

Euclidean Vector Space (1A)

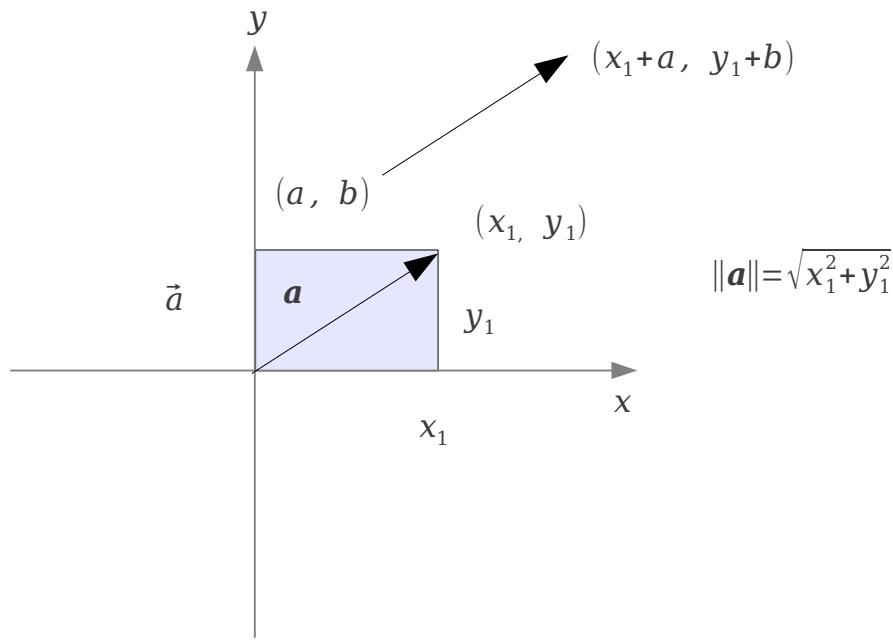
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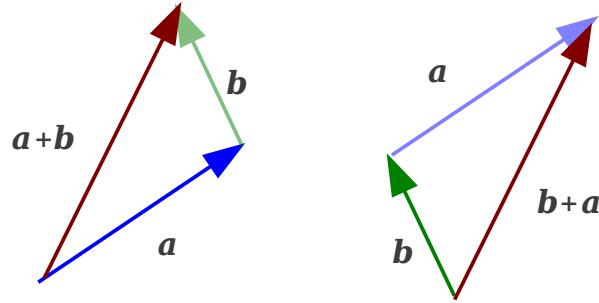
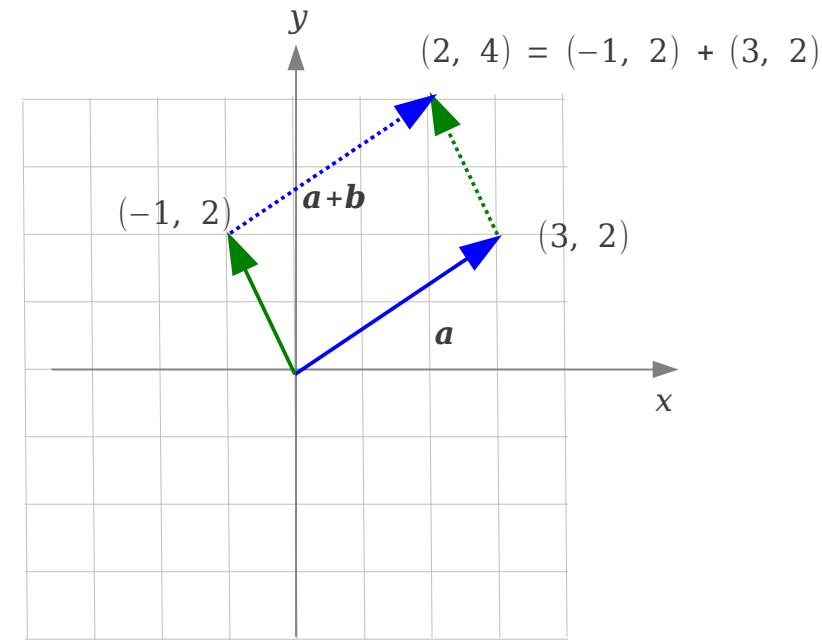
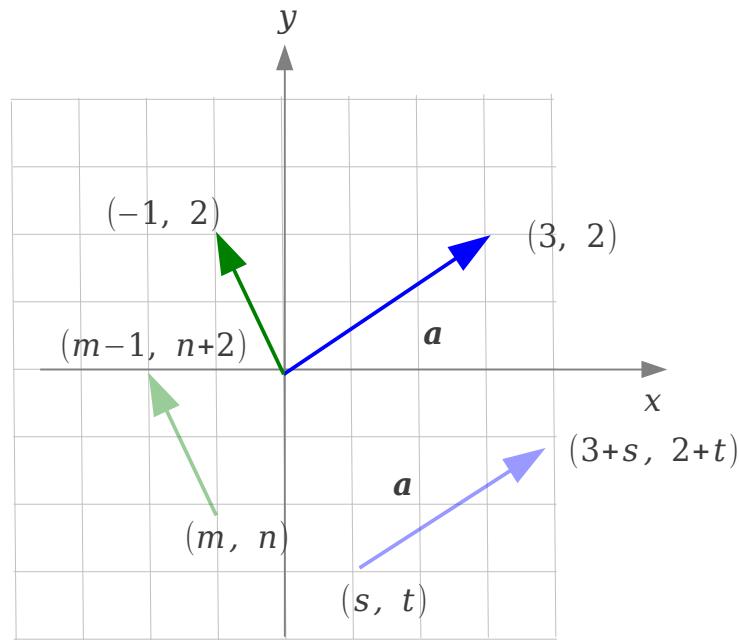
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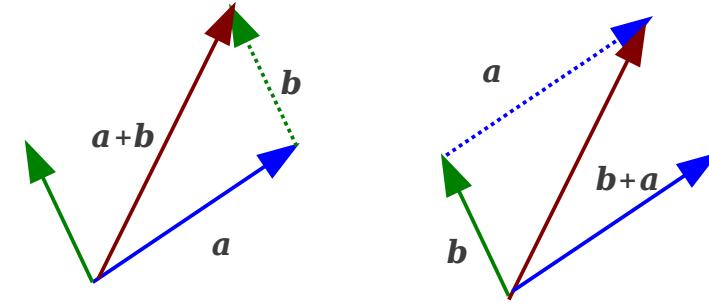
Vectors



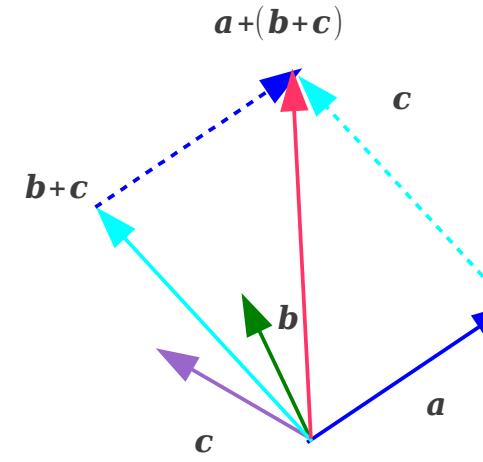
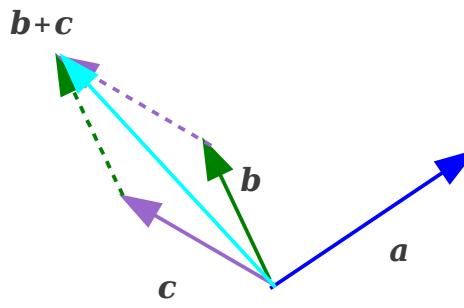
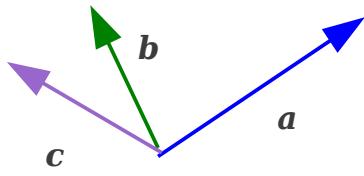
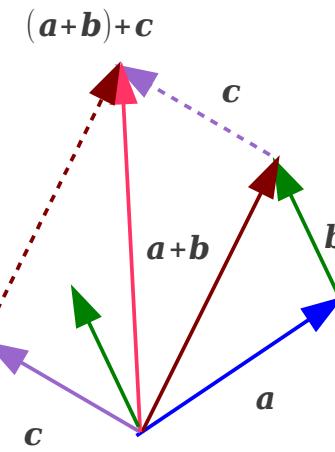
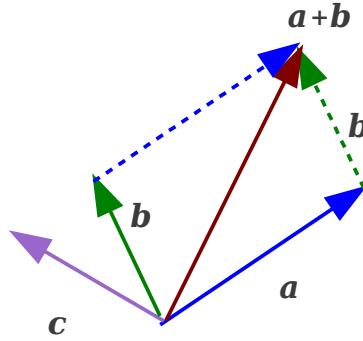
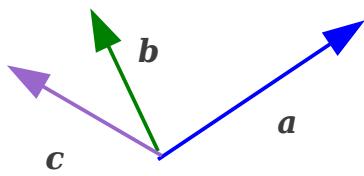
Vector Addition



