



IBM Software Group

# Safety Analysis Profile for the UML

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# What is Safety?

- Safety is freedom from accidents or losses.
- Safety is not reliability!
  - ▶ Reliability is the probability that a system will perform its intended function satisfactorily.
- Safety is not security!
  - ▶ Security is protection or defense against attack, interference, or espionage.



# Safety-Related Concepts

- *Accident* is a loss of some kind, such as injury, death, or equipment damage
- *Risk* is a combination of the likelihood of an accident and its severity:  
$$risk = p(a) * s(a)$$
- *Hazard* is a set of conditions and/or events that leads to an accident.



# Safety-Related Concepts

- A failure is the nonperformance of a system or component, a random fault
  - ▶ A random failure is one that can be estimated from a pdf,
  - ▶ Failures are events
  - ▶ e.g., a component failure
- An error is a systematic fault
  - ▶ A systematic fault is an design error
  - ▶ Errors are states or conditions
  - ▶ e.g., a software bug
- A fault is either a failure or an error



# Hazard Analysis

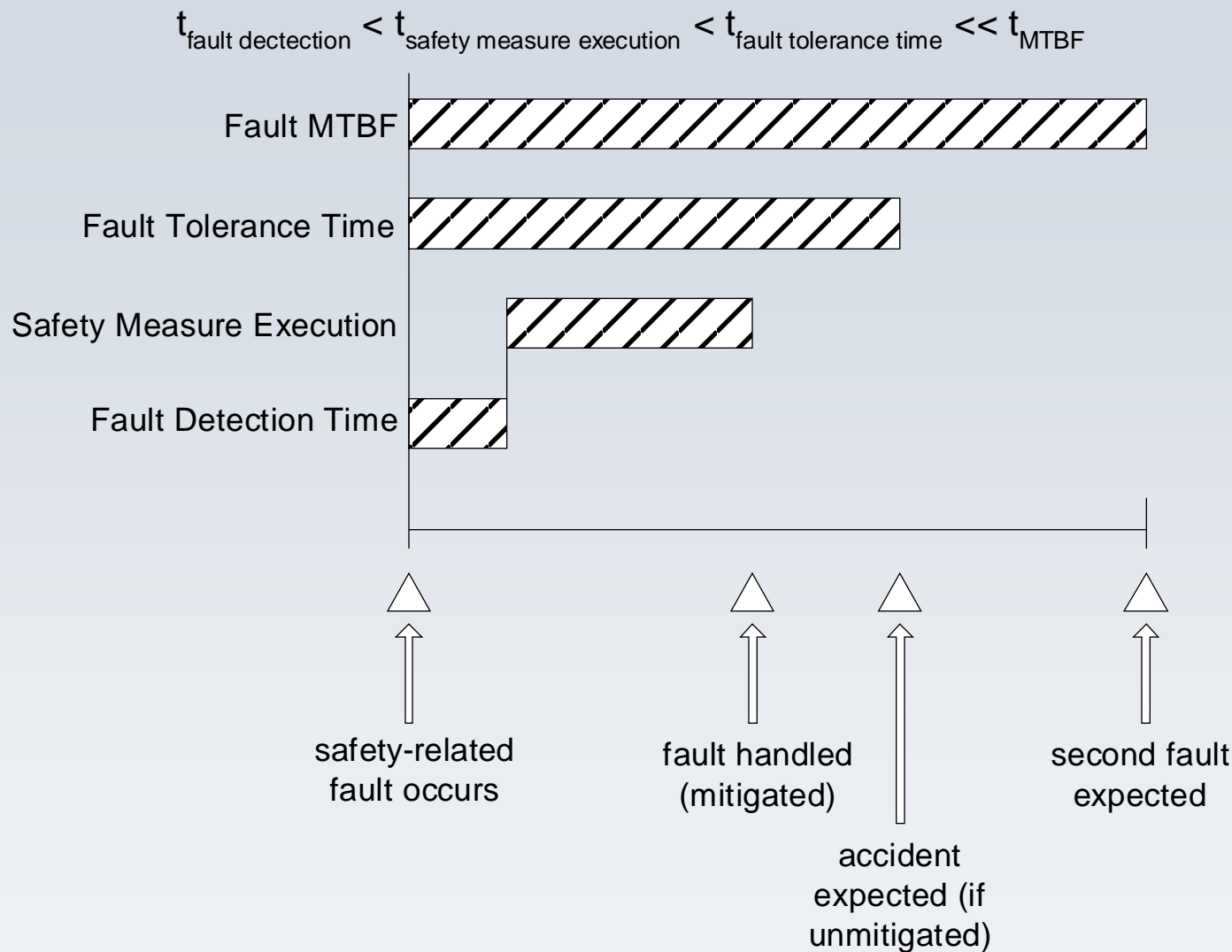
Hazard Analysis											
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**How to use this spreadsheet**

The hazard analysis spreadsheet computes risk = severity \* likelihood, where severity is a ranking of 1 (very low) to 10 (very high)  
 Note that various safety standards may use a different range for severity. Likelihood is the probability of occurrence of the hazard in the life expectancy of the product (0.0 to 1.0). Risk is computed from these values.  
 Exposure time is computed as the sum of the Detection Time + Action Time. For a safe system this value must be less than the Tolerance time  
 Is Safe is computed as = Exposure Time <= Tolerance Time  
 Note that the spreadsheet assumes that the time units are the same for an entire row.

Hazard	Fault	Severity (1 (low) - 10 (high) )	Likelihood (0.0 - 1.0)	Computed Risk	Time units	Tolerance Time	Detection Time	Control Measure	Control Action Time	Exposure Time	Is Safe?
Hypoventilation	Breathing tube disconnect	10	0.2	2	minutes	5	0.5	Blood oxygen sensor	2	2.5	TRUE
Hypoventilation	Ventilator timer error	10	0.2	2	minutes	5	0.5	Independent pressure sensor with alarming	2	2.5	TRUE
Hypoventilation	Gas Supply Failure	10	0.4	4	minutes	5	0.05	Ventilator incoming gas pressure sensor	2	2.05	TRUE
Hypoxia	Gas mixer failure	10	0.6	6	minutes	5	0.05	Inspiratory limb O2 sensor	2	2.05	TRUE
Hyperventilation	Ventilator timer error	8	0.1	0.8	minutes	20	0.5	Blood oxygen sensor	2	2.5	TRUE
Overpressure	Pump failure; expiratory tube blockage	10	0.3	3	ms	200	10	Secondary pressure sensor with auto release valve	5	15	TRUE

# Safety Fault Timeline

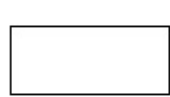


# Safety Measures

- Safety measures do one of the following:
  - ▶ Remove the hazard
  - ▶ Reduce the risk, either by
    - Reducing the likelihood of the accident
    - Reducing the severity of the accident
  - ▶ Identify the hazard to supervisory personnel so that they can handle it within the fault tolerance time
- The purpose of the safety measure is to avoid accident or loss



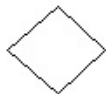
# Fault Tree Analysis (FTA)



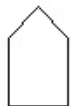
An event that results from a combination of events through a logic gate



A basic fault event that requires no further development



An "undeveloped fault" event, not elaborated because the event is trivial or more decomposition is not necessary



An event that is expected to occur normally



NOT Gate



A condition that must be present to produce the output of a gate



Transfer



AND gate



NAND Gate



OR Gate



NOR Gate



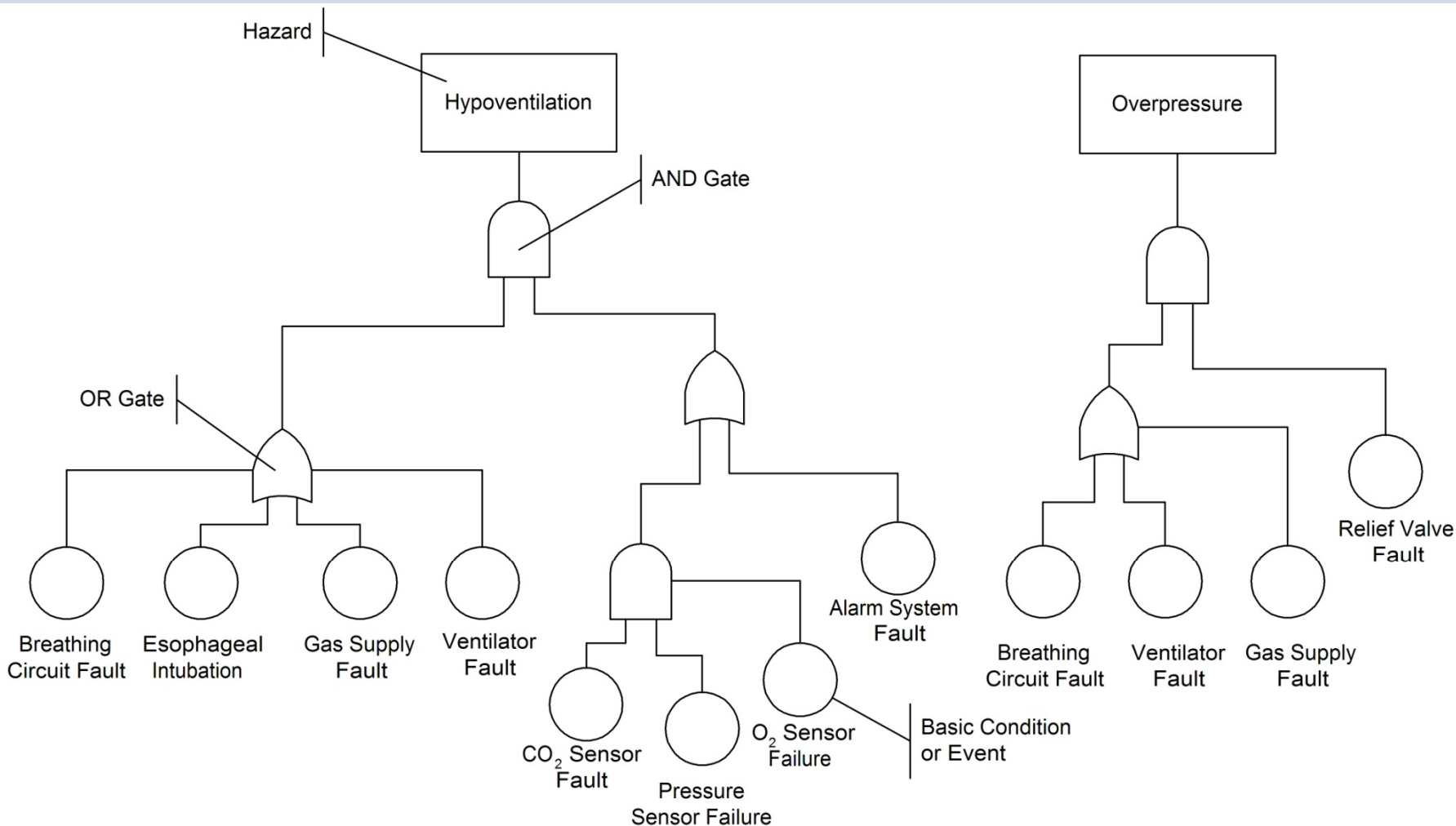
XOR Gate



**Fault Tree Analysis determines what combinations of conditions or events are necessary for a hazard condition to occur**

