ki} \middle/ \Theta_i^{(k)}\right| < \varepsilon_2(PCON)$$

- (3) $k+1 \ge ITER$ (maximum number of iterations)
- (4) For every parameter Θ_j , the gradient of *F* at Θ_j , ∇F_j , is evaluated at $\Theta^{(k+1)}$ by checking

$$\left|r_{j}^{\left(k+1\right)}\right| < \varepsilon_{2}(RCON)$$

where $r_j^{(k+1)}$ is the correlation between the *j*th column $\mathbf{J}_j^{(k+1)}$ of $\mathbf{J}^{(k+1)}$ and $\mathbf{W}^{(k+1)}\mathbf{R}^{(k+1)}$.

If any of these four conditions is satisfied, the algorithm will stop. Then the final parameter estimate Θ^{\ast}

$$\Theta^* = \Theta^{(k+1)}$$

and the termination reason is reported. Otherwise, iteration continues.

Statistics

When iteration terminates, the following statistics are printed.

Parameter Estimates and Standard Errors

The asymptotic standard error of Θ_j^* is estimated by the square root of the *j*th diagonal element a_{jj} of **A**, where

$$\mathbf{A} = \frac{F(\Theta^*)}{n-p} \left(\mathbf{J}^{*'} \mathbf{W}^* \mathbf{J}^* \right)^{-1}$$

and J^* and W^* are the Jacobian matrix J and weight function W evaluated at Θ^* , respectively.

Asymptotic 95% Confidence Interval for Θ_j

$$\Theta_j^* \pm t (0.975, n-p) a_{ii}$$

Asymptotic Correlation Matrix of the Parameter Estimates

$$\mathbf{C} = \mathbf{D}^{-1/2} \mathbf{A} \mathbf{D}^{-1/2}$$

where

$$\mathbf{D} = \operatorname{Diag}\left(a_{11,\ldots,} a_{pp}\right)$$

and a_{ii} is the *i*th diagonal element of A.

4 NLR

Source	df	Sum of Squares
Residual	n-p	$F(\Theta^*)$
Regression	p	$SS_{\text{uncorrected}} - F(\Theta^*)$
Uncorrected Total	n	SS _{uncorrected}
Corrected Total	n-1	$SS_{\text{uncorrected}} - \overline{y}^2 \sum_{i=1}^n W_i (\Theta^*)$

where

$$SS_{\text{uncorrected}} = \sum_{i=1}^{n} W_i(Q^*) y_i^2$$

$$\overline{y} = \left(\sum_{i=1}^{n} W_i(Q^*) y_i\right) / \left(\sum_{i=1}^{n} W_i(Q^*)\right)$$

References

Moré, J. J. 1977. The Levenberg-Marquardt algorithm: implementation and theory in numerical analysis. In: *Lecture Notes in Mathematics* 630, G. A. Watson, ed. Berlin: Springer-Verlag. 105–116.