$$\mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a}$$

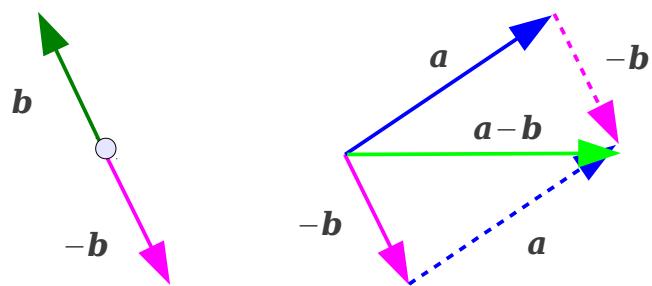
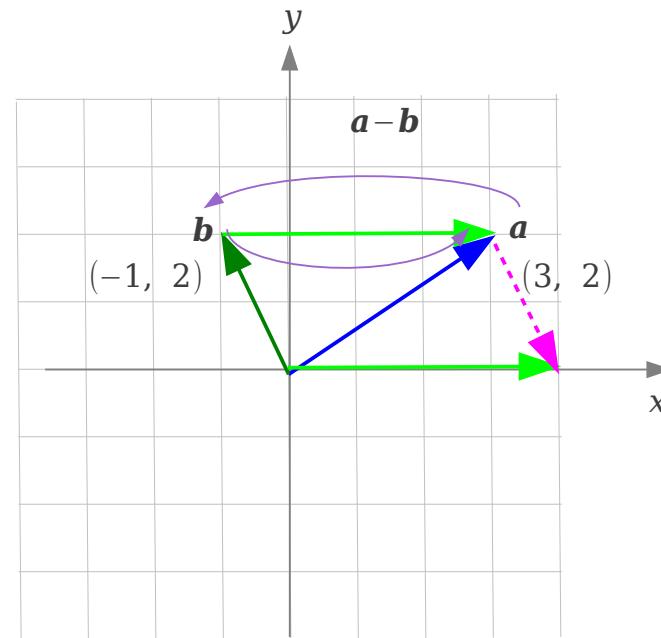
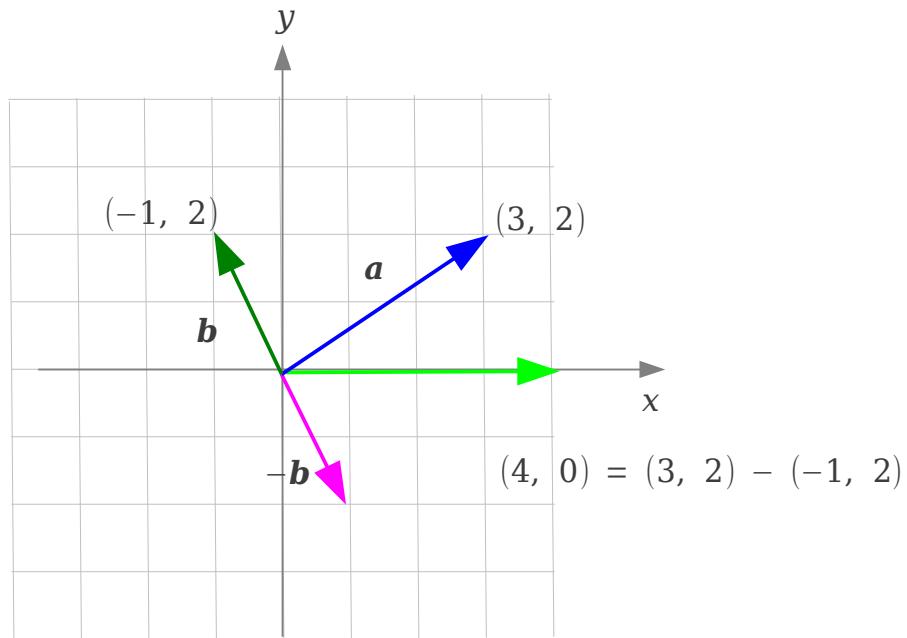


Vector Addition



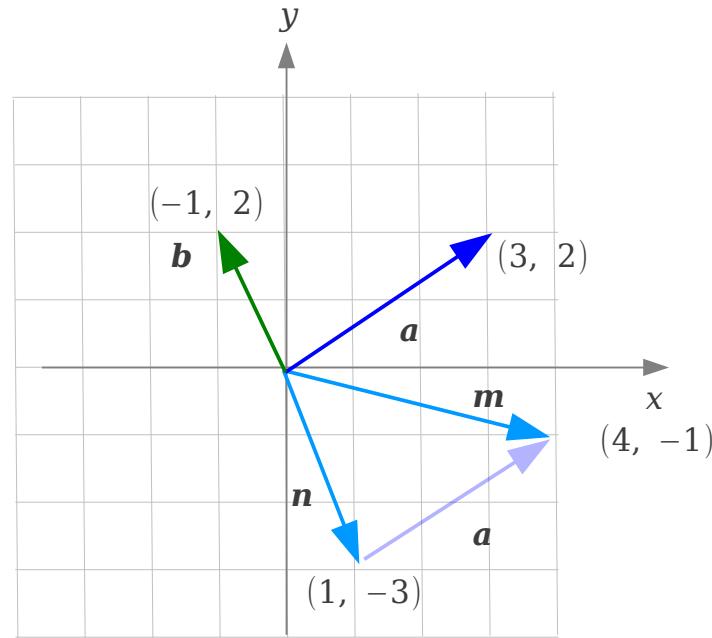
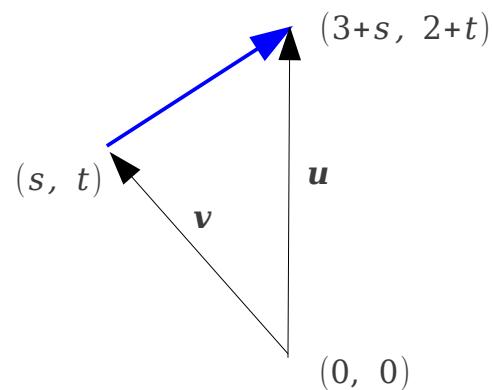
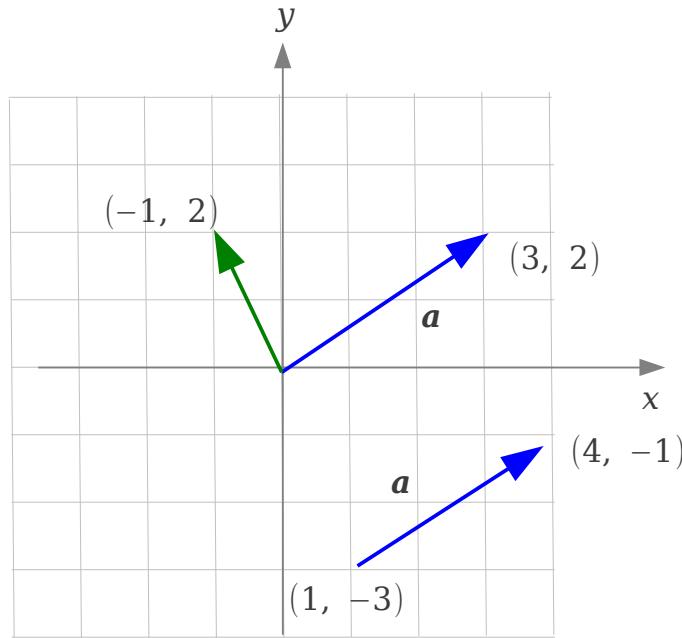
$$(a+b)+c = a+(b+c)$$

Vector Subtraction



$\mathbf{a} - \mathbf{b}$
subtract \mathbf{a} from \mathbf{b}
arrow from \mathbf{b} to \mathbf{a}