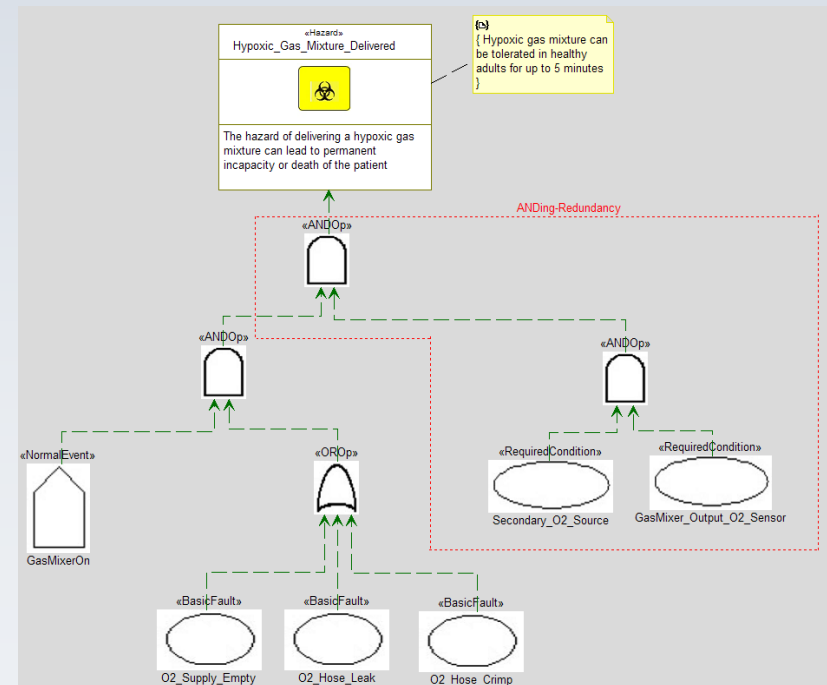
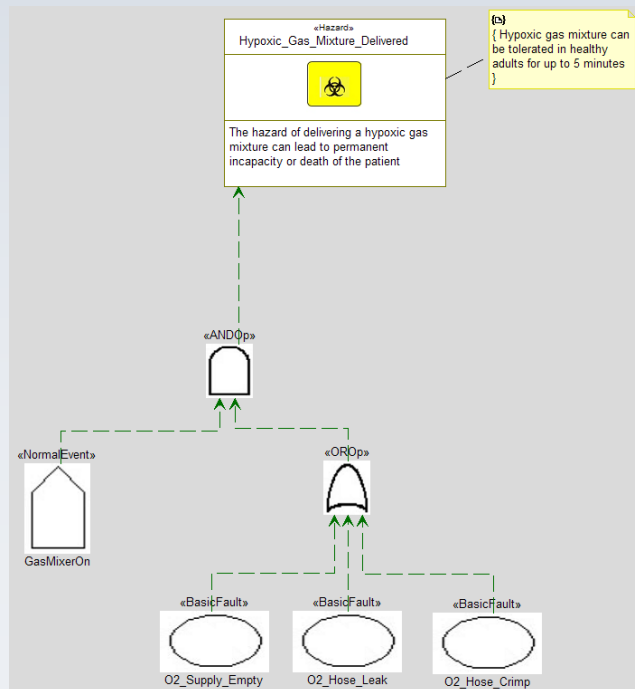


# Example Fault Tree Analysis



# Design Redundancy for Safety

- The key to safe systems is to analyze the system and to identify the conditions and events that can lead to hazards
- Fault Tree Analysis (FTA) determines what logical combination of events and conditions lead to faults
- By adding “ANDing-redundancy”, architectural redundancy can be added

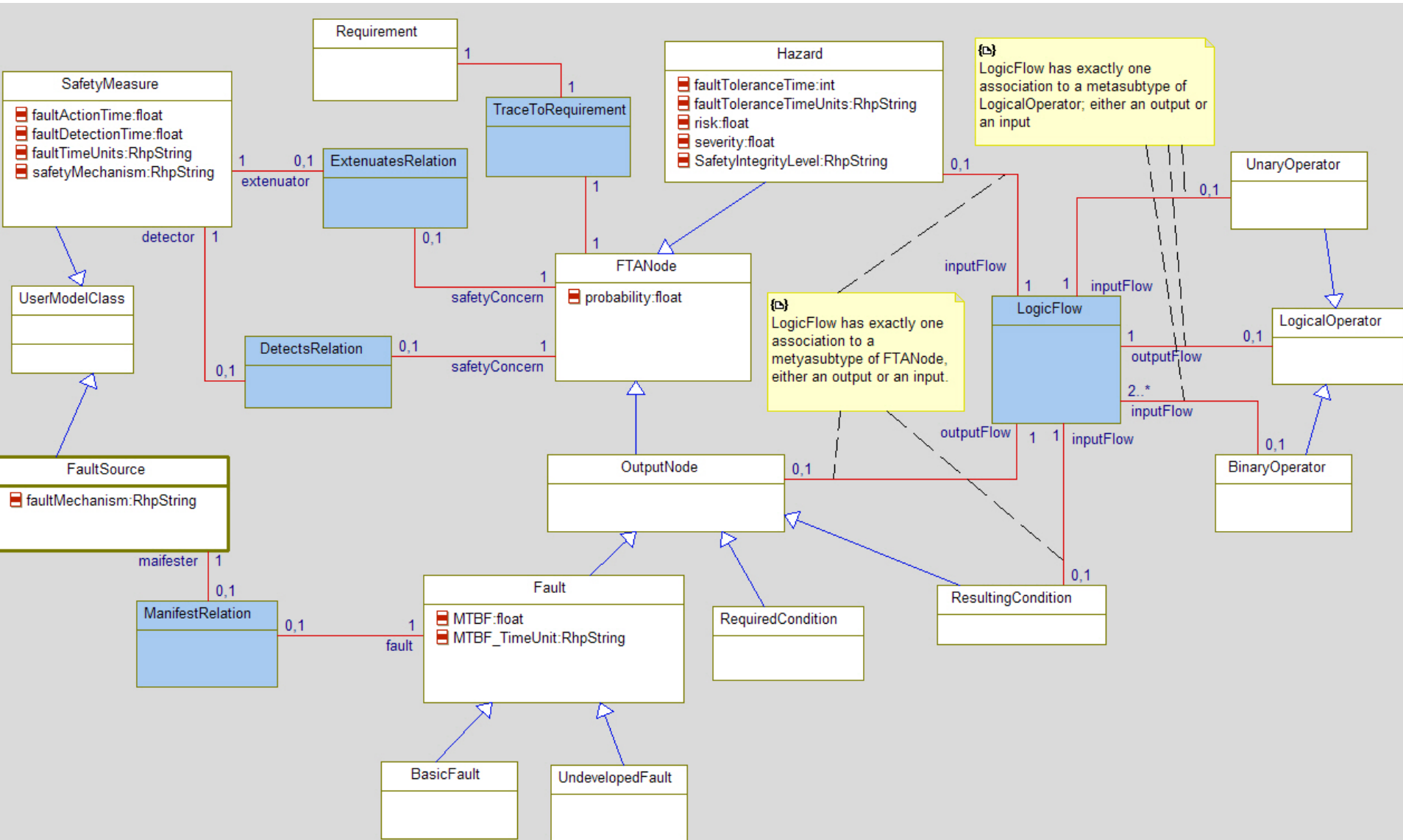


# Safety Metamodel

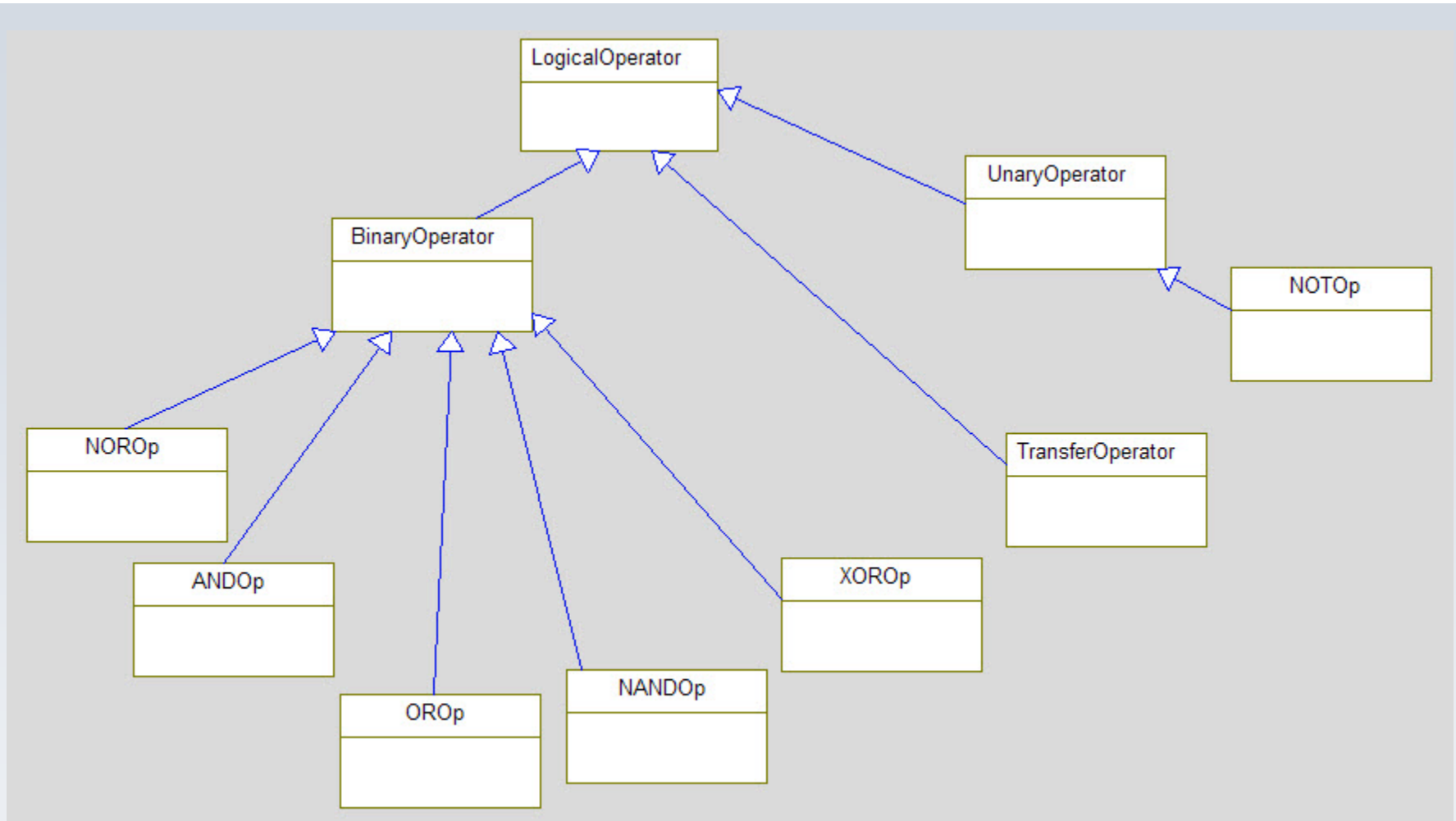
- The Safety Metamodel identifies and characterizes the important concepts (and their metadata) and their relations
- The metamodel serves as a blueprint for stereotypes in the profile