Vector Addition



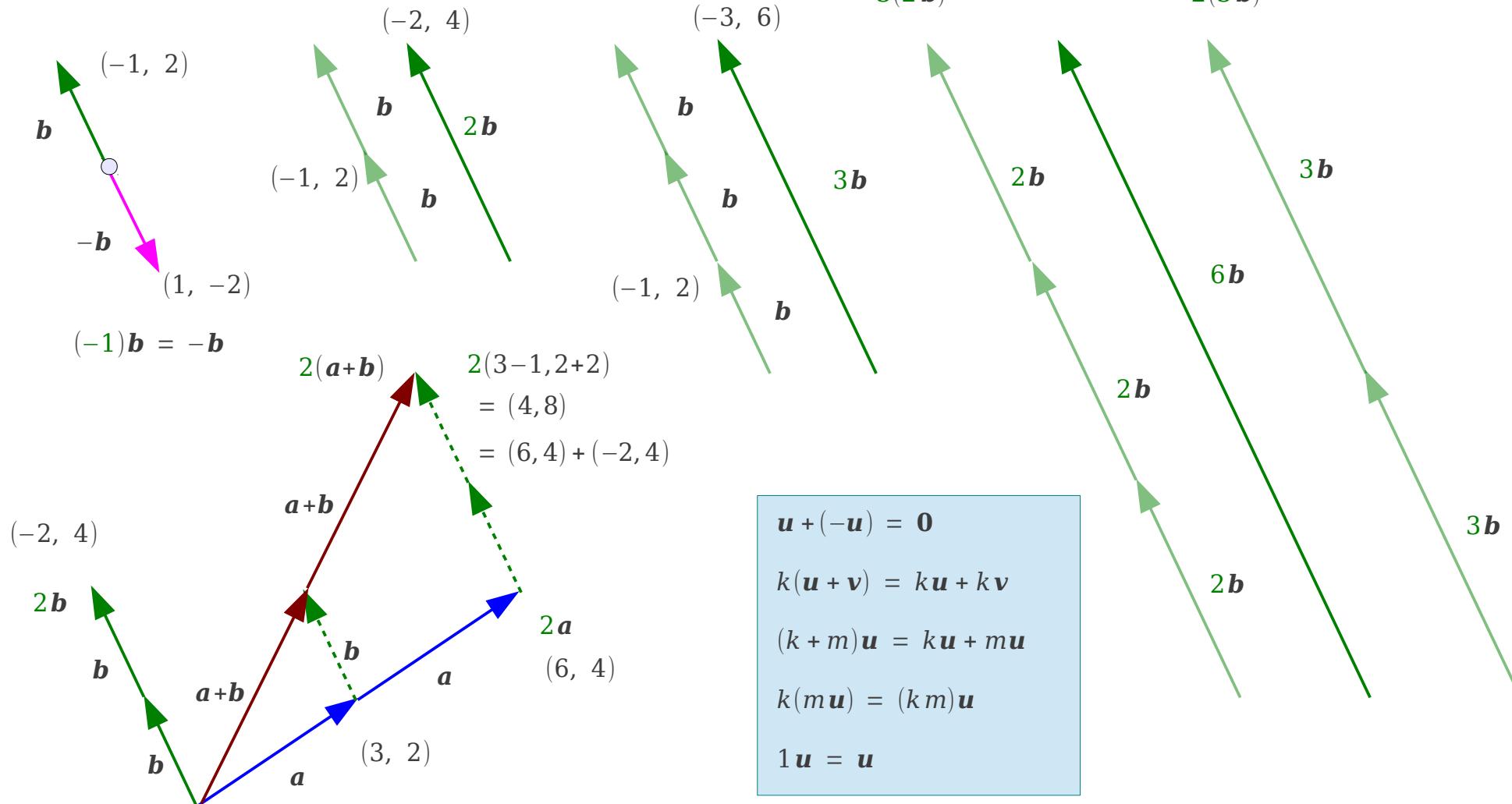
$$\mathbf{m} = (4, -1)$$

$$\mathbf{n} = (1, -3)$$

$$\mathbf{a} = \mathbf{m} - \mathbf{n} = (4, -1) - (1, -3) = (3, 2)$$

Finding the **Component Form** of a vector

Scalar Multiplication



Vector Addition

$$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$$

$$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$$

$$\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$$

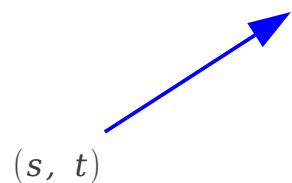
$$\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$$

$$k(\mathbf{u} + \mathbf{v}) = k\mathbf{u} + k\mathbf{v}$$

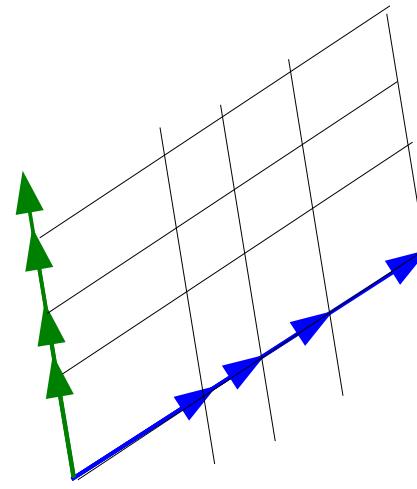
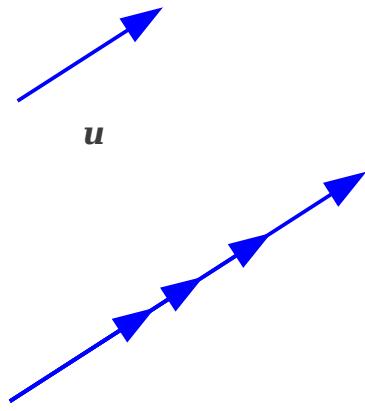
$$(k + m)\mathbf{u} = k\mathbf{u} + m\mathbf{u}$$