# Safety Metamodel



# Safety Metamodel (Operators)



# Metaclasses

- FTA Node
  - ▶ Description: An abstract metaclass providing the Probability metaattribute and various relations
  - ▶ Base metaclass: Class
  - ▶ Metadata
    - Probability [0.0 .. 1.0]
- Fault
  - ▶ Description: An abstract metaclass representing a non-conformant behavior of some kind
  - ▶ Base metaclass: FTA Node
  - ▶ Metadata
    - MTBF
    - MTBF Time Units
- Basic Fault
  - ▶ Description: A fault that cannot be further decomposed
  - ▶ Base metaclass: Fault
- Undeveloped Fault
  - ▶ Description: A fault that may be, but not is, further decomposed
  - ▶ Base metaclass: Fault



# Metaclasses

- Required Condition
  - ▶ Description: A condition required as an input to an operator for a TRUE output
  - ▶ Base metaclass: FTANode
- Resulting Condition
  - ▶ Description: A condition resulting from the combination of other conditions and faults
  - ▶ Base metaclass: FTA Node
- Hazard
  - ▶ Description: A condition that inevitably leads to an accident or loss
  - ▶ Base metaclass: FTA Node
  - ▶ Metadata
    - Fault Tolerance Time
    - Fault Tolerance Time Units
    - Risk
    - Severity
    - Safety Integrity Level (SIL)



# Metaclasses

- Requirement
  - ▶ Description: A capability or condition that must be satisfied by a system
  - ▶ Base metaclass: Class (from SysML)
  - ▶ Metadata
    - Text
    - Id
- Fault Source
  - ▶ Description: A model element that can manifest a fault
  - ▶ Base metaclass: Class
  - ▶ Metadata
    - Fault mechanism: string
- Safety Measure
  - ▶ Description: A model element that can detect or extenuate a fault
  - ▶ Base Metaclass: Class
  - ▶ Metadata
    - Fault action time
    - Fault detection time
    - Fault time units
    - Safety mechanism: string





# Metaclasses

- Logic Flow
  - ▶ Description: A “carrier” of boolean value
  - ▶ Base metaclass: Information flow
- Logical Operator
  - ▶ Description: An abstract metaclass for a function that performs logic on its inputs
  - ▶ Base metaclass: Class
- Unary Operator
  - ▶ Description: A logical operator with a single input and output
  - ▶ Base metaclass: Logical Operator
- Binary Operator
  - ▶ Description: A logical operator that takes two (or more) inputs to produce a single output
  - ▶ Base metaclass: Logical Operator
- Transfer Operator
  - ▶ Description: A binary operator whose purpose is to “connect” logic across multiple diagrams
  - ▶ Base metaclass: Binary operator

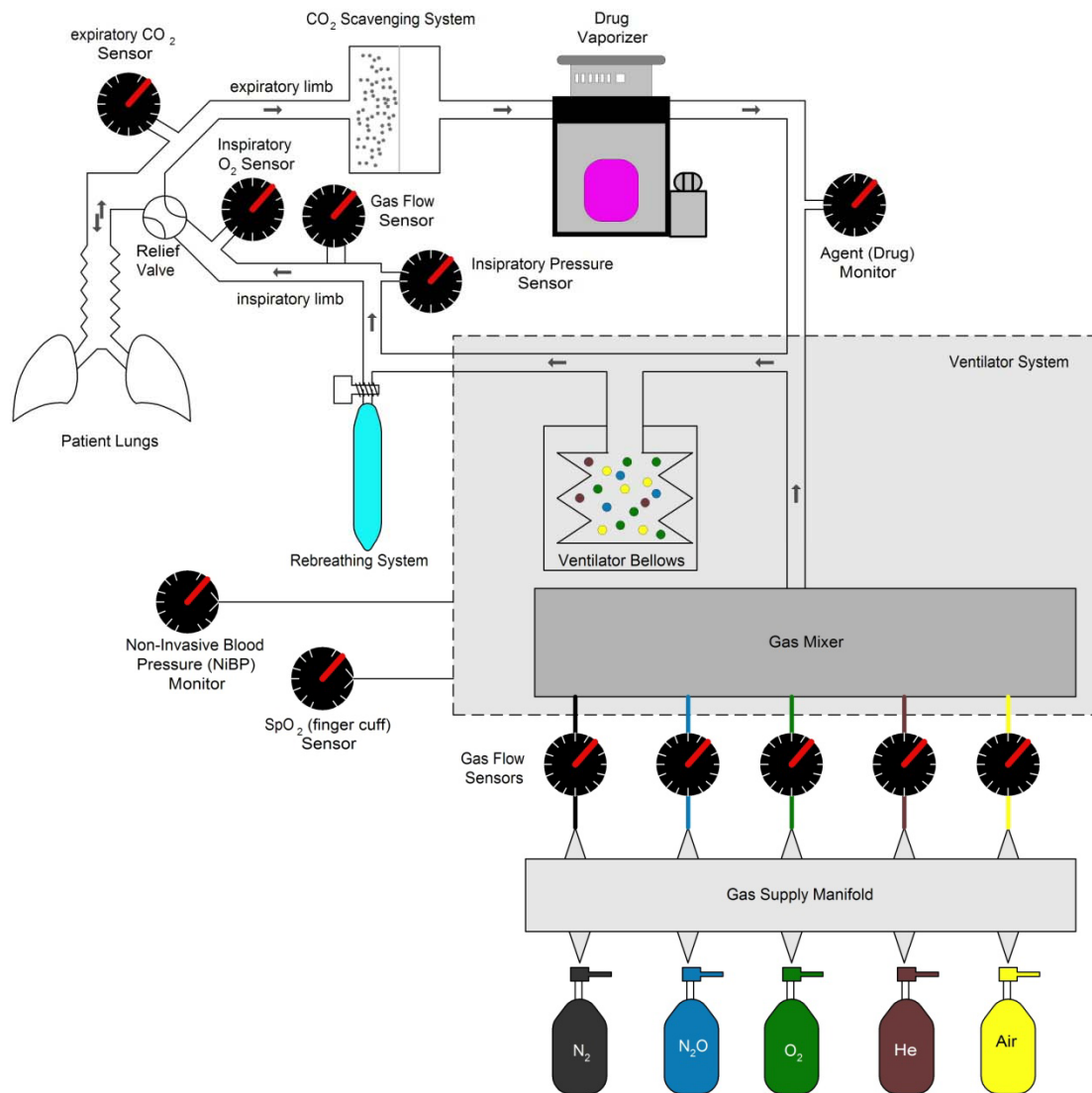


# Metaclasses

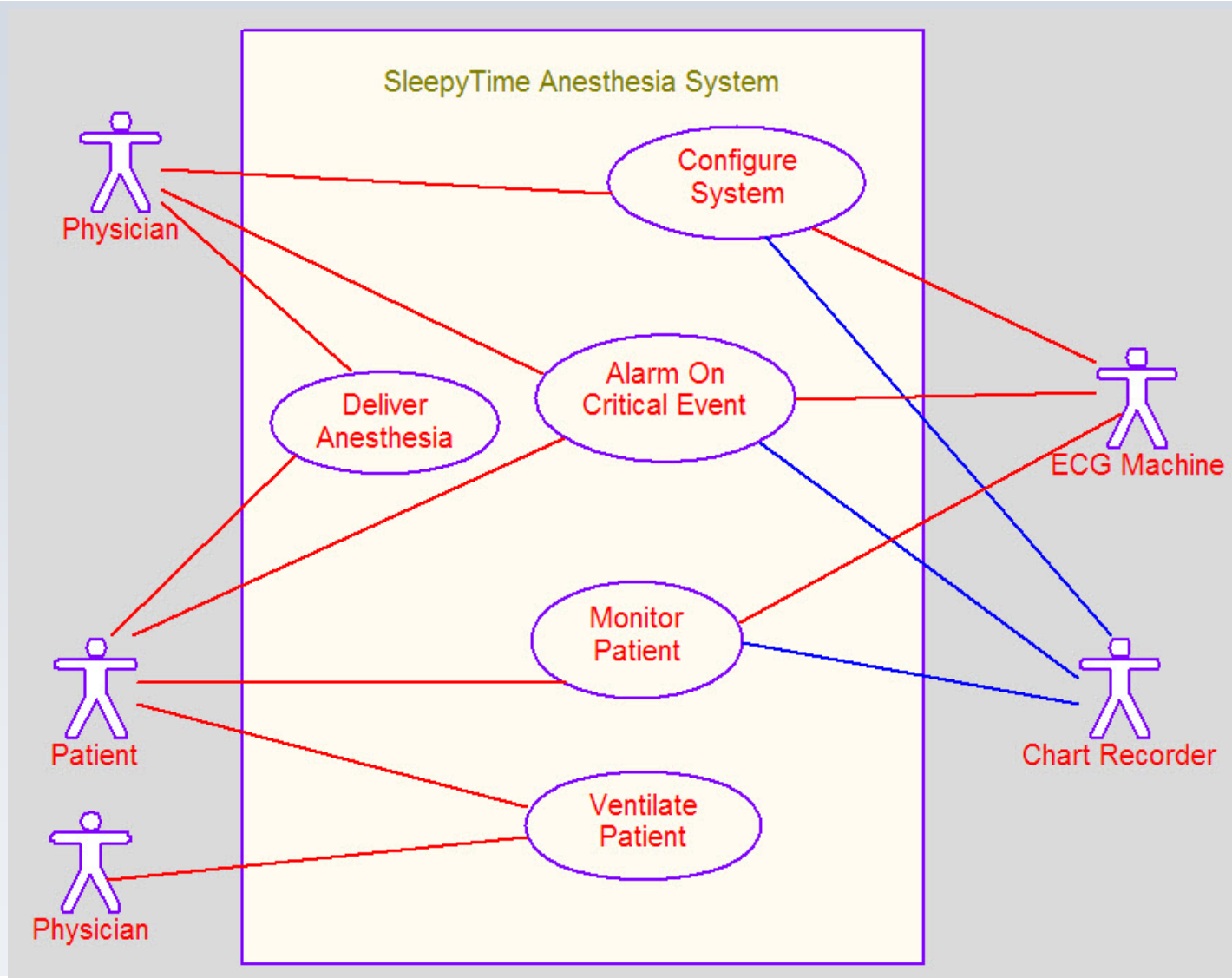
- TraceToReq
  - ▶ Description: A relation from an FTA node to a requirement
  - ▶ Base metaclass: Dependency
- ManifestsRelation
  - ▶ Description: A relation from a Fault to a Fault Source or Class
  - ▶ Base metaclass: Dependency
- DetectsRelation
  - ▶ Description: A relation from an FTA node to a Safety Measure that detects a fault
  - ▶ Base metaclass: Dependency
- ExtenuatesRelation
  - ▶ Description: A relation from an FTA node to a Safety Measure that removes, mitigates, or extenuates a fault
  - ▶ Base metaclass: Dependency