$$k(m\mathbf{u}) = (km)\mathbf{u}$$

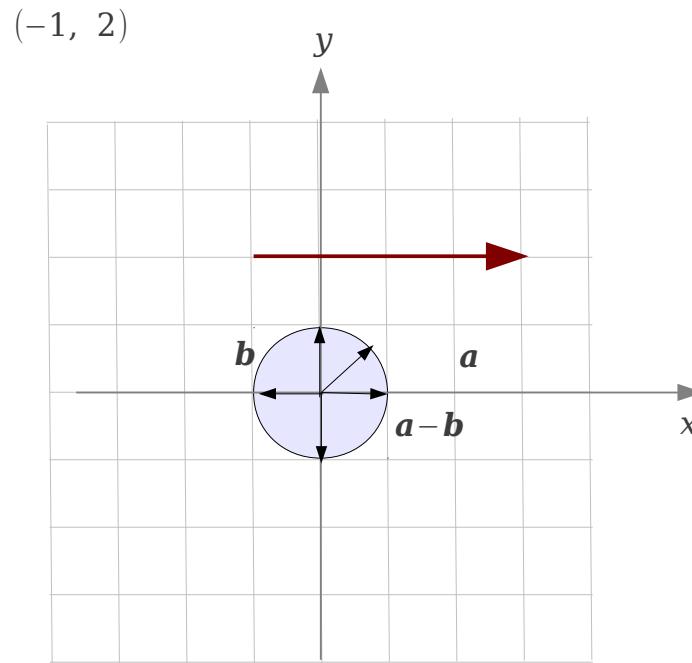
$$1\mathbf{u} = \mathbf{u}$$



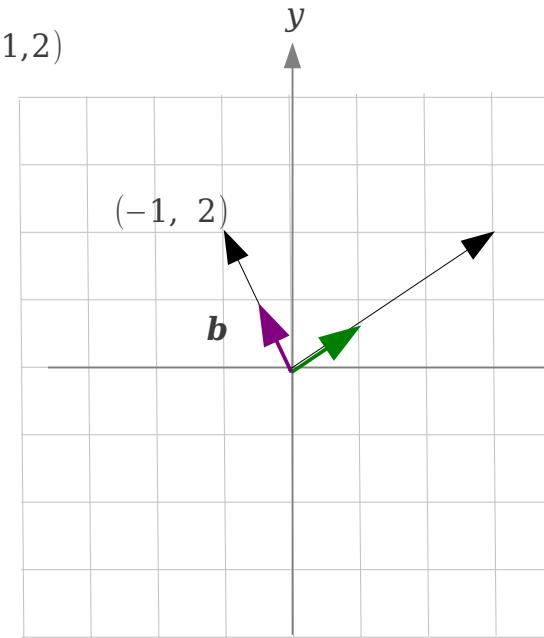
Vector Addition



Unit Vector



$$\mathbf{b} = (-1, 2)$$



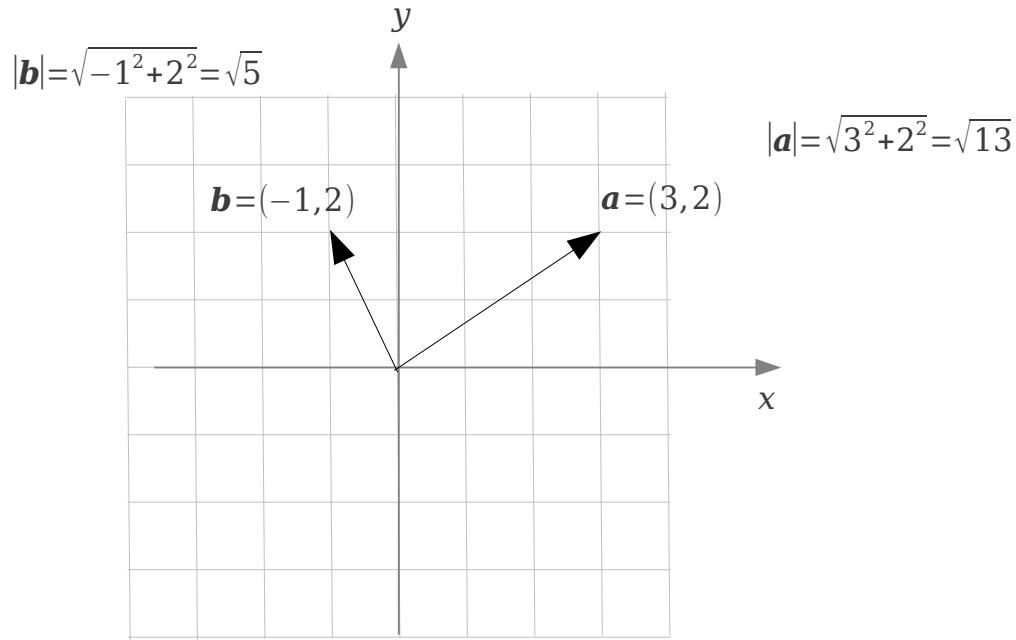
$$|\mathbf{a}| = \sqrt{3^2 + 2^2} = \sqrt{13}$$

$$\mathbf{a} = (3, 2)$$

$$= \left(\frac{3}{\sqrt{13}}, \frac{2}{\sqrt{13}} \right)$$

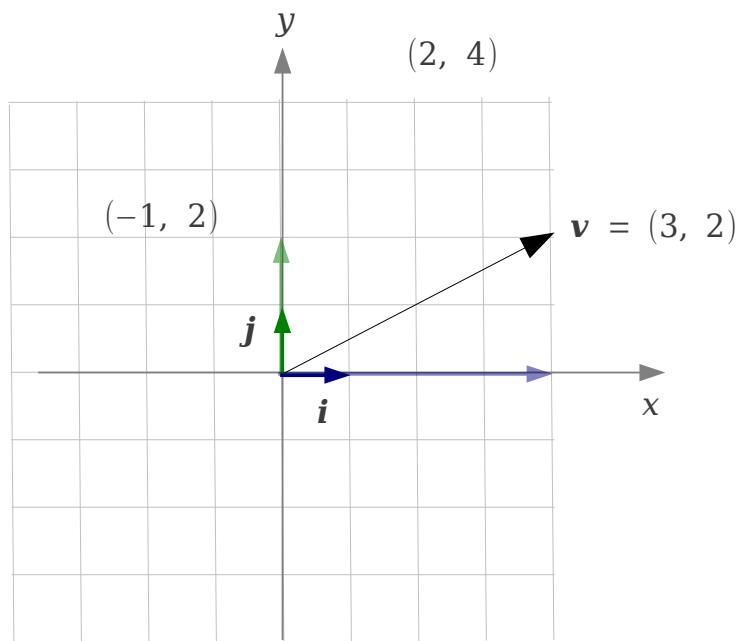
$$= \sqrt{\frac{3^2}{13} + \frac{2^2}{13}}$$

Vector Magnitude



$$\mathbf{a} \cdot \mathbf{b} = 3 \cdot -1 + 2 \cdot 2 = -3 + 4 = 1$$

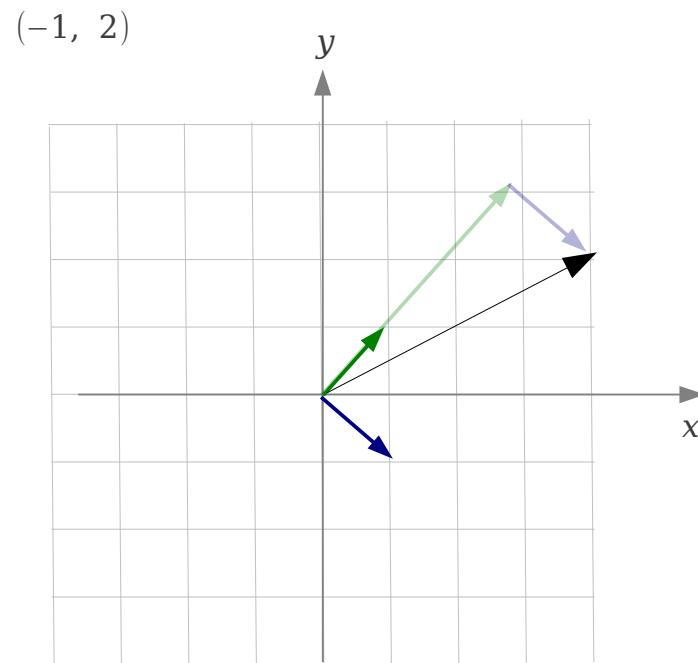
Basis



$$\mathbf{v} = 3\mathbf{i} + 2\mathbf{j}$$

$$a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0 \quad \Rightarrow \quad a = b = 0$$

basis



$$a \begin{bmatrix} 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 0 \quad \Rightarrow \quad a = b = 0$$

basis

Determinant

Determinant of order 2

$$\begin{bmatrix} a_1 & a_2 \\ b_1 & b_2 \end{bmatrix} \quad \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

Determinant of order 3

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \quad \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

$$\begin{bmatrix} a_1 & & \\ b_2 & b_3 & \\ c_2 & c_3 & \end{bmatrix} \quad \begin{bmatrix} & a_2 & \\ b_1 & & b_3 \\ c_1 & & c_3 \end{bmatrix} \quad \begin{bmatrix} & & a_3 \\ & b_2 & \\ b_1 & b_2 & \\ c_1 & c_2 & \end{bmatrix}$$

Determinant

Determinant of order 3

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \quad \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$$

$$\begin{bmatrix} a_1 & & \\ b_2 & \cancel{b_3} & \\ c_2 & c_3 & \end{bmatrix} \quad \begin{bmatrix} & a_2 & \\ b_1 & \cancel{a_3} & \\ c_1 & c_3 & \end{bmatrix} \quad \begin{bmatrix} & & a_3 \\ b_1 & \cancel{b_2} & \\ c_1 & c_2 & \end{bmatrix}$$

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} = + a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

Cross Product (1)

Determinant of order 3

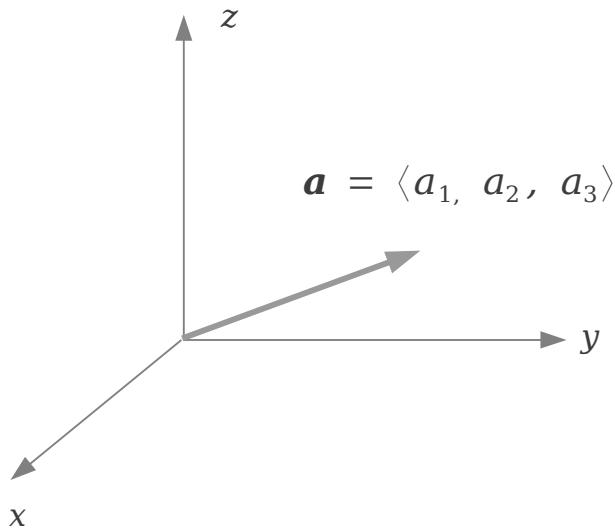
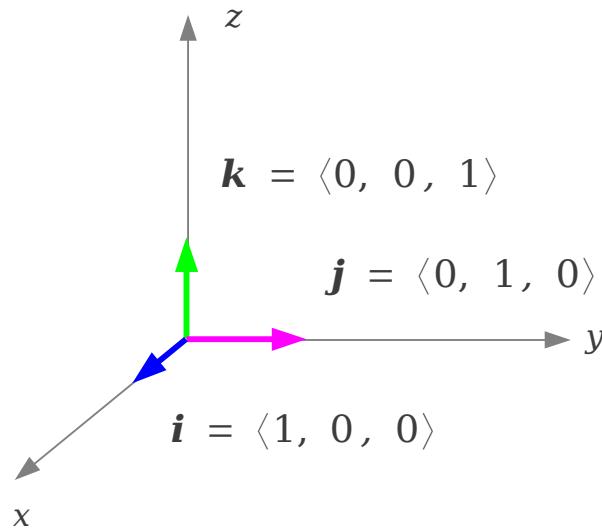
$$\mathbf{a} = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k} = \langle a_1, a_2, a_3 \rangle$$

$$\mathbf{b} = b_1 \mathbf{i} + b_2 \mathbf{j} + b_3 \mathbf{k} = \langle b_1, b_2, b_3 \rangle$$

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \mathbf{i} \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} - \mathbf{j} \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} + \mathbf{k} \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

$$= (a_2 b_3 - a_3 b_2) \mathbf{i} - (a_1 b_3 - a_3 b_1) \mathbf{j} + (a_1 b_2 - a_2 b_1) \mathbf{k}$$

Cross Product (2)



$$\mathbf{i} \times \mathbf{j} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = \mathbf{k} \quad \text{normal to } \mathbf{i} \text{ & } \mathbf{j} \quad \rightarrow \quad \mathbf{j} \times \mathbf{i} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{vmatrix} = -\mathbf{k}$$

$$\mathbf{j} \times \mathbf{k} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = \mathbf{i} \quad \text{normal to } \mathbf{j} \text{ & } \mathbf{k} \quad \rightarrow \quad \mathbf{k} \times \mathbf{j} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{vmatrix} = -\mathbf{i}$$

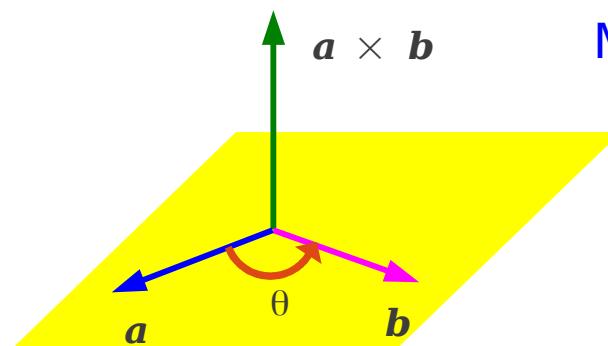
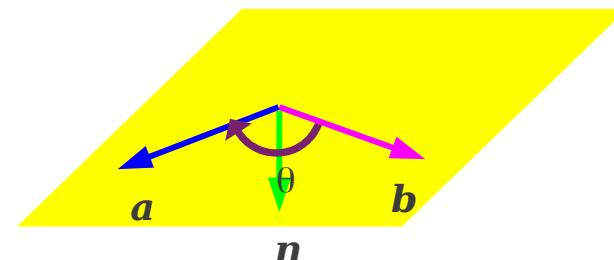
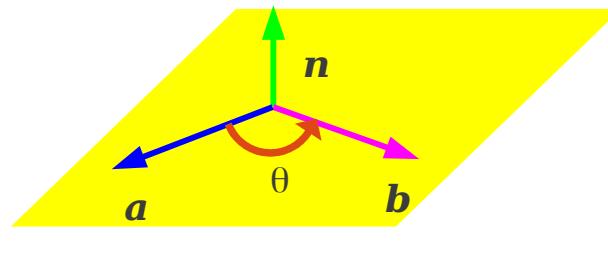
$$\mathbf{k} \times \mathbf{i} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{vmatrix} = \mathbf{j} \quad \text{normal to } \mathbf{k} \text{ & } \mathbf{i} \quad \rightarrow \quad \mathbf{i} \times \mathbf{k} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{vmatrix} = -\mathbf{j}$$

Right Hand Rule

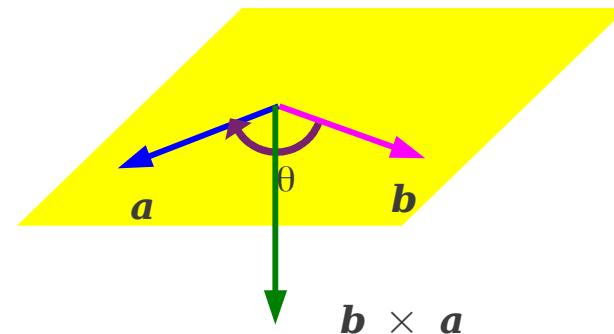
$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$\mathbf{b} \times \mathbf{a} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ b_1 & b_2 & b_3 \\ a_1 & a_2 & a_3 \end{vmatrix}$$

Normal direction \mathbf{n}



Magnitude = $\|\mathbf{a} \times \mathbf{b}\| = \|\mathbf{a}\| \|\mathbf{b}\| \sin \theta$



Line Equations (1)

Vector Equation

$$\mathbf{r} = \mathbf{r}_2 + t\mathbf{a}$$

Parameter

$$\mathbf{r}_2 = \langle x_2, y_2, z_2 \rangle$$

Direction Vector

$$\mathbf{a} = \langle a_1, a_2, a_3 \rangle$$

Parametric Equation

$$\begin{aligned}x &= x_2 + ta_1 \\y &= y_2 + ta_2 \\z &= z_2 + ta_3\end{aligned}$$

$$ta_1 = x - x_2$$

$$ta_2 = y - y_2$$

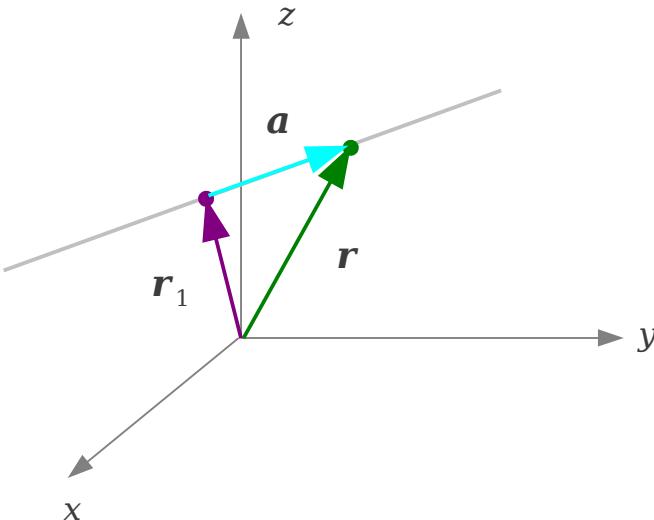
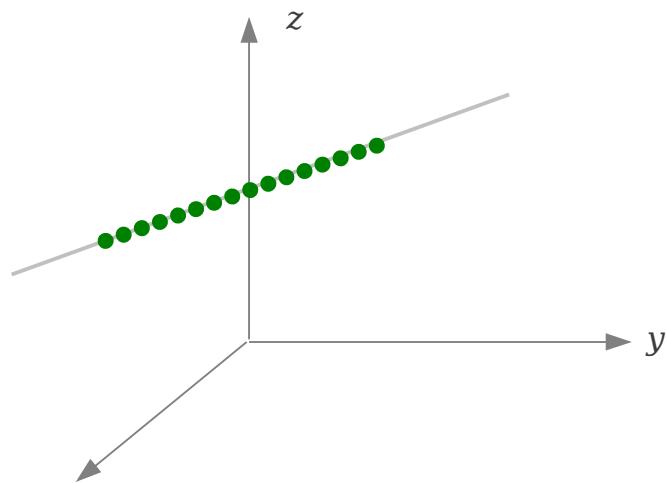
$$ta_3 = z - z_2$$