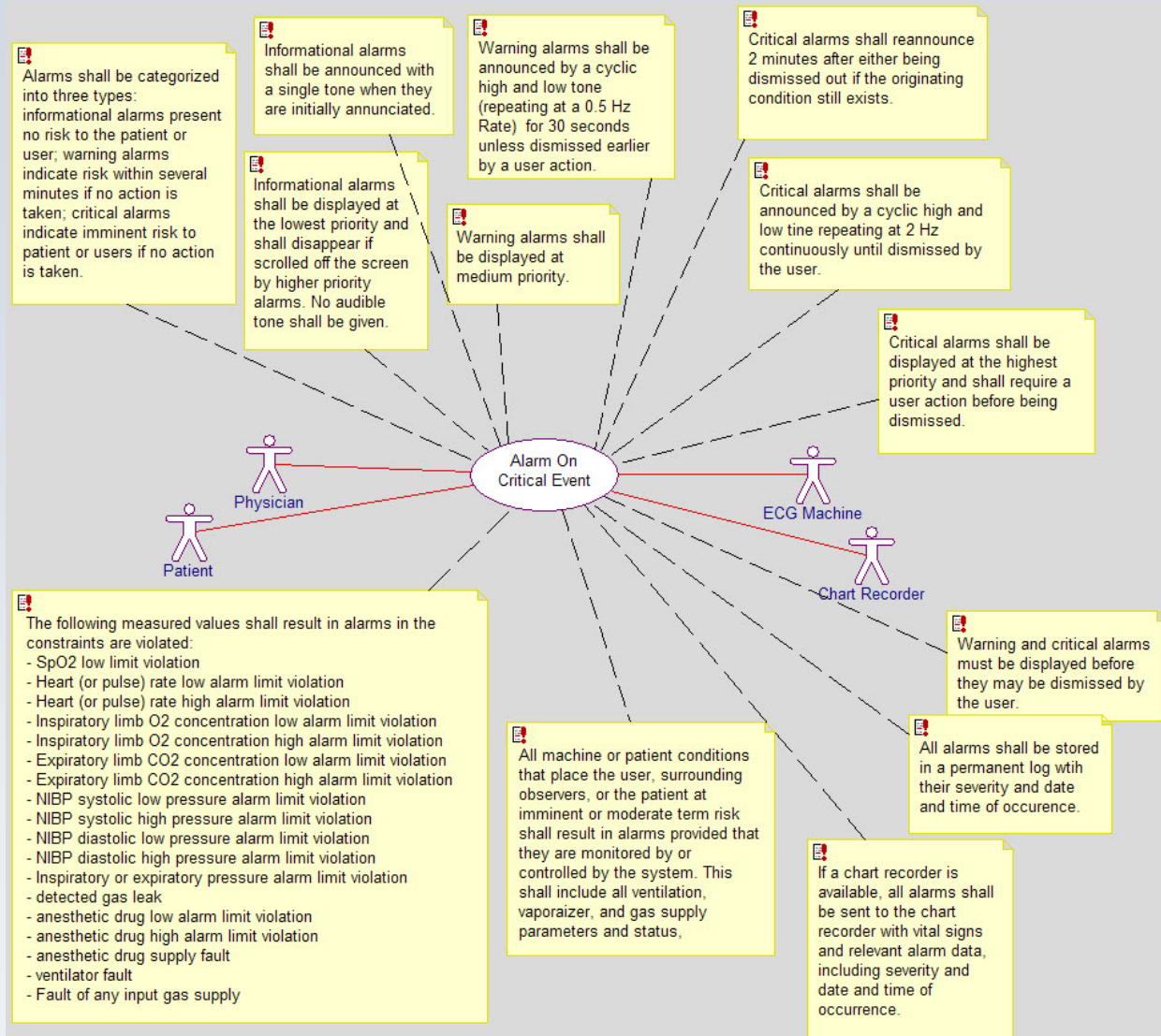
# Safety Example: SleepyTime Anesthesia Machine



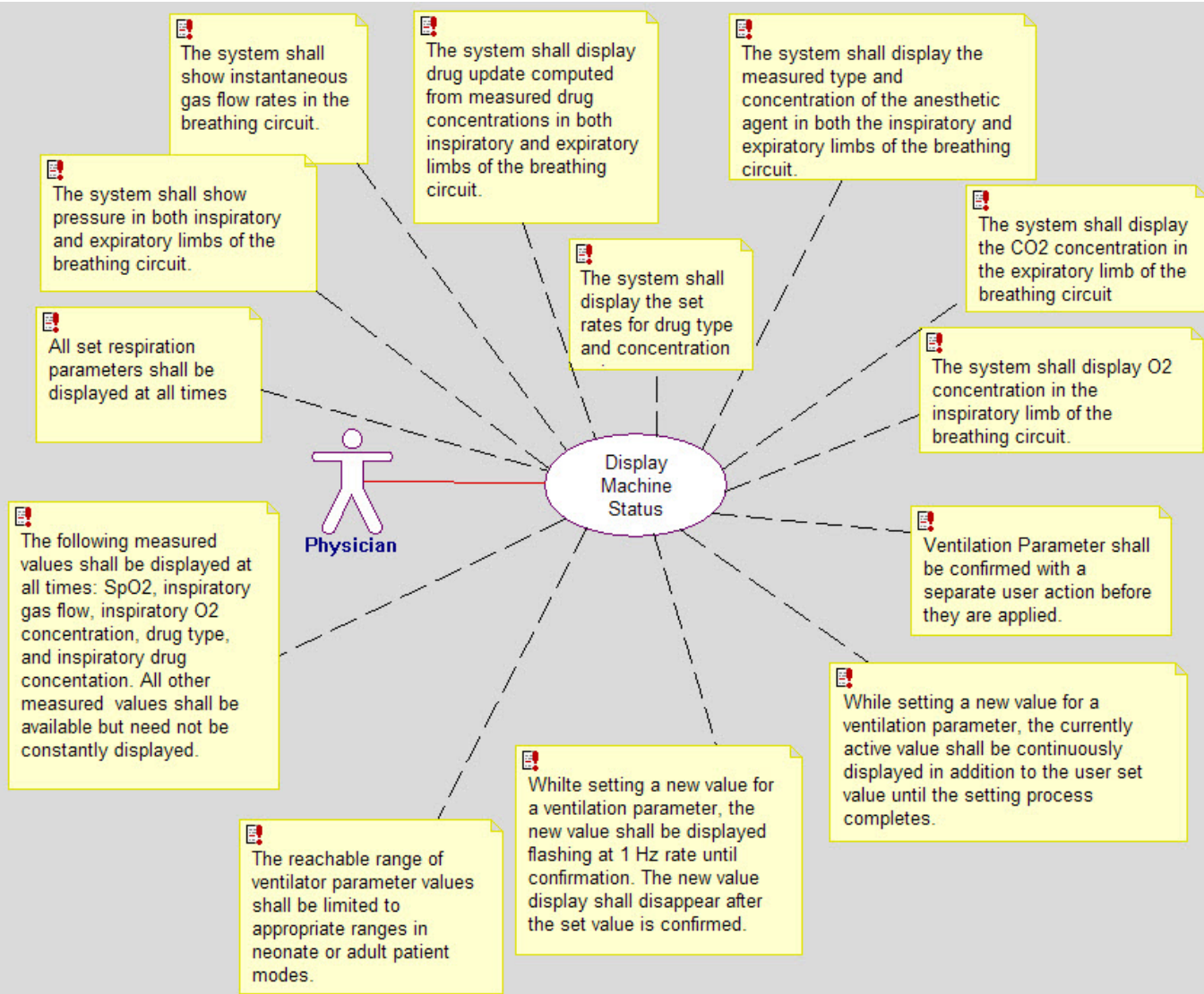
# System Use Case Model



# Alarm Requirements

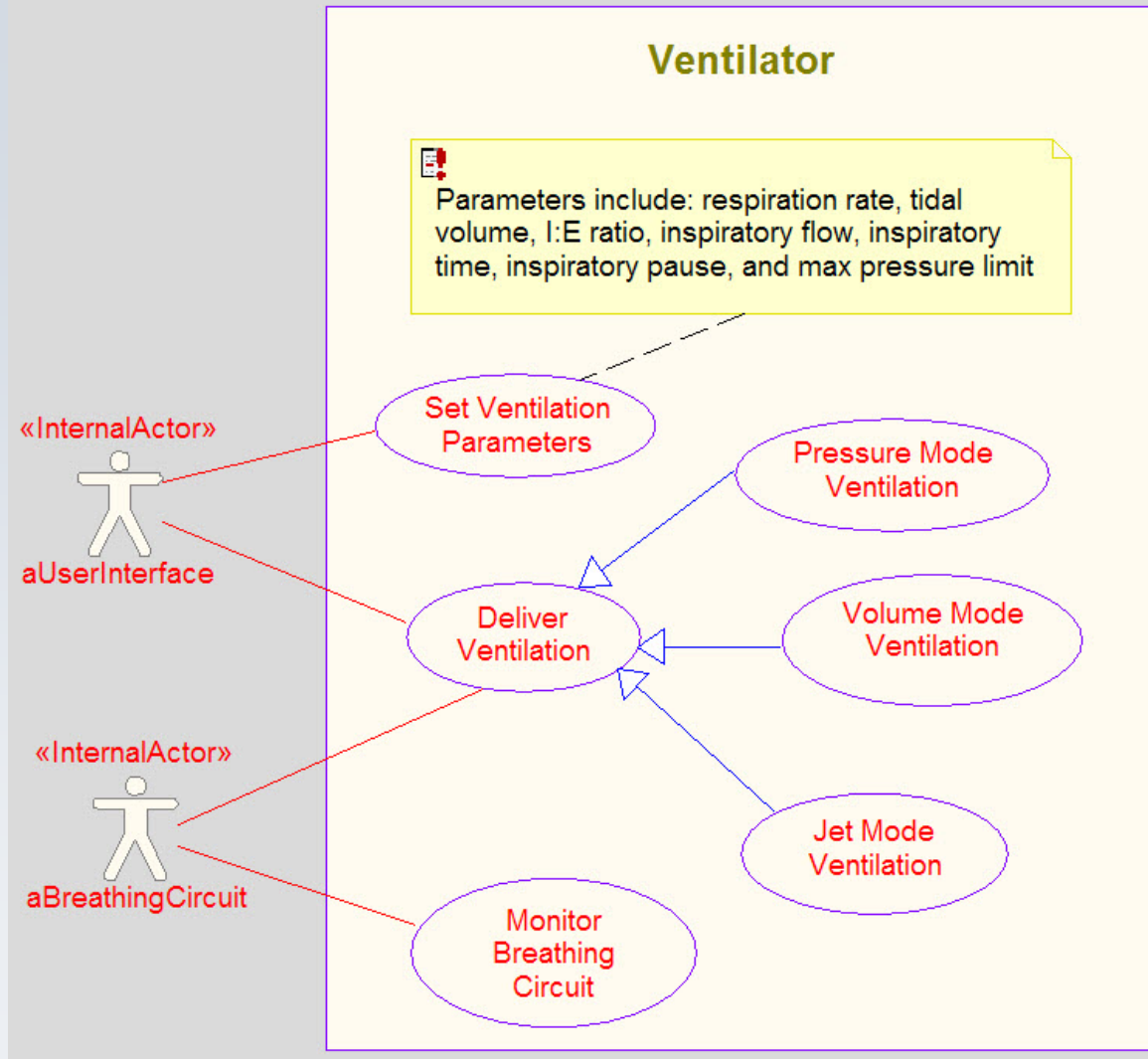


# Display Requirements

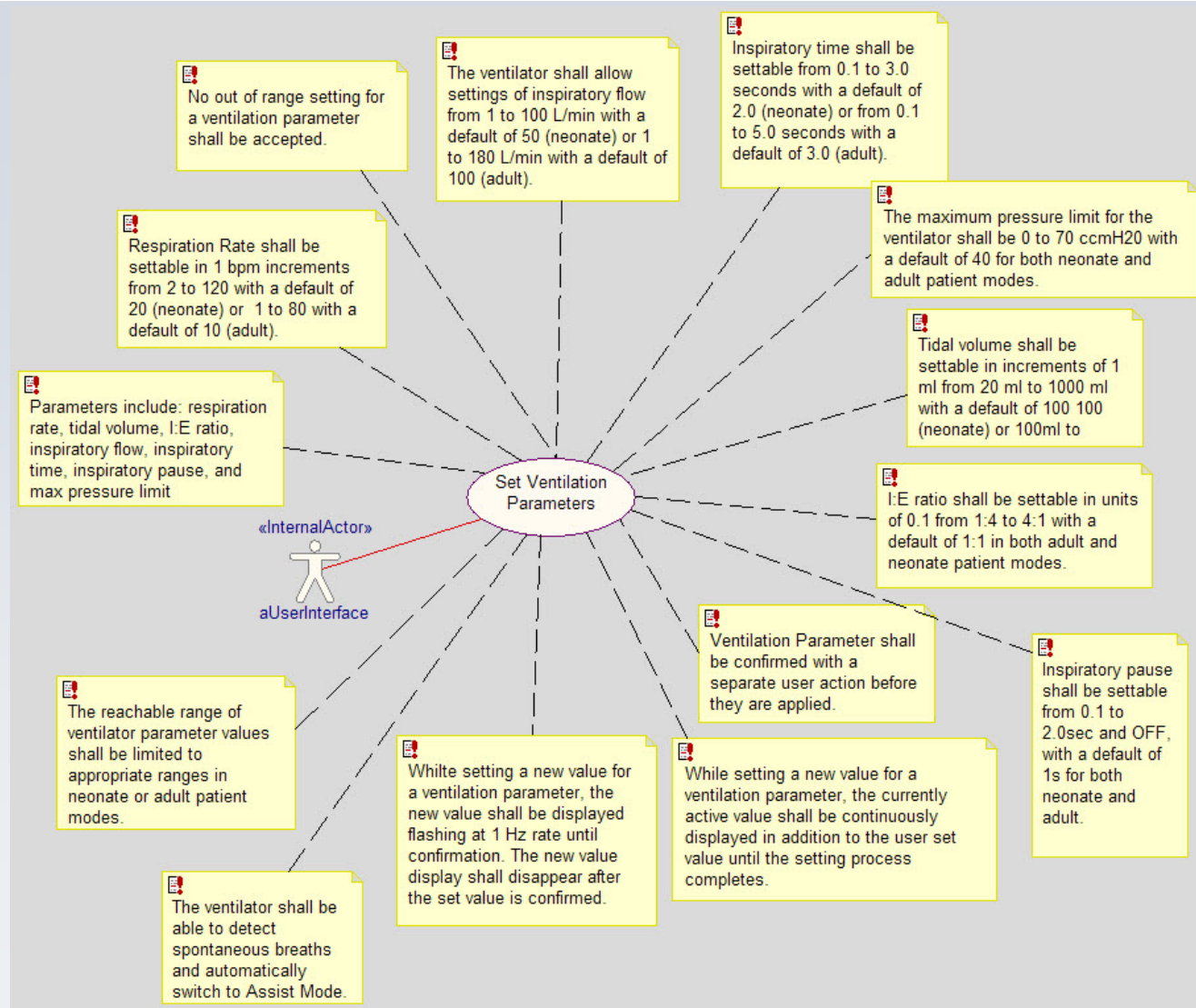




# Ventilator Subsystem Use Case Model



# Ventilator Requirements



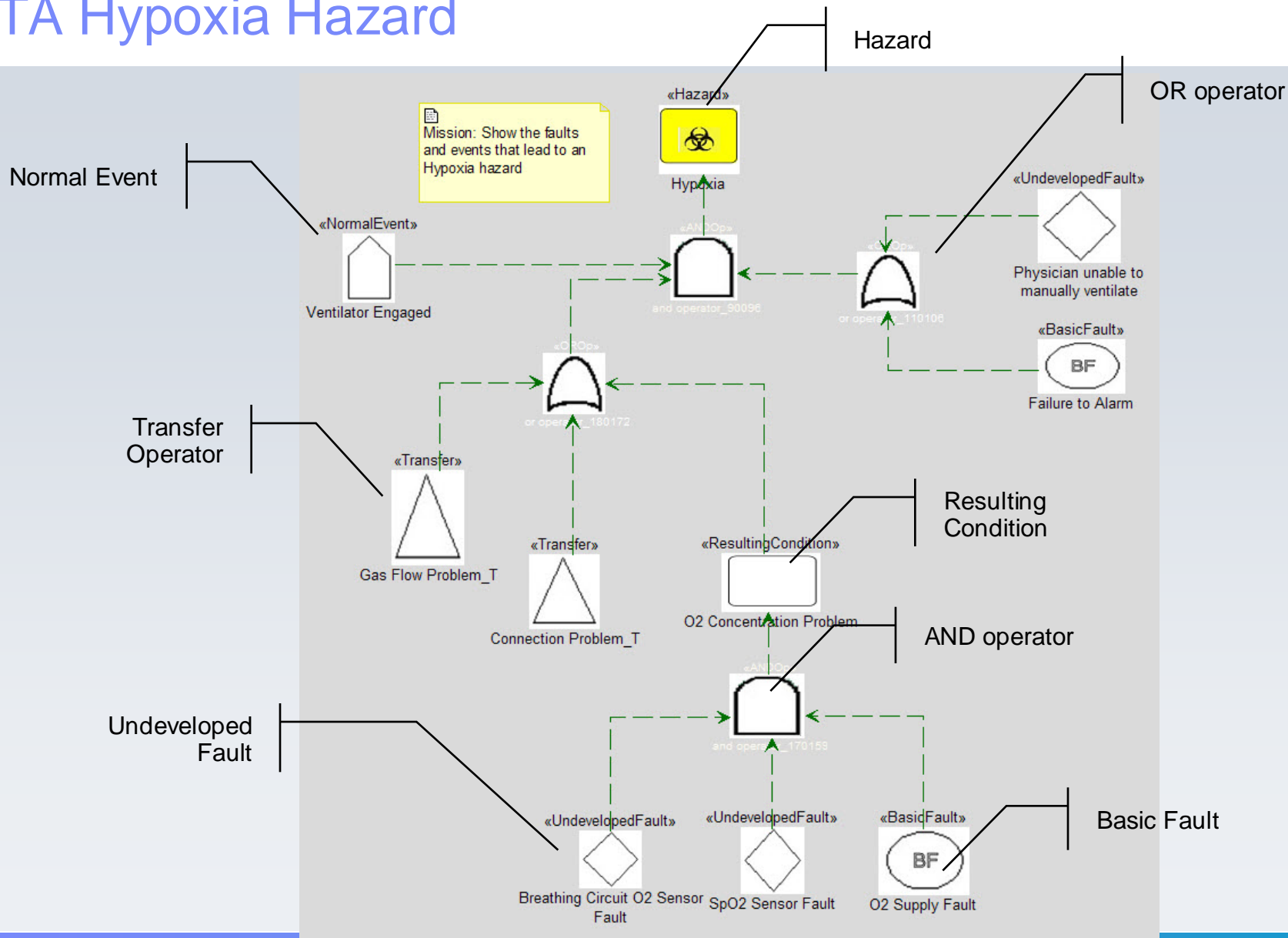


# Hazard Table (generated)

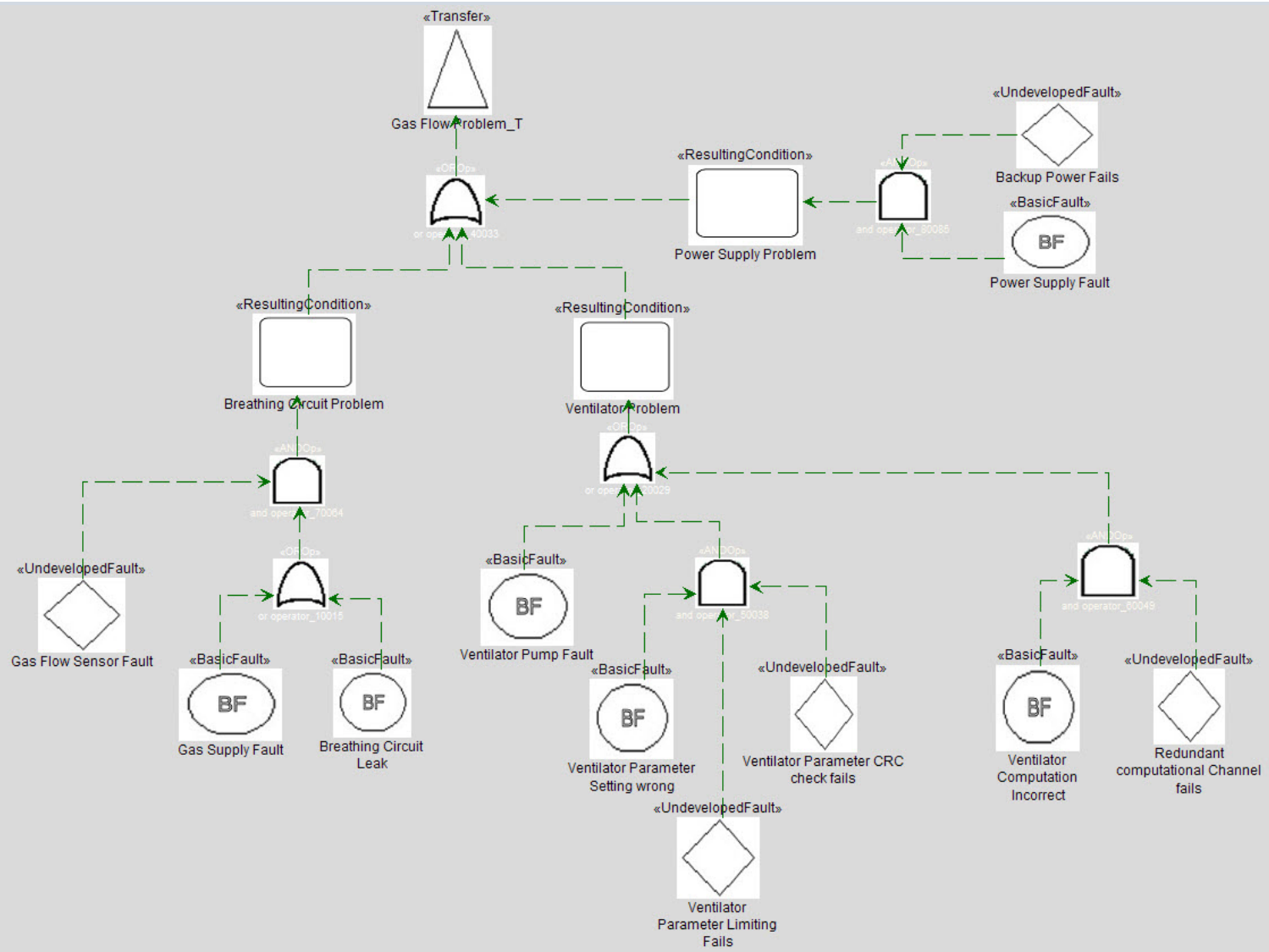
Name	Description	Probability	Severity	Risk	SafetyIntegrityLevel	FaultToleranceTime	FaultToleranceTimeUnits
Hypoxia	The hypoxia hazard occurs when the brain and other organs receive insufficient oxygen. In a	1e-2	8	8e-2	3	5	minutes
Overpressre	Overpressure can damage the lungs. This is an especially severe trauma, possibly fatal, to	1e4	4	3e4	3	200	milliseconds
Hyperoxia	Hyperoxia problems are usually limited to neonates, where it can cause blindness.	1e5	4	4e5	4	10	minutes
Inadequate Anesthesia	In adequate anesthesia leads to patient discomfort and memory retention of the surgical	1e4	2	2e4	2	5	minutes
Over anesthesia	Over anesthesia can lead to death.	1e3	4	4e3	4	3	minutes
Anesthesia leak into ER	Anesthesia leak can lead to short or, in smaller doses, to long-term poisoning of medical staff.	1e5	5	4e5	5	10	minutes