Symmetric Equation

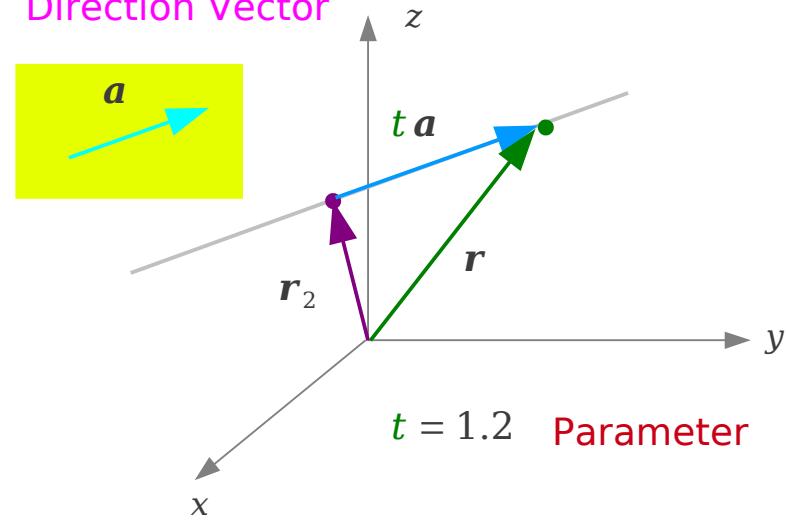
$$t = \frac{x - x_2}{a_1} = \frac{y - y_2}{a_2} = \frac{z - z_2}{a_3}$$

Elimination of parameter

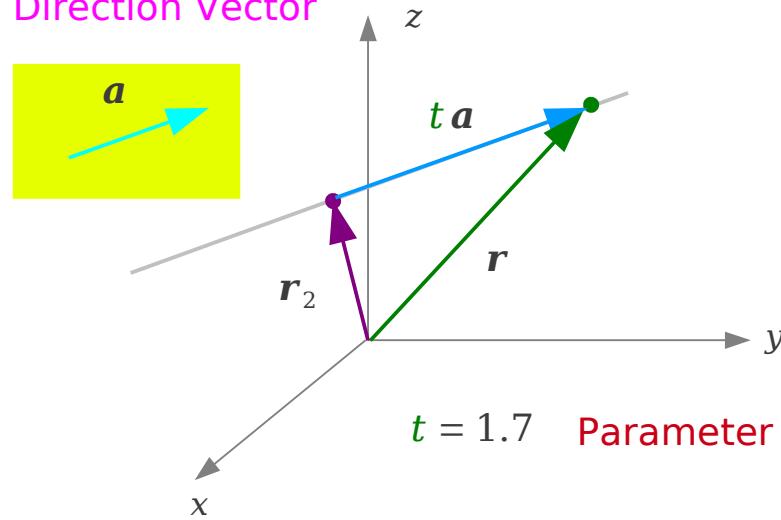
Line Equations (2)



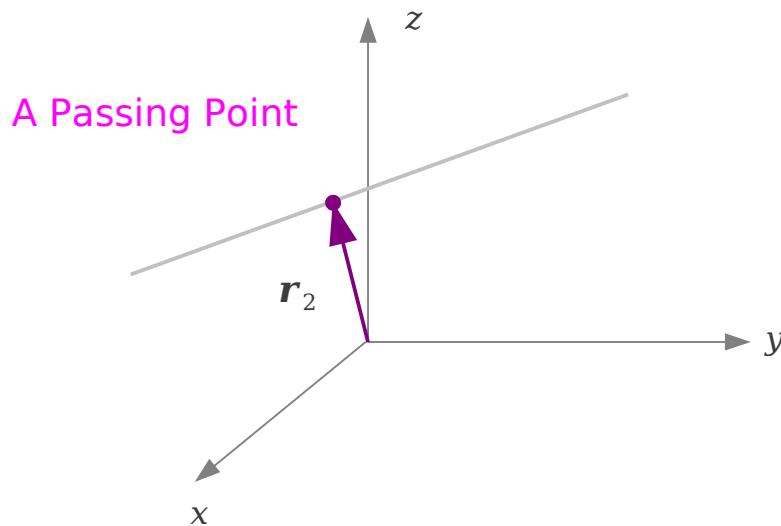
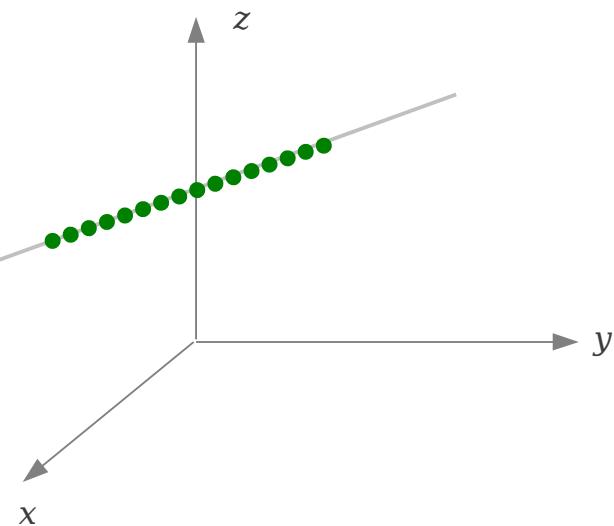
Direction Vector



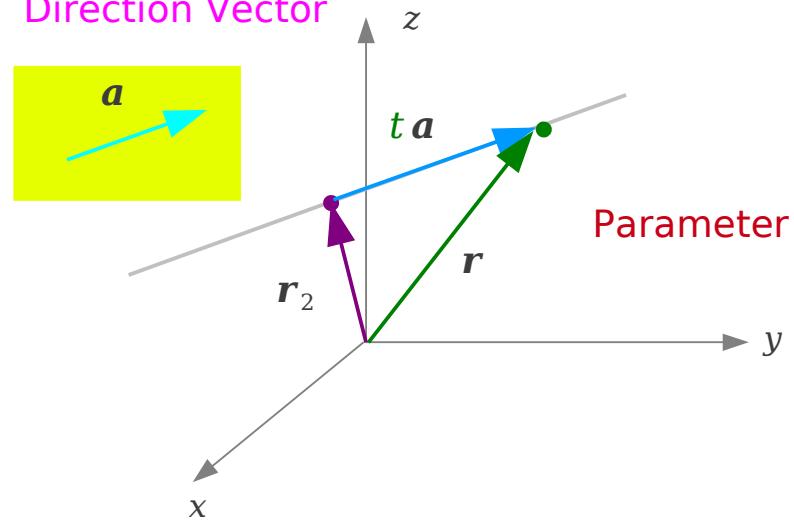
Direction Vector



Line Equations (3)



Direction Vector



$$\mathbf{r} = \mathbf{r}_2 + t\mathbf{a}$$

$$\mathbf{r}_2 = \langle x_2, y_2, z_2 \rangle$$

$$\mathbf{a} = \langle a_1, a_2, a_3 \rangle$$

Plane Equations (1)

Vector equation

$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_1) = 0$$

Normal Vector

$$\mathbf{r} = \langle x, y, z \rangle$$

$$\mathbf{r}_1 = \langle x_1, y_1, z_1 \rangle$$

$$\mathbf{n} = \langle a, b, c \rangle$$

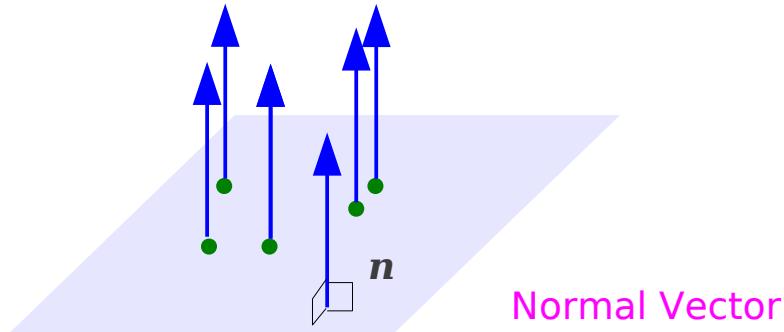
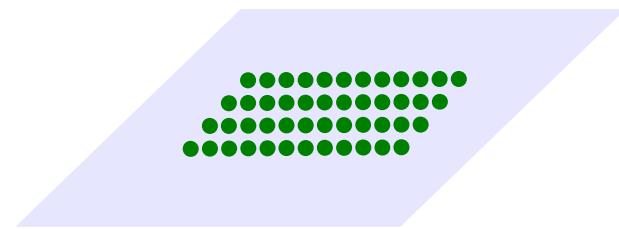
$$\mathbf{r} - \mathbf{r}_1 = \langle x - x_1, y - y_1, z - z_1 \rangle$$

$$\mathbf{n} = \langle a, b, c \rangle$$

Cartesian equation

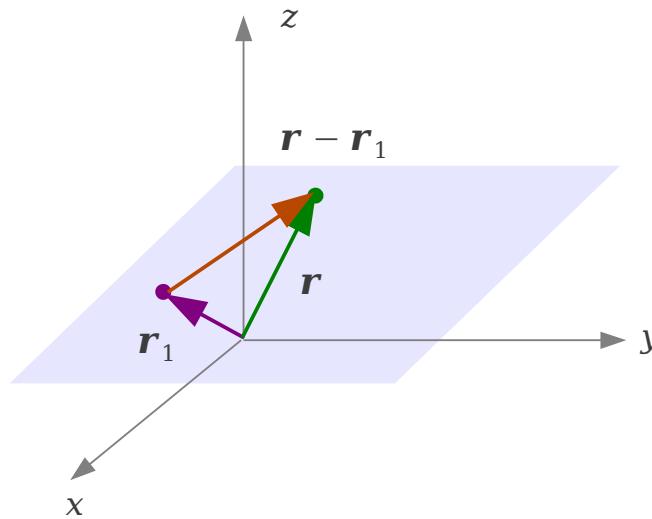
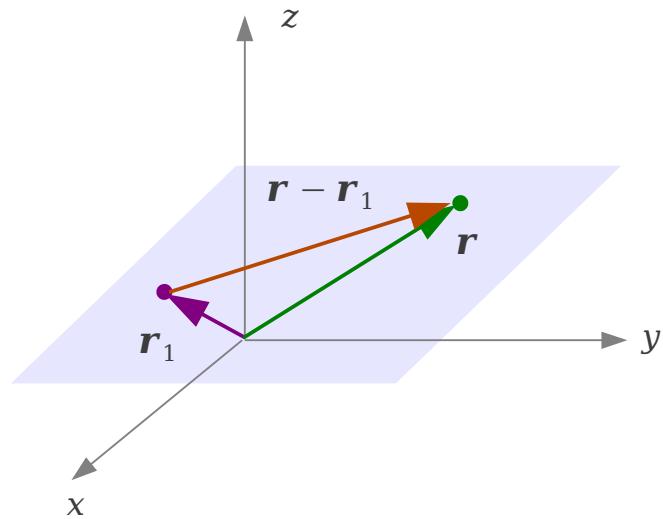
$$a(x - x_1) + b(y - y_1) + c(z - z_1) = 0$$

Plane Equations (2)

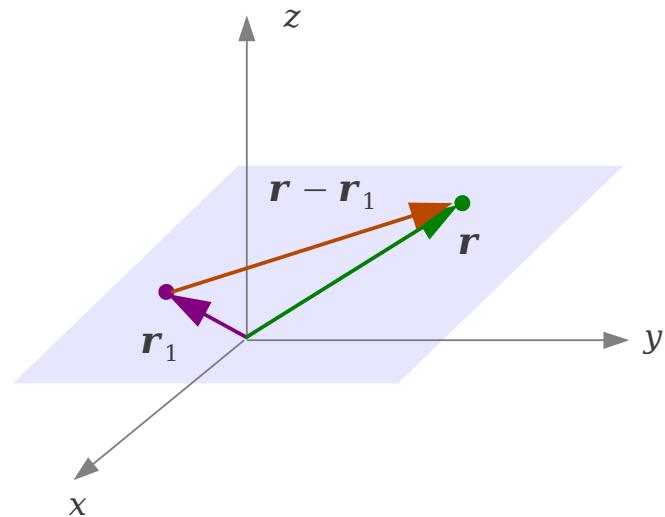
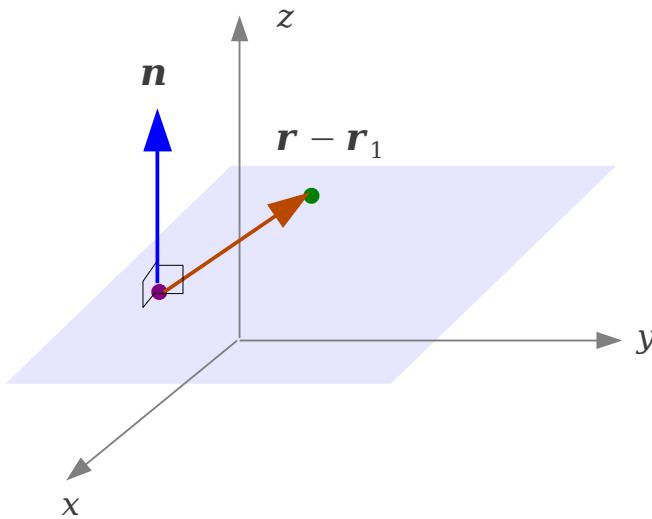
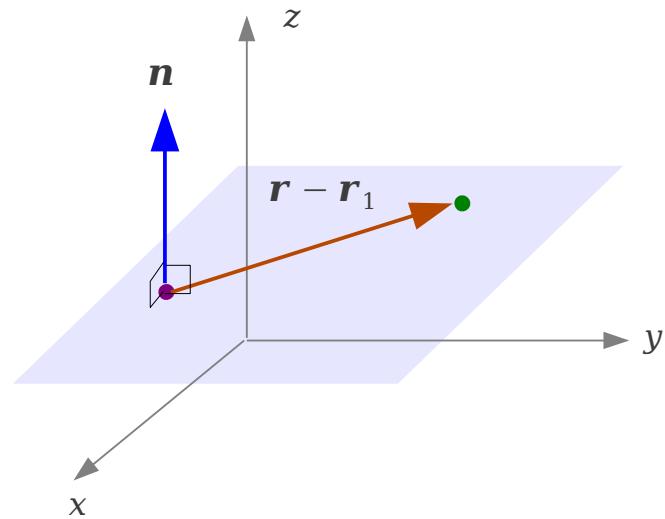


Normal Vector

No Parameter



Plane Equations (3)



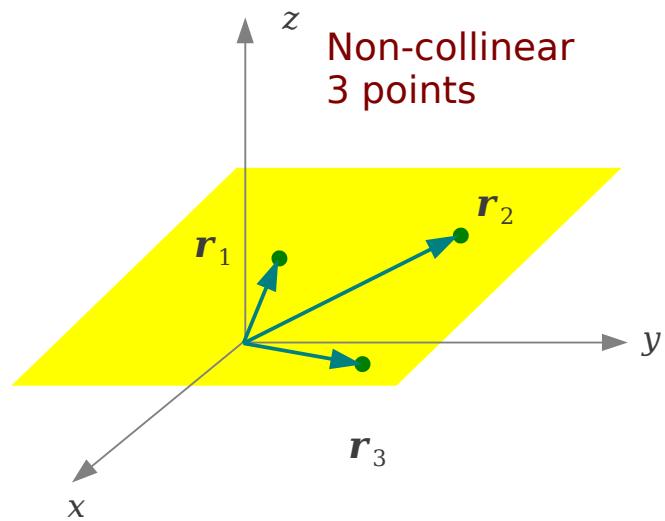
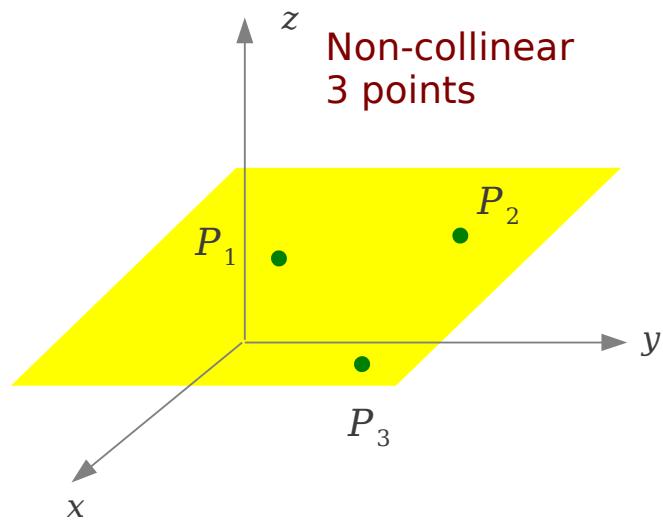
$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_1) = 0$$