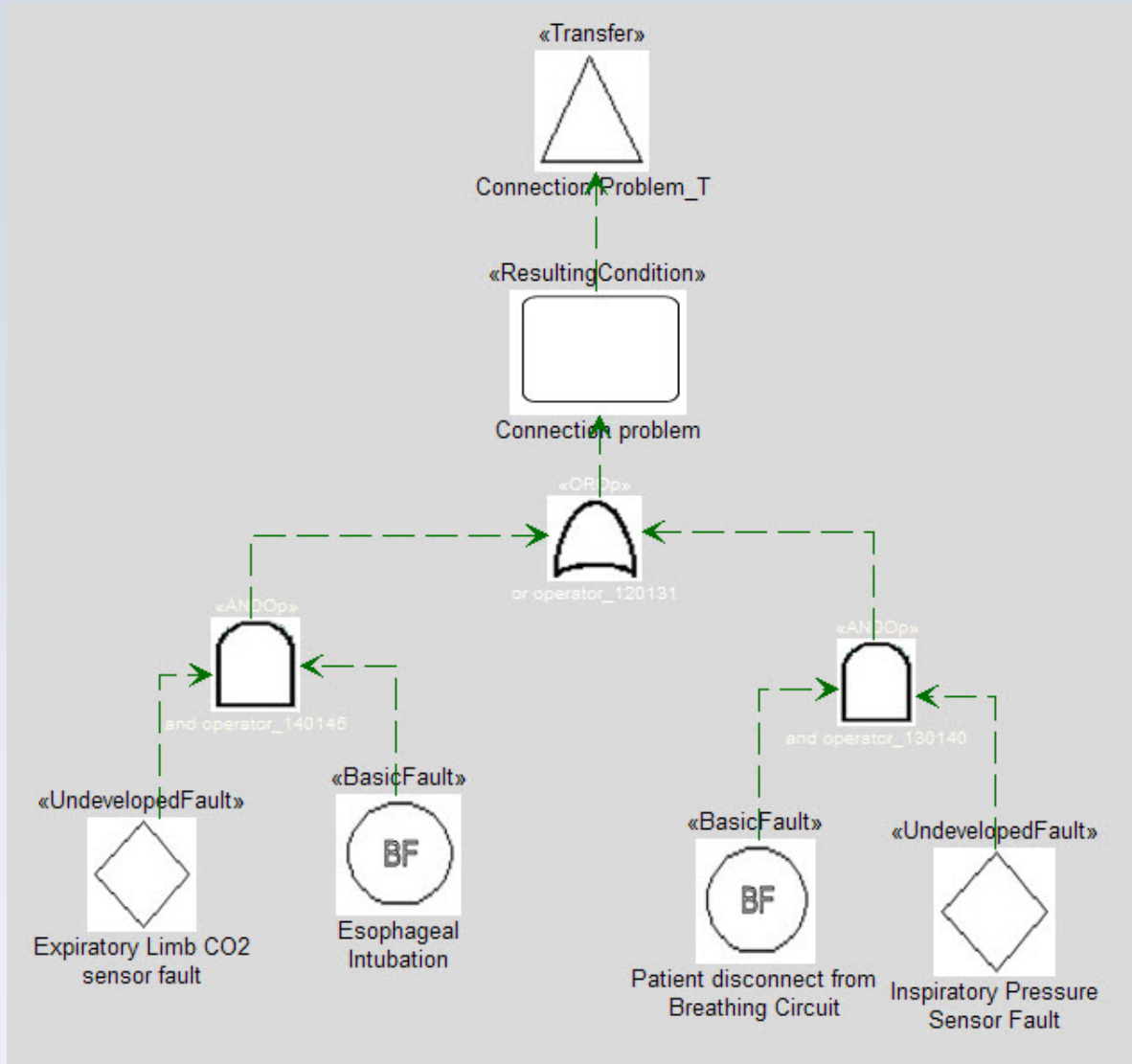
# FTA Hypoxia Hazard



# FTA Gas Flow Problem



# FTA Gas Connection Problem



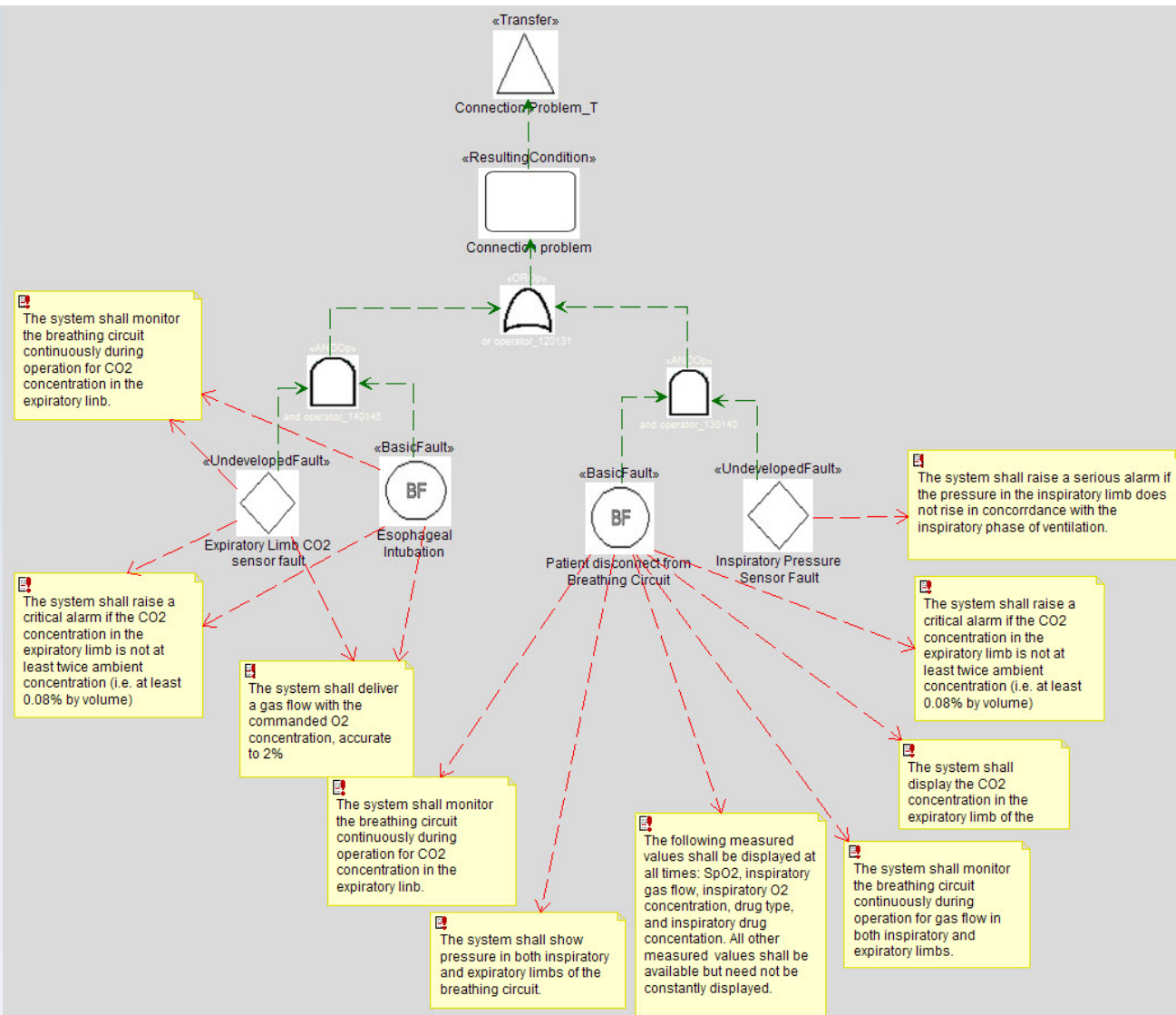
# Fault Table

Name	Description	MTBF	MTBF_TimeUnits	Probability
<input type="radio"/> Gas Supply Fault	This fault occurs when gas from a required source (e.g. O2 air N2 or He). This may be to any number of root causes such as a stuck or closed valve, running out of gas, a leak_	1e6	minutes	1e-6
<input type="radio"/> Breathing Circuit Leak	This fault occurs when a significant amount of gas leaks from the breathing circuit into the	1e3	minutes	1e-3
<input type="radio"/> Ventilator Pump Fault	This fault occurs when the pump internal to the ventilator no longer functions to shape the	1e6	seconds	1e-6
<input type="radio"/> Ventilator Parameter Setting wrong	This fault occurs when a ventilator parameter is out of range. This includes: I:E ratio Tidal Volume Respiration Rate Inspiratory Pause Maximum inspiratory pressure Inspiration time	1e4	seconds	1e-4
<input type="radio"/> Ventilator Computation Incorrect	This fault occurs when an error in the software or a fault in a necessary resource (e.g.	1e5	seconds	1e-5
<input type="radio"/> Esophageal Intubation	This is a user-fault, but is common. This is mitigated by a CO2 sensor on the expiratory	1e5	minutes	1e-4
<input type="radio"/> Patient disconnect from Breathing Circuit	This fault can occur as a result of jostling the breathing circuit during a surgical procedure.	1e4	minutes	1e-4
<input type="radio"/> Power Supply Fault	The mains can fail because of a source power supply fault or if the power cord becomes	1e5	minutes	1e-5
<input type="radio"/> Failure to Alarm	The alarm system is a system that exists solely for safety reasons. Therefore, it need not	1e5	minutes	1e-5
<input type="radio"/> O2 Supply Fault	The O2 supply fault can occur because of a exhaustion of the supply itself, stuck or	1e4	seconds	1e-4
<input type="checkbox"/> Breathing Circuit Problem				
<input type="checkbox"/> Ventilator Problem				
<input type="checkbox"/> Power Supply Problem				
<input type="checkbox"/> Connection problem				
<input type="checkbox"/> O2 Concentration Problem				
<input checked="" type="checkbox"/> Redundant computational Channel fails	The redundant computational channel uses a heterogeneous algorithm to compute the	1e5	seconds	1e-5
<input checked="" type="checkbox"/> Ventilator Parameter Limiting Fails	This fault occurs if the limit checks on the setting of ventilator parameters fail, i.e. allow a	1e6	seconds	1e-6
<input checked="" type="checkbox"/> Gas Flow Sensor Fault	This fault occurs if the gas flow sensor fails to correctly measure the gas flow in the	1e-7	minutes	1e-7
<input checked="" type="checkbox"/> Ventilator Parameter CRC check fails	Ventilator parameters are protected with a 32-bit CRC algorithm. This is specifically	1e5	seconds	1e-5
<input checked="" type="checkbox"/> Backup Power Fails	The battery backup exists as a safety means to enable the system to continue to provide	1e4	minutes	1e-4
<input checked="" type="checkbox"/> Physician unable to manually ventilate	The anesthesiologist is required to have a manual ventilation system available in the case	1e10	minutes	1e-10
<input checked="" type="checkbox"/> SpO2 Sensor Fault	The SpO2 sensor is a fingercuff O2 sensor. This fault occurs if the sensor does not	1e7	seconds	1e-7
<input checked="" type="checkbox"/> Breathing Circuit O2 Sensor Fault	The breathing circuit O2 sensor is provided to ensure that the O2 delivered from the	1e7	seconds	1e-7
<input checked="" type="checkbox"/> Inspiratory Pressure Sensor Fault	The inspiratory pressure sensor is used to determine that the pressures delivered to the	1e7	seconds	1e-7
<input checked="" type="checkbox"/> Expiratory Limb CO2 sensor fault	The expiratory limb CO2 sensor exists to ensure that the breathing circuit is properly	1e7	seconds	1e-7





# Connecting FTA to Requirements (TraceToReq)



# Fault-Requirement Matrix (generated)

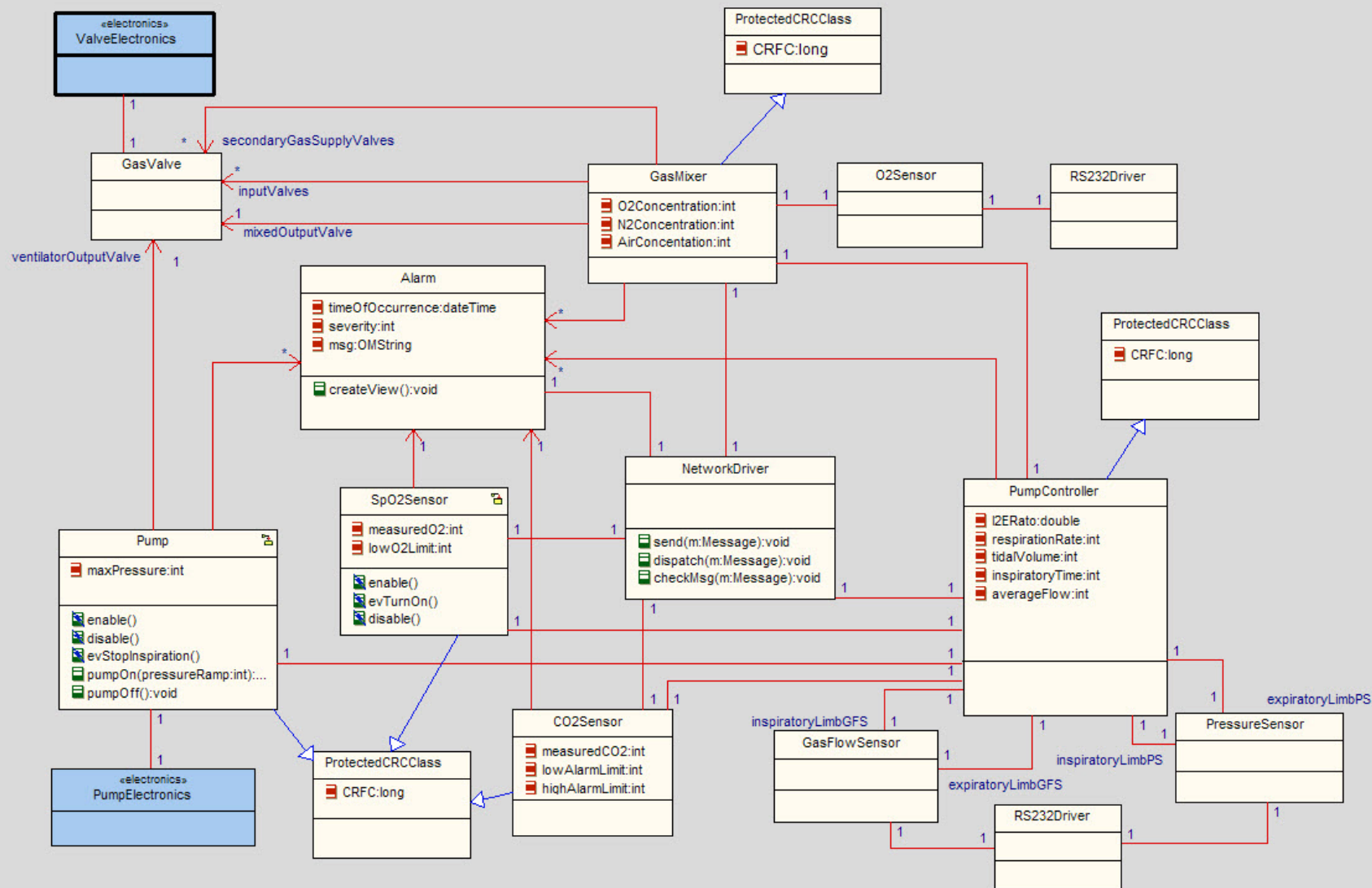
To: Requirement	Scope: RequirementsAnalysis	REQ_BCM_09	REQ_BCM_11	REQ_VD_03	REQ_VD_04	REQ_VD_06	REQ_SpO2_01	REQ_VD_08	REQ_VD_10	REQ_VD_11
Gas Supply Fault				REQ_VD_03	REQ_VD_04	REQ_VD_06		REQ_VD_08		
Breathing Circuit Leak				REQ_VD_03	REQ_VD_04	REQ_VD_06				
Ventilator Pump Fault						REQ_VD_06				
Ventilator Parameter Setting wrong										
Ventilator Computation Incorrect		REQ_BCM_09								
Esophageal Intubation						REQ_VD_06				
Patient disconnect from Breathing Circuit										
Power Supply Fault										REQ_VD_11
Failure to Alarm										
O2 Supply Fault				REQ_VD_03	REQ_VD_04	REQ_VD_06		REQ_VD_08		
Redundant computational Channel fails									REQ_VD_10	
Ventilator Parameter Limiting Fails										
Gas Flow Sensor Fault										
Ventilator Parameter CRC check fails										
Backup Power Fails										
SpO2 Sensor Fault							REQ_SpO2_01			
Breathing Circuit O2 Sensor Fault										
Inspiratory Pressure Sensor Fault		REQ_BCM_11								
Expiratory Limb CO2 sensor fault						REQ_VD_06				

From: Basic Fault, Hazard, Resulting Condition, Transfer Operator, Undeveloped F...