$$\mathbf{r} = \langle x, y, z \rangle$$

$$\mathbf{r}_1 = \langle x_1, y_1, z_1 \rangle$$

$$\mathbf{n} = \langle a, b, c \rangle$$

Normal Vector & 3 Points



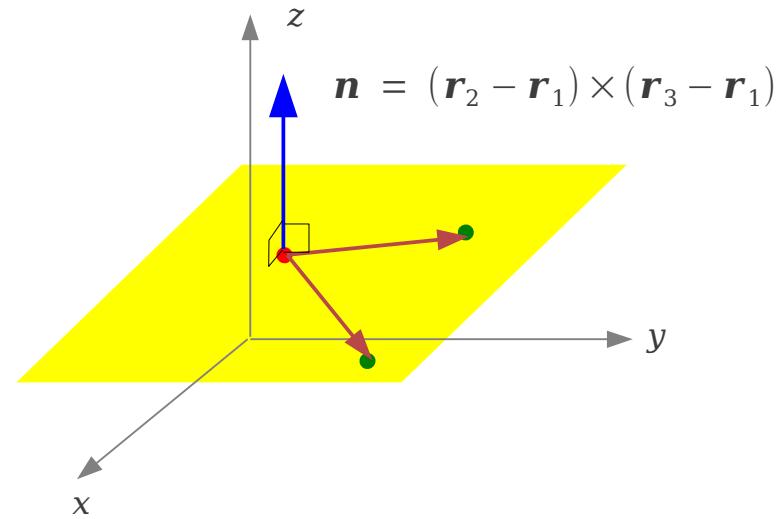
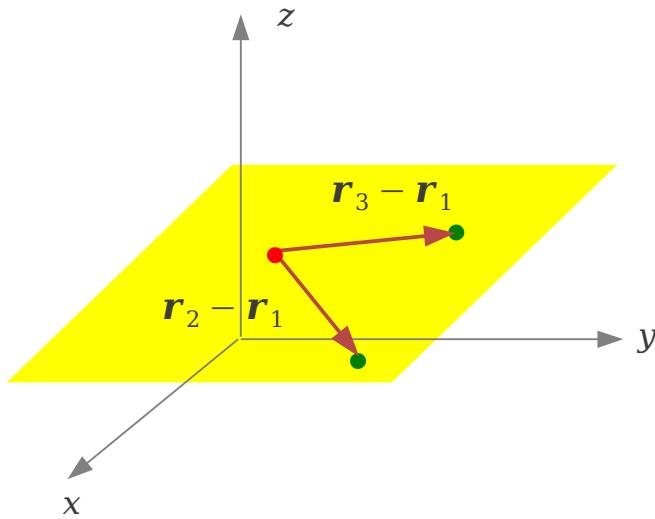
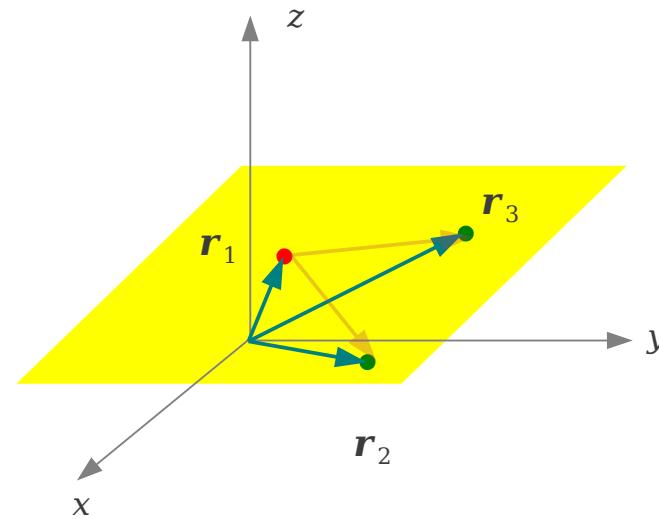
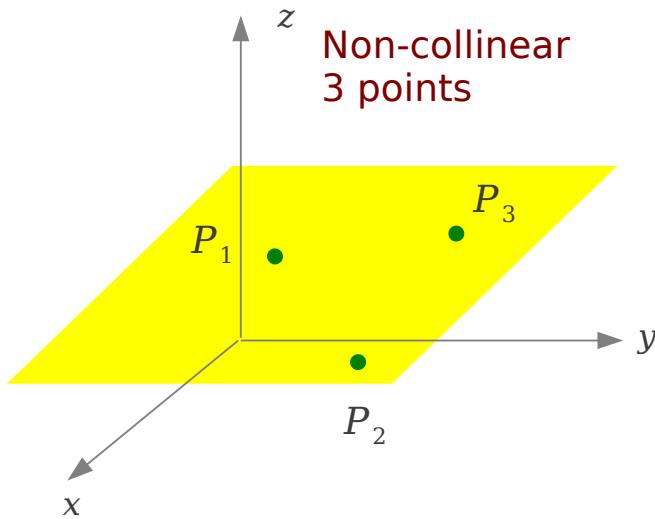
Graph of a plane



Line intersection of two planes

Point of intersection of a line and plane

Normal Vector & 3 Points



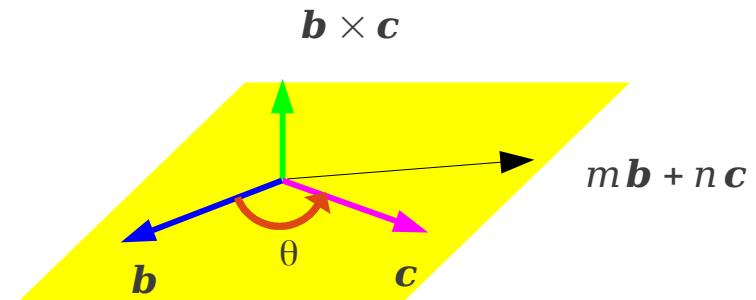
Vector Triple Product

$$\mathbf{a} \times (\mathbf{b} \times \mathbf{c})$$

- ⇒ Perpendicular to $\mathbf{b} \times \mathbf{c}$
- ⇒ Any vector perpendicular to $\mathbf{b} \times \mathbf{c}$
lies in the plane perpendicular to $\mathbf{b} \times \mathbf{c}$
- ⇒ lies in the plane of \mathbf{b} and \mathbf{c}

Perpendicular to the plane of

$$\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) \Rightarrow m\mathbf{b} + n\mathbf{c}$$
$$(\mathbf{a} \cdot \mathbf{c})\mathbf{b} - (\mathbf{a} \cdot \mathbf{b})\mathbf{c}$$



Scalar Triple Product

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})$$

$$\mathbf{a} = a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}$$

$$\mathbf{b} = b_1 \mathbf{i} + b_2 \mathbf{j} + b_3 \mathbf{k}$$

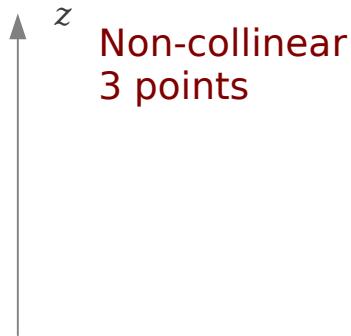
$$\mathbf{c} = c_1 \mathbf{i} + c_2 \mathbf{j} + c_3 \mathbf{k}$$

$$\mathbf{b} \times \mathbf{c} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \mathbf{i} \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - \mathbf{j} \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + \mathbf{k} \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = (a_1 \mathbf{i} + a_2 \mathbf{j} + a_3 \mathbf{k}) \cdot \left(\mathbf{i} \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - \mathbf{j} \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + \mathbf{k} \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} \right)$$

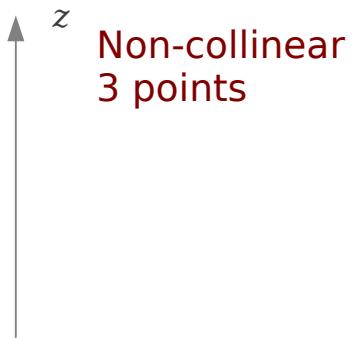
$$= \left(a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} \right) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

Normal Vector & 3 Points



$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \mathbf{i} \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} - \mathbf{j} \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} + \mathbf{k} \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

Normal Vector & 3 Points



Non-collinear
3 points



References

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