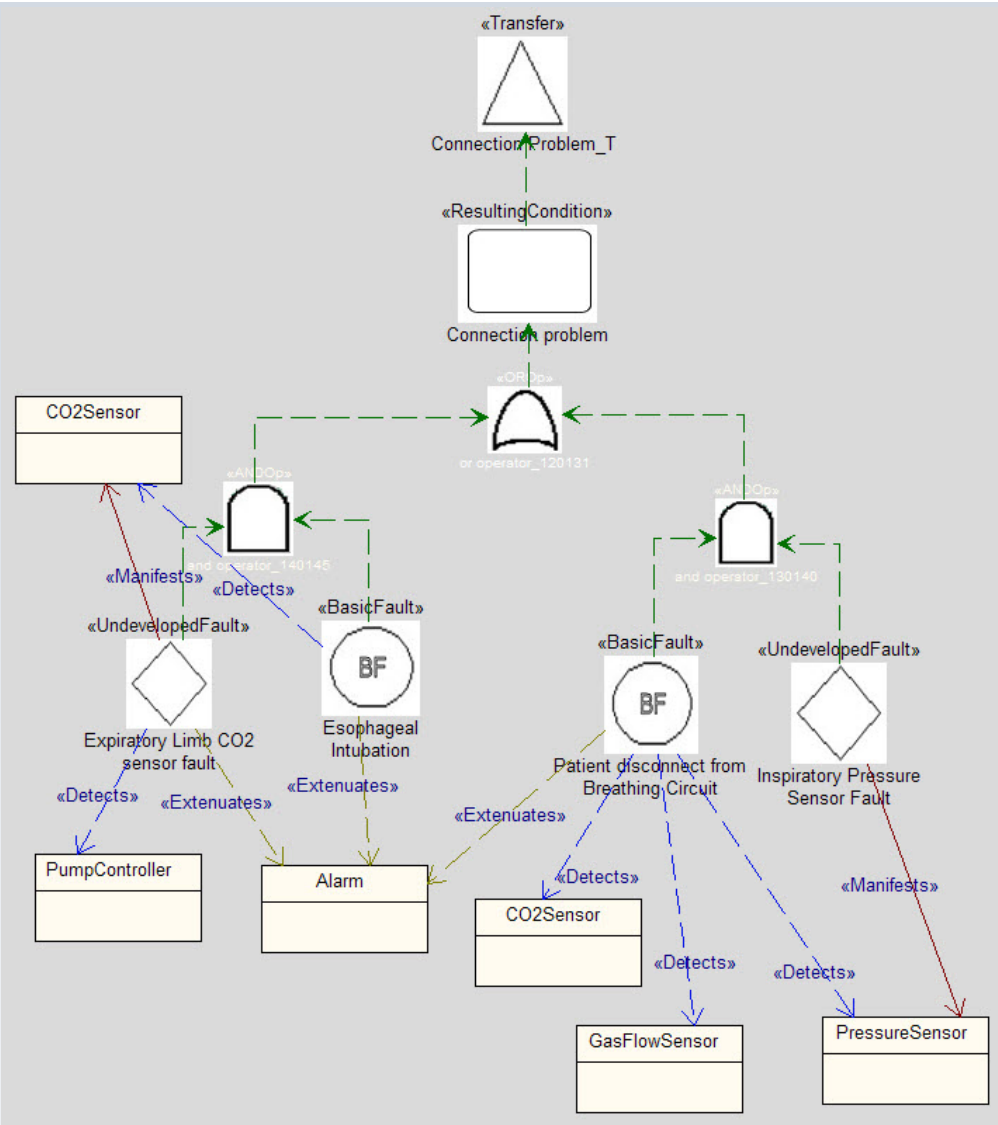


# Analysis Model of the Ventilator Subsystem





# FTA Connection Problem with Design Elements



# Fault-Source Matrix (generated)

To: Class, SafetyMeasure Scope: DesignModel

	AlarmManager	GasFlowSensor	Pump	PressureSensor	SpO2Sensor	GasValve	PumpController	O2Sensor	PowerSupplyRegulator
○ Gas Supply Fault						↳ GasValve			
○ Ventilator Pump Fault			↳ Pump						
○ Ventilator Parameter Setting wrong							↳ PumpController_0		
○ Ventilator Computation Incorrect							↳ PumpController		
○ Power Supply Fault									↳ PowerSupplyRegulator
○ Failure to Alarm	↳ AlarmManager								
○ O2 Supply Fault						↳ GasValve			
◇ Ventilator Parameter Limiting Fails							↳ PumpController_0		
◇ Gas Flow Sensor Fault		↳ GasFlowSensor							
◇ Backup Power Fails									
◇ SpO2 Sensor Fault					↳ SpO2Sensor				
◇ Breathing Circuit O2 Sensor Fault								↳ O2Sensor	
◇ Inspiratory Pressure Sensor Fault				↳ PressureSensor					
◇ Expiratory Limb CO2 sensor fault									

From: Basic Fault, Normal Event, Required Condition, Undeveloped



# Fault Detection Matrix (generated)

To: Class, SafetyMeasure    Scope: DesignModel

	GasFlowSensor	PressureSensor	PumpController	GasMixer	PowerSupplyRegulator	Battery	ProtectedCRCClass	CO2Sensor
Gas Supply Fault	GasFlowSensor							
Breathing Circuit Leak		PressureSensor						
Ventilator Pump Fault			PumpController					
Ventilator Parameter Setting wrong							ProtectedCRCClass	
Ventilator Computation Incorrect	GasFlowSensor			GasMixer				
Esophageal Intubation								CO2Sensor
Patient disconnect from Breathing Circuit	GasFlowSensor	PressureSensor						CO2Sensor
Power Supply Fault						Battery		
O2 Supply Fault				GasMixer				
Redundant computational Channel fails	GasFlowSensor	PressureSensor		GasMixer				
Ventilator Parameter Limiting Fails							ProtectedCRCClass	
Ventilator Parameter CRC check fails							ProtectedCRCClass	
Backup Power Fails					PowerSupplyRegulator			
SpO2 Sensor Fault			PumpController					
Breathing Circuit O2 Sensor Fault				GasMixer				
Expiratory Limb CO2 sensor fault			PumpController					

From: Basic Fault, Normal Event, Required Condition, Undeveloped Fa

## Hazard Analysis (generated external file) Pg 1

Hazard	Description	Fault tolerance time	Fault tolerance time units	Probability	Severity	Risk	Safety integrity level
Hypoxia	The hypoxia hazard occurs when the brain and other organs receive insufficient oxygen. In a normal 21% O <sub>2</sub> environment, death or irreversible injury occurs after five minutes of no oxygen. If the patient is breathing 100% for a significant period of time, this time is about 10 minutes.	5	minutes	1.00E-02	8	8.00E-02	3
Overpressure	Overpressure can damage the lungs. This is an especially severe trauma, possibly fatal, to neonates.	200	milliseconds	1.00E+04	4	3.00E+04	3
Hyperoxia	Hyperoxia problems are usually limited to neonates, where it can cause blindness.	10	minutes	1.00E+05	4	4.00E+05	4
Inadequate anesthesia	Inadequate anesthesia leads to patient discomfort and memory retention of the surgical procedures. This is normally not life threatening but can be severely discomforting.	5	minutes	1.00E+04	2	2.00E+04	2
Over anesthesia	Over anesthesia can lead to death.	3	minutes	1.00E+03	4	4.00E+03	4
Anesthesia leak into ER	Anesthesia leak can lead to short or, in smaller doses, to long-term poisoning of medical staff.	10	minutes	1.00E+05	5	4.00E+05	5



## Hazard Analysis (generated external file) Pg 2

Hazard	Fault or event	Fault type	Fault description	MTBF	MTBF time units	Probability
Hypoxia	Ventilator engaged	NormalEvent				1
Hypoxia	Gas supply fault	BasicFault	This fault occurs when gas from a required source is unavailable. This may be due to any number of root causes, such as a stuck or closed valve, running out of gas or a leak.	1.00E+06		1.00E-06
Hypoxia	Breathing circuit leak	BasicFault	This fault occurs when a significant amount of gas leaks from the breathing circuit into the surrounding environment. This can lead to a poisoning hazard when the gas contains anesthetic drugs.	1.00E+03		1.00E-03
Hypoxia	Ventilator pump fault	BasicFault	This fault occurs when the pump internal to the ventilator no longer functions to shape the breath and push gas into the breathing circuit.	1.00E+06		1.00E-06
Hypoxia	Ventilator parameter setting wrong	BasicFault	This fault occurs when a ventilator parameter is out of range. This includes: -I:E ratio -Tidal Volume - Respiration Rate -Inspiratory Pause - Maximum inspiratory pressure - Inspiration time	1.00E+04		1.00E-04
Hypoxia	Ventilator computation incorrect	BasicFault	This fault occurs when an error in the software or a fault in a necessary resource (such as memory) results in an incorrect computation that in turn results in incorrect delivery of ventilation.	1.00E+05		1.00E-05



# Hazard Analysis (generated external file) Pg 3

Fault or event	Requirements	Manifestors	Detectors	Extenuators
Gas supply fault	REQ_BCM_01	GasValve	GasFlowSensor	Alarm
Gas supply fault	REQ_VD_06			
Gas supply fault	REQ_VD_03			
Gas supply fault	REQ_VD_04			
Gas supply fault	REQ_VD_08			
Breathing circuit leak	REQ_VD_03		PressureSensor	Alarm
Breathing circuit leak	REQ_VD_04			
Breathing circuit leak	REQ_VD_06			
Ventilator pump fault	REQ_VD_06	Pump	PumpController	PumpController
Ventilator parameter setting wrong	REQ_vent_limit_range_on_patient_mode	PumpController	ProtectedCRCClasses	Alarm
Ventilator parameter setting wrong	REQ_vent_parameter_out_of_range_setting			
Ventilator parameter setting wrong	REQ_Vent_confirmation			





# References to enhance your Harmony

**Dr. Douglass' Guided Tour Through the Wonderland of Systems Engineering, UML™ and Rhapsody®**

**Model Driven Architecture and Rhapsody**

**Any Port in a Storm**

**DODAF Architectures in UML and Rhapsody**

**What is DODAF?**

The DODAF Architecture Framework is a semantic framework for developing, representing, and integrating architectures in a consistent way for the Department of Defense applications[1]. The DoDAF specification is a recent upgrade to the 1997 CISR-AF specification. It was conceived as a way of providing a common means to specify systems for the Department of Defense (DoD) in its many facets and programs. The DODAF specification defined architectures to be:

An architecture description is a representation of a defined domain, as of a current or future point in time, in terms of its component parts, what those parts do, how the parts relate to each other, and the rules and constraints under which the parts function. What constitutes each of the elements of this definition depends on the degree of detail of interest. For example, domains can be at any level, from DoD as a whole down to individual functional areas or groups of functional areas. Component parts can be anything from "U.S. Air Force" as a component of DoD, down to a "satellite ground station" as a component part of a communications network, or "workstation A" as a component part of system "x." What those parts do can be as general as their high-level operational concept or as specific as the lowest-level action they perform. How the parts relate to each other can be as general as how organizations fit into a very high-level command structure or as specific as what frequency one unit uses in communicating with another. The rules and constraints under which they work can be as general as high-level doctrine or as specific as the e-mail standard they must use.

The term *architecture* is generally used both to refer to an architecture description and an architecture implementation. Hereafter in this document, the term *architecture* will be used as a shortened reference

